### Sensitivity Analysis of BCN with ZRL Congestion Benchmark

### Part 1

# Mitch Gusat and Cyriel Minkenberg IEEE 802 Dallas Nov. 2006

IBM Zurich Research Lab GmbH

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# Outline

- Next phase: BCN validation
  - larger datacenter networks
  - > demanding traffic patterns
- ZRL congestion benchmarking
  - $\succ$  congestion taxonomy and a practical toolbox
- Analytical dual ranking: The APS method
  - > BCN's algorithmical sensitivity to parameters
  - > Parameters' sensitivity to benchmarking traffic
- Simulation results
  - validation of analytical selection
  - > parameters' sweep: stability plane
- Conclusion

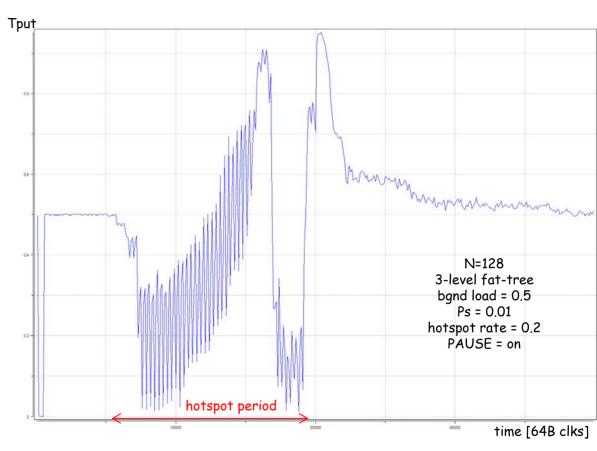
# Next phase of BCN validation

- Baseline BCN: validated by multiple parties
  - $\succ$  joint effort of the .1au adhoc simulation teams
- Basic scheme is functional
  - for detail conclusions see .1au repository
- Next: BCN w/ larger networks under stress traffic
- How to proceed?
  - Empirical approach: Brute force simulations (see next foil)
  - > More rigorous approach: ZRL congestion benchmarking
    - o Iterate between analytical and simulation models to systematically parse the combinatorial tree and reduce the dimension of the parameter space

# Empirical approach: Brute force simulations

Multi-dimensional problem

- 1. no. nodes
- 2. switch / adapter arch.
- 3. topology
- 4. LL-FC settings
- 5. BCN params
- 6. traffic scenario
- 7. metrics of interest
- 8. no. of simulation points
- ⇒ Combinatorial explosion
  of an 8D (actually 20+
  dim's) search space.
- ⇒ Not practical for standard work

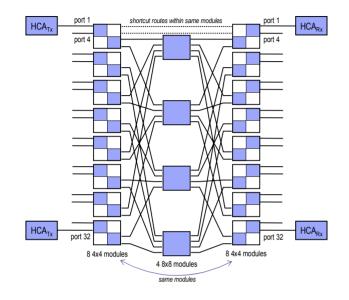


BCN with baseline settings: unstable. Which dimension to explore 1<sup>st</sup>?

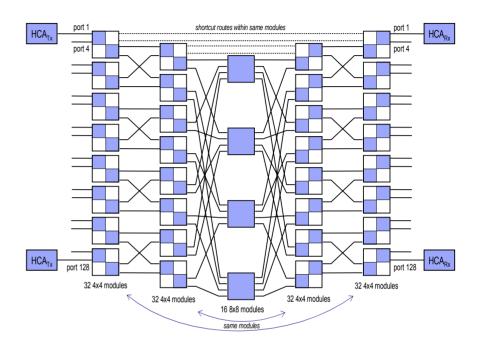
## A More Rigorous Alternative

- Dimensions 1-3 (architectural) are determined by
  - market of datacenter and HPC
  - > 802 architectural definitions (e.g., ideal OQ)
- Dim's 4,5 (scheme settings) => Our main target.
- Dim's 6-8 (methodology) => Toolbox
- Toolbox proposal: "ZRL Congestion Benchmarking"
  - 1. Benchmarks designed for datacenter environments
  - 2. Combines analysis w/ simulation in a systematical method
  - 3. Tried and improved thru work in related standards.

# Baseline Topology Proposal: Bidir Fat Trees (FT)



- 2-level / 3-stage bidir MIN
- Simulate: 8 32 nodes
- Time per run: < 1hr



- 3-level / 5-stage bidir MIN
- Simulate: 128 2K nodes
- Time per run: TBD

Fat-trees: Scalable, w/ excellent routing and performance properties. Optimum performance/cost with current trends in technology. Can emulate <u>any</u> k-ary n-fly *and* n-cube topology. Large body of knowledge.

## Toolbox-1. Traffic: ZRL Congestion Benchmark

- Source nodes generate\* one or more hotspots according to matrix  $[\mathbf{\lambda}_{ij\_hot}]$ :  $t_{p>q} = \alpha_{k\_hot} [\mathbf{\lambda}_{ij\_hot}]$ :  $t_{p>q}$ ,  $[\mathbf{\lambda}_{ij\_hot}]$  is specified\*\* per case as below
- 1. Congestion type: IN- or OUT- put generated
- 2. Hotspot severity: HSV =  $\Lambda_{aggr} / \mu_{HS}$ ,  $\Lambda_{aggr} = \sum \Lambda_i$  at hotspotted output,  $\mu_{HS}$  = service rate of the HS
  - ➢ Mild 1 < HSV <= 2</p>
  - Moderate 2 < HSV <= 10</p>
  - Severe HSV > 10.
- 3. Hotspot **degree**: HSD is the fan-in of congestive tree at the measured hotspot
  - Small HSD < 10% (of all sources inject hot traffic)</p>
  - ➤ Medium HSD ~ 20..60%
  - ➤ Large HSD > 90%.

\* Traffic generation is a Markov-modulated process of burstiness B (indep. dimension) \*\*Metrics and measurement methodology are subject of another deck

#### Toolbox-2: BCN Parameters. How to proceed?

BCN entails 6 params

- 1. Equilibrium threshold  $Q_{eq}$
- 2. Rate unit  $R_u$
- 3. Sampling rate  $P_s$
- 4. Feedback weight W
- 5. Increase (additive) gain  $G_i$
- 6. Decrease (multiplicative) gain  $G_d$

Next step?

- a) The empirical approach is unsustainable because it generates too many singular points, as seen on foil #4
- b) A purely analytical approach is difficult owing to non-linearity of model. Would also require validation by simulation.

c) However, a combined analytical and simulation method is feasible!

## Reduction of Simulation Space: Dual Ranking

- Using ZRL Benchmarking, the smallest simulation space is given by the tuple product
  - SimRuns = {topology, HS type, HS severity, HS degree, burstiness} x {BCN param} = 2\*2\*3\*3\*4 x {BCN param} = 144 x {6D}
- SimRuns =  $144 \times \{Q_{eq}, R_{u}, P_{s}, W, G_{i}, G_{d}\}$  ... still a VERY large space!

- Further reduction by (simplified) dual ranking analysis
  - 1. algorithmical sensitivity to BCN params: which param matter most?
  - 2. parametrical sensitivity to traffic: which benchmarks are critical?

Next: Algorithmic and parametrical (AP) sensitivity of BCN Sensitivity is often a more accurate metric of stability margin than either gain or phase margin! However, here we didn't use canonical sensitivity.

# Ranking by AP Sensitivity - 1

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From BCN stability model

- 1. Conservation:  $dq/dt = HSD*\lambda(t) \mu_{HS}$
- 2.  $q(s) = HSD^* \lambda(s) / s$
- 3. Feedback:  $Fb(t) = -(q(t) Q_{eq}) + w^*(dq/dt) / (\mu_{HS}^* p_s) = >$
- 4.  $Fb(s) \approx G * [1 + w*s / (\mu_{HS}*p_s)]$

5. AI: 
$$d\lambda(t)/dt = G_i^*\lambda(t)^* p_s^*Fb(t-\tau)$$

- 6.  $\delta AI(t)/\delta Fb(t-\tau) = G_i * p_s * \mu_{HS}/HSD$
- 7. AP sensitivity of  $G_i = \delta AI(t)/\delta Fb(t-\tau) * HSD/(p_s*\mu_{HS})$
- 8. MD:  $d\lambda(t)/dt = G_d^*\lambda(t)^*\lambda(t-\tau)^* p_s^*Fb(t-\tau)$
- 9.  $\delta MD(t)/\delta Fb(t-\tau) \approx G_d * p_s * (\mu_{HS}/HSD)^2$
- 10. AP sensitivity of  $G_d = \delta MD(t)/\delta Fb(t-\tau) * (\mu_{HS}/HSD)^{-2} / p_s$ .

q(t) =queue occupancy; HSD=no. of hot flows, each with rate  $\lambda(t)$ , at hotspot served w/ rate  $\mu_{HS}$ 

# Ranking by AP Sensitivity - 2

#### (7,10) =>

- a) p<sub>s</sub> directly impacts G<sub>i</sub> and G<sub>d</sub>
  - $\blacktriangleright$  1<sup>st</sup> order sensitivity on p<sub>s</sub>
- b)  $G_i$  and  $G_d$  depend on the HSD/ $\mu_{HS}$  ratio
  - $\blacktriangleright$  congestion w/ high HSD and low  $\mu_{HS}$  stresses stability

(10) =>

c)  $G_d$  is *more* sensitive than  $G_i$  to the HSD/ $\mu_{HS}$  ratio (squared)

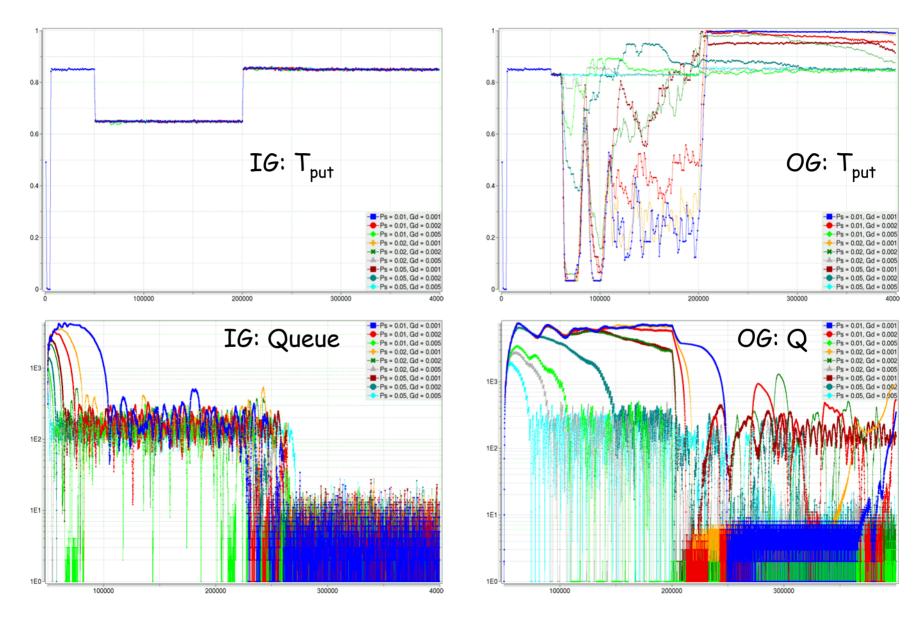
(4,7,10) =>

- if denominator ~ f ( $p_s * \mu_{HS}$ ), where  $p_s \ll 1$  and  $\mu_{HS} \le 1$ , -> the hotspot drain rate *further* increases the sensitivity to  $p_s$
- d) everyting else being equal, *output-generated* (OG) congestion is more stressful for BCN's stability than IG

What to begin with?

- $\succ$  BCN params:  $p_s$  and  $G_d$
- $\succ~$  Traffic: Output-generated congestion w/ high HSD and low  $\mu_{HS}$  .

### Qualitative Validation: Input- vs. Output-Generated HS



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#### Simulations Confirm Our Sensitivity Ranking

- OG requires higher control effort than IG
  - Slower throughput recovery; overshoot
  - > Higher queue size fluctuations
  - > Less stability margin: more sensitive to parameter settings
- BCN's impulse response improves as  $P_s$  and  $G_d$  increase (within bounds!)
  - > Applies to both scenarios => as  $P_s$  and  $G_d$  increase, so does the system's distance between pole(s) and origin... up to a point
- Next: Simulation-based sensitivity analysis of  $P_s$  and  $G_d$

#### Simulation Overview

- Single-stage network, 32 nodes
- Shared-memory switch
- Background traffic is uniformly distributed
- All frames minimum size (64 B, time slot = 51.2 ns)
- No TCP/IP, raw Ethernet!
- Parameters
  - > Mean load  $\lambda$
  - > Mean burst size B
  - Shared-memory size M
  - Round-trip time RTT (in slots)
  - > BCN parameters ( $P_s$ ,  $G_d$ ,  $G_i$ ,  $Q_{eq}$ , W,  $R_u$ )
- Metrics
  - Throughput (aggregate and per port/flow)
  - Latency (measured per burst)
  - Queue length (congested queue)
  - Fairness (RJFI, ALFI)
  - Number of PAUSE and BCN frames sent

#### Switch

### Adapter Model

- Shared-memory outputqueued switch
- PAUSE enabled
  - Global high- and lowwatermark memory threshold trigger pause and unpause
  - High watermark T<sub>h</sub> = M -N\*(RTT\*B + L<sub>max</sub>)
  - > Low watermark  $T_1 = T_h / 2$
  - PAUSE renewed before expiry (take into account RTT)

- VOQ-ed per end node
- Round-robin service discipline
- Number of rate limiters unlimited
- Egress buffer flow-controlled using PAUSE (high/low watermarks)

# Lossless operation: No frame drops due to buffer overflows!

### Traffic Scenarios

- Output-generated hotspot
  - Service rate of output 0 is reduced to 20% of full line rate
  - Results in an N-degree hotspot
  - Without CM, aggregate throughput is limited to 20% due to hogging

**Initial Param Settings** 

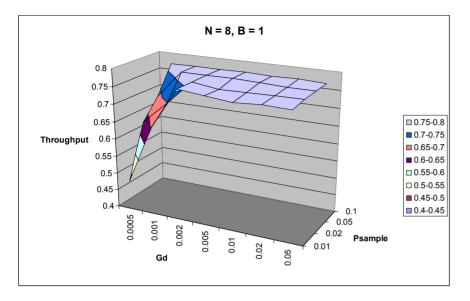
- 1.  $Q_{eq} \leftarrow M / N$  (memory is partitioned to reduce hogging)
- 2.  $R_u = R_{max} / 1000$
- 3. P<sub>s</sub> = [0.01, 0.1]
- 4. W = 1

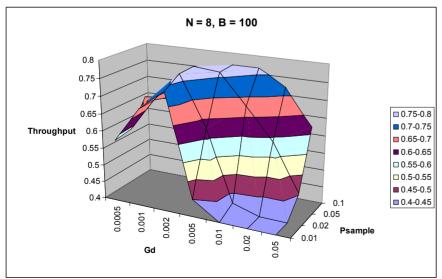
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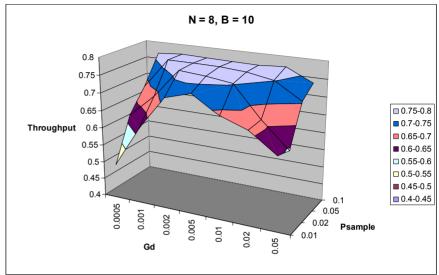
- 5. *G*<sub>i</sub> = 1
- 6. *G*<sub>d</sub> = [0.0005, 0.05]

Note: Above settings may be neither optimal nor a baseline match.

#### Results: OG hotspot (N=8)

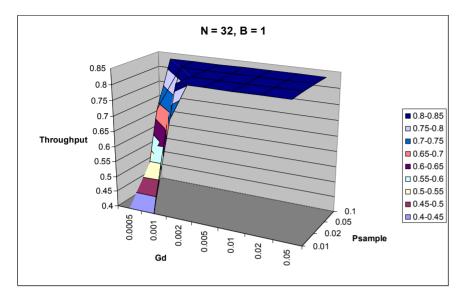


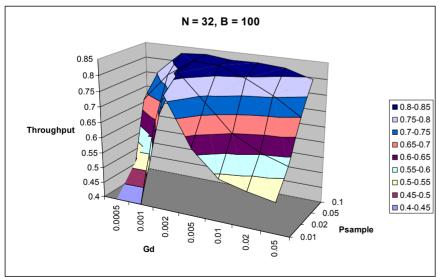


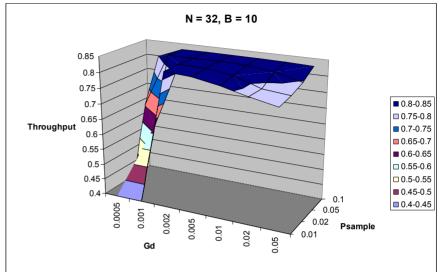


- RTT=0, M=256\*N,Q<sub>eq</sub>=M/N ٠
- Throughput measured during hotspot
- Hotspot rate = 20% ٠
- $Tp_{max} = \lambda * (N-1)/N + 0.2/N$  $\lambda = 85\%$ , N=8 =>  $Tp_{max} = 0.77$ •
- Varying G<sub>d</sub> and P<sub>s</sub>

#### Results: OG hotspot (N=32)

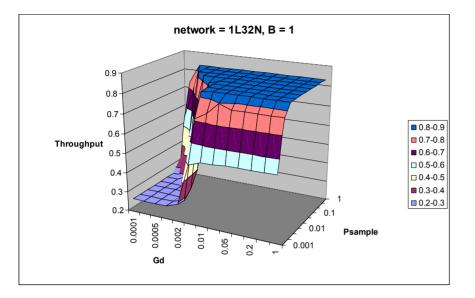


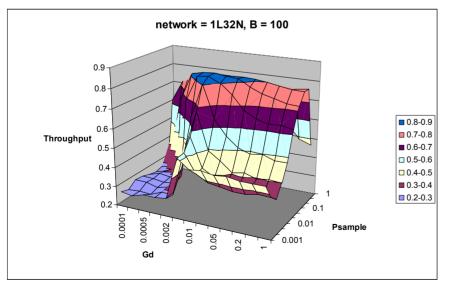


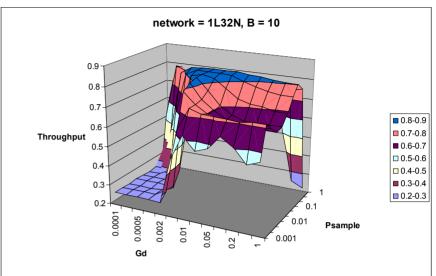


- RTT=0, M=256\*N, Q<sub>eq</sub>=M/N
- Throughput measured during hotspot
- Hotspot rate = 20%
- $Tp_{max} = \lambda * (N-1)/N + 0.2/N$
- $\lambda$ =85%, N=32 => Tp<sub>max</sub> = 0.83
- Varying  $G_d$  and  $P_s$

#### Results with M/(2N) Memory Partitioning: OG hotspot 1L32N





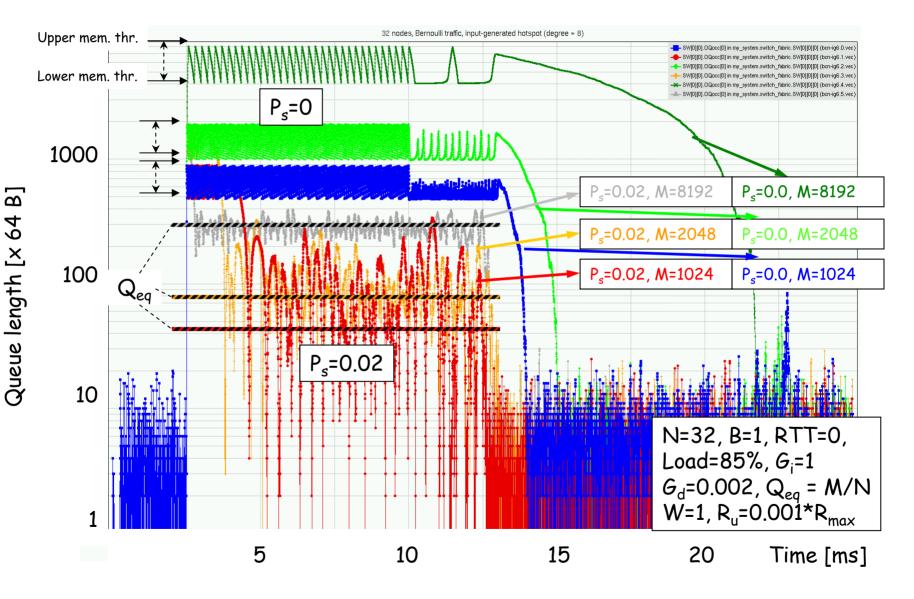


- RTT=0, M=256\*N, Q<sub>eq</sub>=M/(2N) ! Throughput measured during hotspot
- Hotspot rate = 20% => severity = 85%/20% = 425%
- $Tp_{max} = \lambda * (N-1)/N + 0.2/N$
- $\lambda$ =85%, N=32 => Tp<sub>max</sub> = 0.83 •
- Varying  $G_d$  and  $P_s$

# IG results

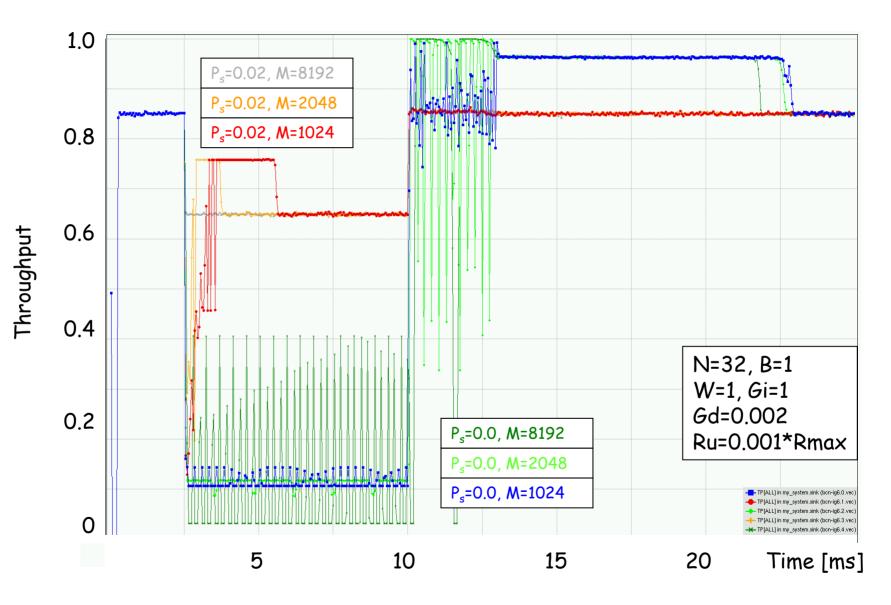
- Input-generated severe hotspot
  - > Uniform background traffic load = 85%
  - > Multiple (HSD) inputs send 100% of their traffic to output 0
    - o Primary HSD = 8 (all the other also send a smaller quota)
    - o Hotspot is targeted by 8 hot flows and 24 background flows
    - o Aggregate severity = (8\*100% + 24\*85%/32) = 863%
  - Without BCN, aggregate throughput is limited to about 100% / (HSD((N-1)/N)+1)

### Results: Input-gen'd hotspot (1)



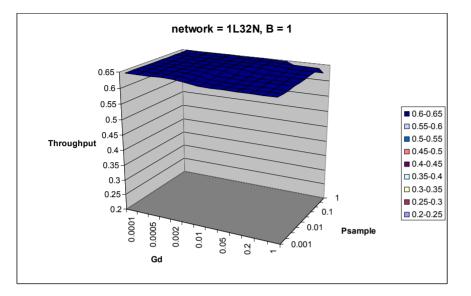
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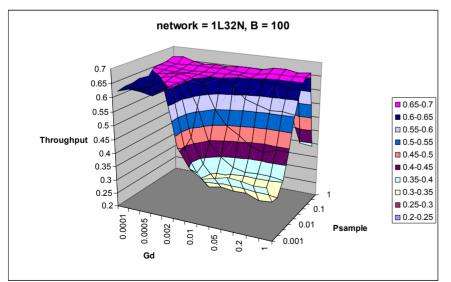
#### Results: Input-gen'd hotspot (2)

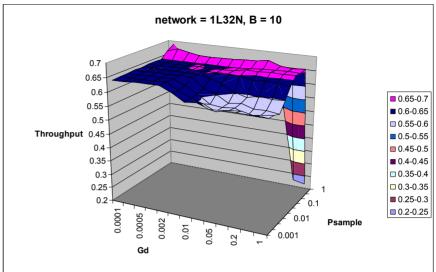


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#### Results with M/(2N) Memory Partitioning: IG hotspot 1L32N







- RTT=0, M=256\*N, Q<sub>eq</sub>=M/(2N) Throughput measured during hotspot
- Hotspot severity = 863%
- $Tp_{max} = 0.65$
- Varying  $G_d$  and  $P_s$

### Conclusions

- Analytical and simulation modeling show that BCN's stability and performance depend on
  - > Two  $1^{st}$  order params:  $p_s$  and  $G_d$
  - > Type of traffic: Output-generated congestion is a stress test
- Optimal ranges for OG (assuming fixed W\*, G<sub>i</sub>, R<sub>u</sub>, Q<sub>eq</sub>)
  ▷ P<sub>s</sub> = [0.02, 0.05]
  ▷ G<sub>d</sub> = [0.002, 0.005]
- Burstiness also determines sensitivity
  - Large bursts (MTU-Jumbo) increase the sensitivity
- Upcoming
  - > Increase network size to 128, with 2 and 3 levels.

\* In simulations W proved less sensitive than we've analytically expected