## A Short Tutorial on CSMA

- Related work and history
- Analytical results
- Ethernet & measured results
- Pros and Cons

## What this Is

- Presentation of established work in the field
- Highlights of well-known work

### What this is Not

- A pitch for CSMA
- Attempt to apply these or other results to 802.11 work (merits a separate submission)

### Context for CSMA Discussion<sup>1</sup>

#### Definitions -

Autonomous Networks networks operated by independent entities not actively coordinated with each other

Collocated Networks networks operating on the same physical channel in the same vicinity

#### Basic System and Market Assumptions

- A few cells will exist
- The system architecture should exploit the existence of cells to the maximum extent possible but
- There will not be enough cells to guarantee every autonomous collocated network exclusive use of a cell
- Users will not accept a solution that requires coordinated network engineering by unrelated collocated users it follows that
- Spectrum sharing among user communities or independent access points using a common cell/channel is an essential requirement for the system architecture.

## Consequently, 2 channel access issues exist

- To regulate channel sharing by autonomous collocated networks
- To regulate channel sharing by nodes within an autonomous system

## Any proposed system architecture must address both issues to be viable

<sup>&</sup>lt;sup>1</sup>This introductory section does not form part of the Tutorial since it represents the opinions of the author.

## Context for CSMA discussion, contd

#### Why propose CSMA?

- A serious contender
- Well suited to small cells and work-groups
- Supports cooperative spectrum use between independent systems
- Supports portable computer environments well (dynamic topologies)

## History and Related Work

#### History of CSMA

- First proposed in 1971 for use in packet radio channels
- Research funded by DoD for use in Packet Radio
- The Darpa Packet Radio Network (PRNET) is CSMA based
- Use in packet radio preceded use in wired networks

#### CSMA and related protocols

- Aloha
- CSMA
- Ethernet/802.3

#### Conceptual basis

- The channel carries its own control information
- Control is distributed among all nodes

#### References

The research of L. Kleinrock, F. Tobagi, S. Lam et al

Primary source materials for this presentation:

"Packet Switching in Radio Channels: Part I - Carrier Sense Multiple-Access Modes and their Throughput-Delay Characteristics" by Klenirock and Tobagi

"Packet Switching in Radio Channels: Part II- The hidden terminal problem in Carrier Sense Multiple Access and the busy tone solution" by Tobagi and Kleinrock

Unless otherwise stated, all graphs are reproduced from these sources.

## Analytical Results

- System assumptions
- non-persistent CSMA
- p-persistent CSMA
- 1-persistent CSMA

#### System Assumptions (basis for analysis)

- Wideband channel
- Propagation delay a small fraction of packet transmission time
- Fixed length packets
- Infinite population
- Independent Poisson source of packets
- Retransmissions increase the offered load on the channel
- Half-duplex nodes
- Channel noiseless
- Propagation delay is identical for all source-destination pairs
- No capture (overlap causes destruction of all transmitted pkts)

#### Simulation results

• in agreement with analytic results

## Aloha protocols

#### Aloha

Node transmits whenever it has a packet ready (total chaos model!)

#### • Slotted Aloha

Node transmits when it has a packet ready, but only on time slot boundaries

#### Performance

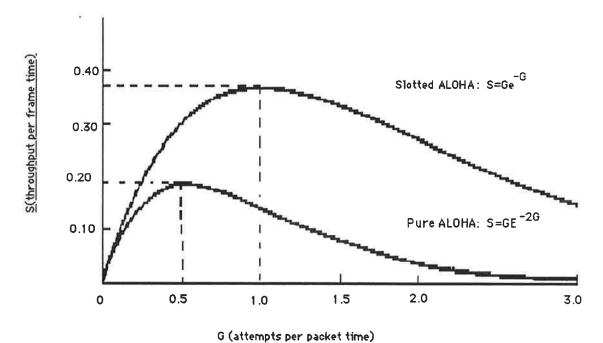


Fig. 3-3. throughput versus offered traffic for ALOHA systems.

## CSMA protocols

- Sense the channel before transmitting
- Execute a channel-state-dependent algorithm
- Different algorithms yield different "CSMA-class" protocols
- Main variants
  - non-persistent
  - p-persistent
  - 1-persistent
  - Ethernet (1-persistent with collision detect)
- Important parameter:
  The *collision window* caused by propagation delay
  Normalized collision window is defined as

Propagation time<sup>2</sup>

Packet transmission time

a =

Effective propagation time = actual propagation time + carrier sense time + rcv-xmt turn-around time

and is dominated by the carrier sense and rcv-xmt turn-around times.

If carrier sense time < 10 µsec rcv-xmt turnaround time < 10 µsec (these are good representative numbers) then effective propagation time <sup>a</sup> 20 µsec

If data rate = 1 Mb/s, range = 50m, packet length = 1000 bytes (8000 bits) - a = 0.0025If data rate = I Mb/s, range = 50m, packet length = 100 bytes (800 bits) - a = 0.025

<sup>&</sup>lt;sup>2</sup>In practice,

## Non-persistent CSMA

#### Algorithm:

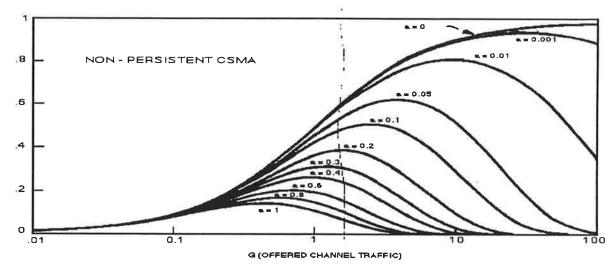
Sense the channel before transmitting.

If channel idle, transmit

If channel busy, backoff, then repeat entire algorithm (sense + transmit/wait)

Backoff algorithm is usually exponential

#### Performance curves



Throughput in nonpersistent CSMA.

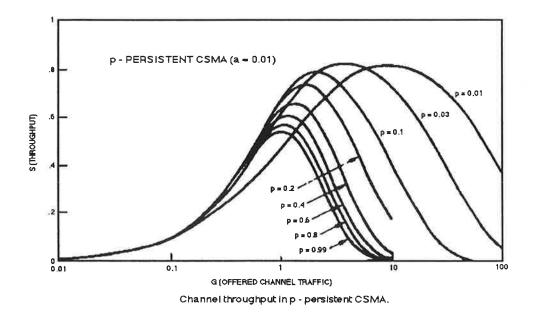
## p-persistent CSMA

- Assumes a very fine-grained slotted channel
- If p = 1 protocol similar to 1-persistent CSMA
- p=0 is not the same as non-persistent CSMA

#### Algorithm:

Sense the channel before transmitting on mini-slot boundaries If busy, wait till channel goes idle If idle, transmit with probability p Else wait for the next mini-slot, and repeat.

#### Performance curves



## 1-persistent CSMA

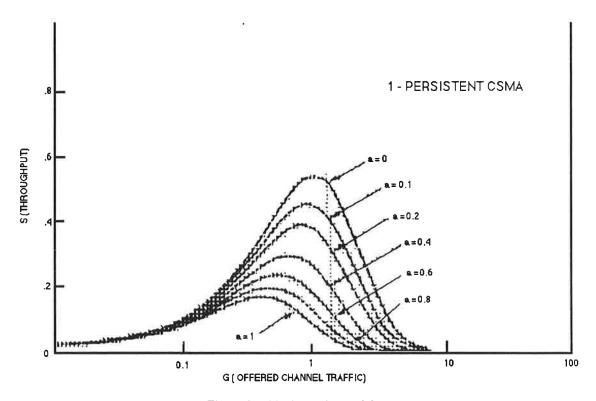
#### Algorithm:

Sense the channel before transmitting on mini-slot boundaries If idle, transmit

If busy, wait till channel goes idle and then transmit

- Collision *will occur* if > 1 node ready to transmit during a packet transmission time
- Ethernet/802.3 is 1-persistent with Collision Detect.

#### Performance curves

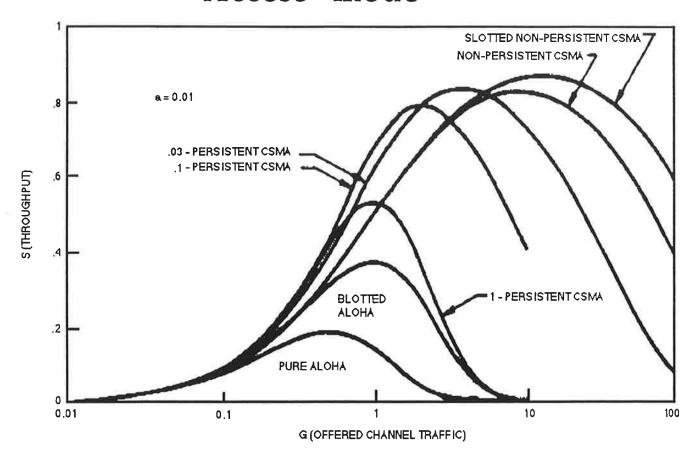


Throughput in 1-persistent CSMA.

# CSMA throughput determinants and characteristics

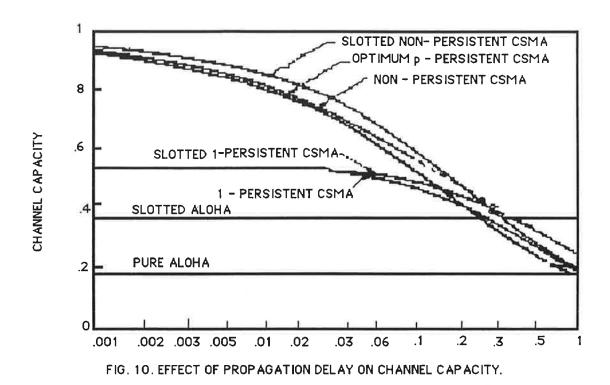
- Access mode
- Propagation Delay
- p in p-persistent CSMA

#### Access mode

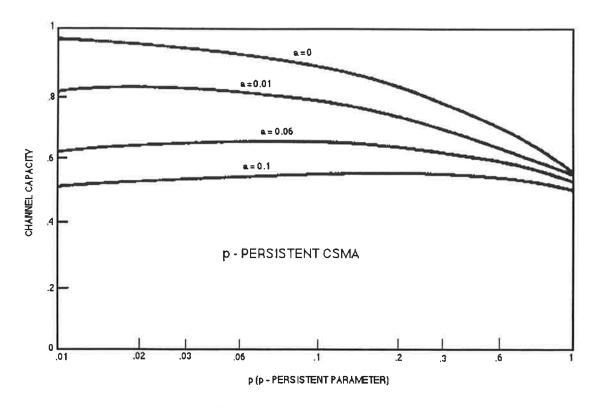


Throughput for the various access modes (a = 0.01)

## Propagation Delay



## p in p-persistent CSMA



p - persistent CSMA: effect of p on channel capacity.

## Ethernet

#### **Profile**

- 1-persistent CSMA with Collision Detect
- Collision detected within 64 byte (512 bit) times
- Collision Detect reduces wasted bandwidth when collision occurs transmission aborted
- 1-persistent protocols not practical for heavily loaded channels without collision detect

#### Algorithm:

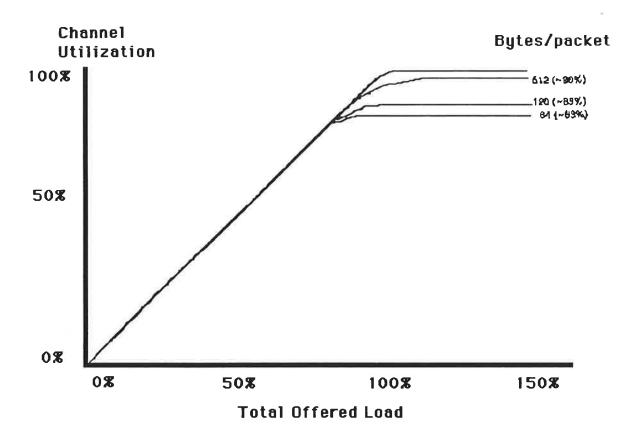
Sense the channel before transmitting.

If idle, transmit

If busy, wait till transmission is complete, then transmit with probability 1

If collision detected, do exponential backoff and repeat entire algorithm

# Measured Performance of Ethernet



Measured Performance of Ethernet

Source: Measured Performance of an Ethernet Local Network, John Shoch and Jon A Hupp

## Pros and Cons (non-persistent CSMA)

#### **Benefits**

- Distributed control
- Algorithm run independently at each node
- Simple
- Extensive analytical and simulation work available
- Stable over loads well in excess of channel capacity

#### Cons

- Degrades in the presence of hidden nodes, Aloha in limiting case
- Throughput rises slowly at high load If offered load = channel capacity, throughput = ~50%
- Delay increases with load

#### Areas for study

• Generalized Busy Tone algorithm to reduce hidden node degradation<sup>4</sup>

Suitability to our application and consequent overall system characteristics deferred to a separate submission.

<sup>&</sup>lt;sup>4</sup>Busy Tone is a contentious algorithm. While this author does not personally favour it, other IEEE 802.11 members may have supporting arguments.