

Seq. #	Section number	your initials	Comment type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
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Results of Ballot on Draft Standard D3.0

Comments on clause 9

	9.1 10	WD	E	n	The figures 35 (MAC Architecture Block Diagram) and 53 (GET and SET Operations) do not match. In particular, figure 35 shows a Sublayer Management interface that is not described in section 10. It is suggested to delete this interface from the figure 35.	Delete Sublayer Management interface from figure 35.	
	9.1	rw	T	y	The MAC architecture must be able to handle more than one outstanding transmit frame. This is not reflected in clause 9.1, in clause 9.2.5.2 which defines the backoff procedure, or in the MAC transmit state machine in Annex C. This is very important in an infrastructure based system. If an AP is trying to transmit a frame to a STA in poor coverage and has to backoff and retry, the MAC must be able to transmit another frame during the backoff. If this is not done, a STA in poor cover will decrease the through-put of the entire BSS	The MAC architecture allows a STA to process more than one transmit frame at a time. This allows a STA to transmit a frame while another frame is in backoff due to not receiving an ACK.	
	9.1	db	T	Y	figure 35, appears to be a hold over from the state machine stuff that was in this clause in D2 - the rest was moved to an annex, but this was left. I think it should be moved also - this picture of a MAC architecture is not relevant and represents the partitions assumed by the state machine annex.	remove this figure from the draft or place it in the state machine annex where it belongs.	
	9.1.1	jz	t		Replace "ad hoc" with "independent" or "autonomous".		
	9.1.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not correctly convey operational requirements.	of the distributed coordination function. This access method uses a point coordinator, which shall must operate at the access point of the BSS, to determine which station currently has the right to transmit. The	
	9.1.2	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was	use of an access priority mechanism, aided by the virtual carrier sense	

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					not used the draft does not corectly convey operational requirements.	mechanism. Different classes of traffic mayean be defined through the use of different values for Inter Frame Spacing (IFS), thereby creating prioritized access to the medium for those classes with a shorter IFS. The point coordination	
	9.1.2	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	allowed to begin their transmissions under the DCF access method. The point coordinator mayean then control the frame transmissions of the stations so as to eliminate contention for a limited period of time.	
	9.1.4	ch	t		Second paragraph, if the MSDU is too long, the MSDU must be fragmented, not the 'frame'	When a MSDUframe is received from the LLC with a MSDU-size greater than aFragmentation_Threshold , the MSDUframe must be fragmented	
	9.1.4	AS	t	y	Only the last fragment is allowed to be smaller than aFragmentation_Threshold		
	9.1.4	TT	T	Y	<p>The following comment essentially wishes to add text which says that only DATA frames are fragmented. All Control and Management frames are not.</p> <p>The issue of whether to fragment Control and Management frames is only relevant for Beacon frames. All Control frames are less than 256 bytes long, therefore will never be fragmented. Similarly all Management frames except an AP Beacon, are also less than 256 bytes long (the minimum fragmentation threshold size).</p> <p>Since the Beacon MPDU is a broadcast frame with a maximum length of 355 bytes the value of fragmenting this frame if the threshold is below this amount is questionable. Especially since the element that will be split by the fragmentation is the TIM which will require the beacon be re-assembled first before an STA can</p>	<p>Add new paragraph after first paragraph:</p> <p>Only DATA frames shall be fragmented. All Control and Management frames shall not be fragmented, even if their length exceeds aFragmentation_Threshold.</p>	

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					determine if its SID bit is set.		
	9.1.4 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	When a frame is received from the LLC with a MSDU size greater than aFragmentation_Threshold, the frame shall must be fragmented. The MSDU is divided into MPDUs. Each MPDU is a fragment with a	
	9.1.4	TT	T	Y	<p>The following comment essentially wishes to add text which says that only DATA frames are fragmented. All Control and Management frames are not.</p> <p>The issue of whether to fragment Control and Management frames is only relevant for Beacon frames. All Control frames are less than 256 bytes long, therefore will never be fragmented. Similarly all Management frames except an AP Beacon, are also less than 256 bytes long (the minimum fragmentation threshold size).</p> <p>Since the Beacon MPDU is a broadcast frame with a maximum length of 355 bytes the value of fragmenting this frame if the threshold is below this amount is questionable. Especially since the element that will be split by the fragmentation is the TIM which will require the beacon be re-assembled first before an STA can determine if its SID bit is set.</p>	<p>Add new paragraph after first paragraph:</p> <p>Only DATA frames shall be fragmented. All Control and Management frames shall not be fragmented, even if their length exceeds aFragmentation_Threshold.</p>	
	9.14	TT	T	Y	<p>There is currently no valid reason why broadcast and multicast frames are required to be fragmented if their size exceeds aFragmentation_Threshold. The only reason for fragmentation is:</p> <ul style="list-style-type: none"> - to improve reliability of MSDU delivery in a noisy medium <p>Therefore given a certain chance of a bit error it does not</p>	<p>Add new paragraph after first paragraph:</p> <p>Only Directed Frames shall be fragmented. Broadcast/Multicast frames shall not be fragmented even if their length exceeds aFragmentation_Threshold.</p>	

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					<p>make any sense to add more bits to a broadcast frame, which fragmentation does, when any one of these bits received with error, will cause the whole MSDU to be discarded.</p> <p>The often quoted reason of PHY's not being able to transmit MPDUs larger than a certain size would be valid, except that all the PHYs in the current standard quote a maximum MPDU size the PHY shall be capable of sending, that is larger than the maximum MSDU size.</p> <p>i.e. 4095 in the FH PHY 65000 in the DS PHY 2500 in the IR PHY</p> <p>I've heard people say that some PHYs cannot transmit continuously for the max length frame time but then these PHYs cannot be 802.11 therefore we don't have to worry about them.</p> <p>So if the PHY can transmit a max length MPDU and fragmenting broadcast frames decreases the probability they get through, then why fragment them.</p> <p>From the implementation point of view, it is simpler to qualify the MSDU length check against aFragmentation_Threshold with the fact the MSDU is a broadcast, than create a whole new TX state machine to transmit framgments back to back.</p>		
	9.14	TT	T	Y	<p>There is currently no valid reason why broadcast and multicast frames are required to be fragmented if their size exceeds aFragmentation_Threshold. The only reason for fragmentation is:</p> <ul style="list-style-type: none"> - to improve reliability of MSDU delivery in a noisy medium <p>Therefore given a certain chance of a bit error it does not</p>	<p>Add new paragraph after first paragraph:</p> <p>Only Directed Frames shall be fragmented. Broadcast/Multicast frames shall not be fragmented even if their length exceeds aFragmentation_Threshold.</p>	

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					<p>make any sense to add more bits to a broadcast frame, which fragmentation does, when any one of these bits received with error, will cause the whole MSDU to be discarded.</p> <p>The often quoted reason of PHY's not being able to transmit MPDUs larger than a certain size would be valid, except that all the PHYs in the current standard quote a maximum MPDU size the PHY shall be capable of sending, that is larger than the maximum MSDU size.</p> <p>i.e. 4095 in the FH PHY 65000 in the DS PHY 2500 in the IR PHY</p> <p>I've heard people say that some PHYs cannot transmit continuously for the max length frame time but then these PHYs cannot be 802.11 therefore we don't have to worry about them.</p> <p>So if the PHY can transmit a max length MPDU and fragmenting broadcast frames decreases the probability they get through, then why fragment them.</p> <p>From the implementation point of view, it is simpler to qualify the MSDU length check against aFragmentation_Threshold with the fact the MSDU is a broadcast, than create a whole new TX state machine to transmit framgments back to back.</p>		
	9.2	BO	T	Y	<p>All references to multirate support shall be deleted. There is no mechanism described to allow any determination of interoperability to be made.</p>	<p>The medium access protocol allows for stations to support different sets of data rates. All STAs must receive all the Basic Rate Set and transmit at one or more of the Basic Rate Set data rates. To support the proper operation of the RTS/CTS and the Virtual Carrier Sense mechanism, all STAs must be able to detect the RTS and CTS frames. For</p>	

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						this reason the RTS and CTS frames must be transmitted at one of these mandatory rates.	
	9.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	frame and the returning ACK frame. All stations within the reception range of either the originating station (which transmits the RTS) or the destination station (which transmits the CTS) shall will learn of the medium reservation. Thus a station may can be "hidden" from the originating station and still know about the impending use of the medium to transmit a data frame.	
	9.2	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	The RTS/CTS exchange also performs a type of fast collision detection and transmission path check. If the return CTS is not detected by the STA originating the RTS, the originating STA may can start the process over (after observing the other medium use rules) more quickly than if the long data frame had	
	9.2	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	overlap. The medium reservation mechanism works across the BSA boundaries. The RTS/CTS mechanism may can also improve operation in a typical situation where all STAs may can hear the AP but not all other STAs in the BSA.	
	9.2	db	T	Y	w/o the requested change the Draft is technically	The RTS/CTS mechanism shall can not	

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	A.4.4				incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	be used for broadcast and multicast frames because there are multiple destinations. This mechanism need not be used for every data frame transmission. Because the	
	9.2	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	The use of the RTS/CTS mechanism is under control of the RTS_Threshold attribute. This parameter is a manageable object and may be set on a per station basis. This mechanism allows stations to be	
	9.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	A STA configured not to initiate the RTS/CTS mechanism shall must still update its Virtual Carrier Sense mechanism with the duration information contained in an RTS or CTS frame, and shall must always respond to an RTS addressed to it with a CTS.	
	9.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	The medium access protocol allows for stations to support different sets of data rates. All STAs shall must receive all the Basic Rate Set and transmit at one or more of the Basic Rate Set data rates. To support the proper operation of the RTS/CTS and the Virtual Carrier Sense mechanism, all STAs shall must be able to detect the RTS and CTS frames. For this reason the RTS and CTS frames shall must be transmitted at one of these mandatory rates.	
	9.2.1	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey	The NAV state is combined with physical carrier sense to indicate the busy/free state of the medium. The	

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					operational requirements.	NAV mayean be thought of as a counter, which is counting down. When the counter is zero the virtual carrier sense indication is free.	
	9.2.1	jz	T	Y	Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.	<<adopt text from 95/15 for this subclause>>	
	9.2.1	jz	T	Y	Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.	<<Adopt changed text for this section from 96/15 and 96/16.>>	
	9.2.1, 9.3.2.2, 9.4, 14.4.2.2, 15.2.3.5	vz	E		On page 72, under 9.2.1 there is a reference to a clause with no number following it. Please identify the clause or subclause number. The same occurs on page 85 under 9.3.2.2, and on page 90 under 9.4, on page 188 under 14.4.2.2, on page 220 under 15.2.3.5.		
	9.2.10	ch	e		grammer problems	All timings are referenced from the end of the transmission, which is are referenced from the last symbol of a frame on the medium.	
	9.2.10	ch	e		Figure 47 uses wrong MIB variable name	aMAC_Prc x DelayTime	
	9.2.10	ch	e		Fix the funny capitalization of aSlot_Time	DIFS = aSIFS_Time + 2 * aAS Lo F_time Tx_PIFS = Tx_SIFS + aAS Lo F_time	

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	9.2.10	ch	T	Y	<p>inconsistent definition of aSlot_Time - the picture include aMAC_Prc_Time in Slot_Time but the text does not. The PHY MIB definition in 13.1.4.4 matches the text here.</p> <p>I think the picture is correct, aSlot_time also includes aMAC_Prc_Delay.</p>	<p>ASLoT_time is: aCCA_Asmnt_Time + aRxTx_Turnaround_Time + aAir_Propagation_Time + aMAC_Prc_Delay</p>	
	9.2.10	ch	T	Y	<p>Remove this sentence because there is no reason why this should be fixed - it should be a per PHY value. It is not fixed according to the definition in 13.1.4.19</p>	<p>aAir_Propagation_Time is fixed at 1 usec.</p>	
	9.2.10 A.4.4	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>and the different MAC Slot Boundaries Tx_SIFS, Tx_PIFS and Tx_DIFS. These Slot Boundaries define when the transmitter shallea be turned on by the MAC to meet the different IFS timings on the medium,</p>	
	9.2.10 A.4.4	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>The tolerances are specified in the MIB, and shallwill only apply to the SIFS specification, so that tolerances shallwill not accumulate.</p>	
	9.2.10	jz	T	Y	<p>The paragraph "The following equations..." claims that the slot definitions take timing variability into account. I think this should be clarified. In any case, it should indicate that it is the <i>PHY MIB</i> that defines the numbers.</p>	<p><<I will write text at the La Jolla meeting after the MAC group has discussed SIFS "slop" and timing variability>></p>	
	9.2.3	ch	e		<p>extra word</p>	<p>PHY MIB parameters are-specify IFS values.</p>	
	9.2.3	jz	T	Y	<p>Treating SIFS as a constant value in the MAC is wrong. Implementations must be allowed a certain amount of "slop" for interframe timings. They must ensure that their frames don't start too soon after a previous frame (or else the intended recipient may not yet be ready to receive),</p>	<p>Each PHY shall define aRxTx_Turnaround_Time in terms of a nominal value plus/minus some tolerance. A conformant 802.11 implementation shall ensure that, when</p>	

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					<p>nor too long (or someone else may grab the medium). We need three SIFS values: min-SIFS, nominal-SIFS and max-SIFS. The duration field should be encoded based on the <i>maximum</i> length of time we allow to elapse between frames (max-SIFS). But the MAC should only wait min-SIFS before telling the PHY to transmit. Basically, the standard has an idealized notion of a MAC that instantaneously commands the PHY to do something, and the PHY instantaneously responds. Real implementations may not be able to ensure sub-microsecond repeatability in timings. There needs to be a (small) window within which frame transmission can commence. Add this paragraph at the end of the subclause:</p>	<p>transmitting a frame after a SIFS, transmission does not occur before the minimum allowable duration of a SIFS nor after the maximum allowable duration of a SIFS.</p>	
	9.2.3.1 A.4.4	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>The SIFS timing shall^{will} be achieved when the transmission of the subsequent frame is started at the Tx_SIFS Slot boundary as specified in clause Error! Reference source not found.</p>	
	9.2.3.2	jz	T	Y	<p>Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.</p>	<p><<Adopt changed text for this section from 96/15 and 96/16.>></p>	
	9.2.4	amb	e		<p>Figure 39 shows Cwmin to be 31. Everywhere else it is set to 7.</p>	<p>Show it as 7 in figure</p>	
	9.2.4	ch	e		<p>CW values 7 and 15 are missing from figure 39..</p>	<p>add values 7 and 15 to figure 39</p>	
	9.2.4	ch	e		<p>sentance should not be underlined</p>	<p>of aCWmax. <u>A retry is defined as the entire sequence of frames sent to attempt to deliver an MPDU.</u> A retry is defined as the entire sequence of frames sent to attempt to deliver an <u>MPDU</u>. The CW will remain at a value of aCWmax for the remaining retries.</p>	

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3	9.2.4	jjk	e		Figure 39 is incorrect and does not reflect the values of 7 and 15 for Cwmin. Also the last sentence uses the word should. It shall be changed to shall.	aCWmin and aCWmax are MAC constants that shall should be fixed for all MAC implementations, because they effect the access fairness between stations.	
	9.2.4	RM	e		Figure 39: revise to correct CWmin		
	9.2.4	ch	t		requirement - needs to be 'shall' instead of 'will'	The CW shall will remain at a value of aCWmax for the remaining retries.	
	9.2.4 11.4.4.2 .27	WD	T	Y	<p>The initial aCWmin default should be increased. This parameter determines the residual collision probability during the collision avoidance process of selecting the backoff delay after a defer. A high collision probability does directly influence the successrate of Broadcast and Multicast traffic, including the Beacon frame used within 802.11. It will further have a negative effect on the efficiency of medium use, resulting in a lower overall throughput of the total system, as demonstrated in the simulations as described in doc P802.11 95/80. The simulation shows a very high "lost Frame" probability for the Cwmin parameter as is currently specified.</p> <p>It is therefore suggested to increase the CWmin parameter as suggested in doc 95/80.</p> <p>The subject of Contention resolution, and Lost frame probability was also addressed in doc 95/182 and 183, with suggestions to decrease the collision probability that was based on the already suggested much larger Cwmin =32. HIPERLAN uses a different mechanism, but their goal is to achieve a maximum collision probability of 3.5 % maximum. The currently specified Cwmin=7 does represent a much much higher collision probability in the 20-30% range. Subsequent simulation results will be presented at the meeting where feasible.</p> <p>Several users that gained experience with the access</p>	<p>Change 9.2.4, just above figure as follows:</p> <p>The set of CW values are $CW=2^k * Cwmin-1$, with k ranging from 0 to a value that results in a $CW=255$.</p> <p>CWmin should be 32 for a DS PHY. CWmin should be TBD for a FH PHY. Cwmin should be TBD for an IR PHY.</p>	

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					<p>method using prototype implementations have testified to me that the suggested Cwmin =7 is too low.</p> <p>This Cwmin parameter should be the same for all stations that do contend for the medium within the same area, because they affect the access fairness between stations, and can therefore be specified on a per PHY basis, unlike described in section 9.2.4, which specifies this value to be the same across all PHY's.</p>		
	9.2.4	AS	t	y	<p>Since aCWmin and aCWmax are MAC constants that effect fairness they should be fixed and not be get/replace in the MIB.</p>	<p>Original Text: aCWmin and aCWmax are MAC constants that should be fixed for all MAC implementations, because they effect the access fairness between stations.</p> <p>Replacement Text: aCWmin and aCWmax are MAC constants that are fixed for all MAC implementations, because they effect the access fairness between stations.</p>	
	9.2.4 7.3.1.11	TT	t	Y	<p>See 7.3.1.11 for detail comment.</p> <p>Immediately after Figure 39 which shows the Exponential increase of CW there is the statement:</p> <p>'aCWmin and aCWmax are MAC constants that should be fixed for all MAC implementations, beacuse they effect the access fairness between stations.'</p> <p>This statement is totally true however aCWmin and aCWmax are GET-REPLACE MIB variables. The optimum setting for these, especially aCWmin, is different depending on:</p> <ul style="list-style-type: none"> - the number of active STAs in a BSS - the percentage of these STAs that on average have data to send. 	<p>Change last sentence of 9.2.4 to say:</p> <p>"aCWmin and aCWmax are settable MAC constants that should shall be fixed for common to all MAC implementations, beacuse they effect the access fairness between stations. STAs within a given BSS. Each STA will update its aCWmin and aCWmax variables from the CW field contained in each Beacon frame received from its AP."</p>	

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					Since each collision wastes bandwidth, reducing the number of collisions should improve the overall BSS throughput, therefore aCWmin and aCWmax should be controlled by the AP of a BSS by including these parameters in each Beacon frame.		
	9.2.4 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not correctly convey operational requirements.	<u>deliver an MPDU.</u> The CW shall will remain at a value of aCWmax for the remaining retries. This	
	9.2.4	jz	T	Y	Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.	<<Adopt changed text for this section from 96/15 and 96/16.>>	
	9.2.4 7.3.1.11	TT	t	Y	<p>There is a need to be able to control the aCWmin and aCWmax values on a per BSS basis. In addition, this control must be fair to all nodes in the BSS.</p> <p>The Current CWmin default of 7 will work fine for a few nodes in a BSS but when the number gets large (>50) then the number of collisions would increase dramatically. Simply making aCWmin = 31 as Wim has asked may times will improve this situation, however it is very inefficient for an STA who is the only associated STA in a BSS to have to wait an average of 15 slot times to transmit each frame.</p> <p>The tradeoff between the individual STA's response time vs BSS throughput will change depending on the application, therefore CW should be a dynamic variable.</p> <p>The current standard does not have any way for aCWmin to be adjusted by any management entity. Putting the fields in the Association Response and Beacon frame would allow a management entity to set these on a per BSS basis in a fair manner. The MIB variables are</p>	<p>Add the fixed field: CW (Contention Window) which contains:</p> <p>CWmin CWmax</p> <p>A STA receiving a management frame with a valid BSSID and with this fixed field shall set its MIB variables aCWmin and aCWmax to these values.</p>	

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					<p>already GET-REPLACE.</p> <p>The default setting should be defined in the MIB and used unless the AP has the capability (and the user has a need) to alter the numbers. From the MAC point of view it does not care what the algorithm is that sets the CW's, but how and where it gets the values to use, as long as everyone in the BSS uses the same numbers.</p> <p>Simple algorithms, which are outside the scope of this standard, could base CW on the number of associated STAs, the current traffic statistics, the number of retry attempts, etc. All of these are, or can be, known by the AP which is the one who should set the CW for its BSS.</p>		
	<p>9.2.4</p> <p>7.3.1.11</p>	<p>TT</p>	<p>t</p>	<p>Y</p>	<p>See 7.3.1.11 for detail comment.</p> <p>Immediately after Figure 39 which shows the Exponential increase of CW there is the statement:</p> <p>'aCWmin and aCWmax are MAC constants that should be fixed for all MAC implementations, because they effect the access fairness between stations.'</p> <p>This statement is totally true however aCWmin and aCWmax are GET-REPLACE MIB variables. The optimum setting for these, especially aCWmin, is different depending on:</p> <ul style="list-style-type: none"> - the number of active STAs in a BSS - the percentage of these STAs that on average have data to send. <p>Since each collision wastes bandwidth, reducing the number of collisions should improve the overall BSS throughput, therefore aCWmin and aCWmax should be controlled by the AP of a BSS by including these</p>	<p>Change last sentence of 9.2.4 to say:</p> <p>"aCWmin and aCWmax are <u>settable</u> MAC constants that should shall be fixed for common to all MAC implementations, because they effect the access fairness between stations. STAs within a given BSS. Each STA will update its aCWmin and aCWmax variables from the CW field contained in each Beacon frame received from its AP."</p>	

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					parameters in each Beacon frame.		
	9.2.4, 11.4.2.2 .1, 11.4.4.2 .27, 11.4.4.2 .28	ch	t		aCWmin and aCWmax are fixed, aren't they? If they're not, isn't an unfair advantage gained by someone who chooses to use 31 as a minimum instead of 7?	<p>9.2.4: aCWmin and aCWmax are MAC constants that are should be fixed for all MAC implementations, because they effect the access fairness between stations.</p> <p>11.4.2.2.1: aCW_max GET-REPLACE, aCW_min GET-REPLACE,</p> <p>11.4.4.27 "This attribute indicates the maximum size of the contention window, in slots. The default value of this attribute shall be 255."</p> <p>11.4.4.28: "This attribute indicates the minimum size of the contention window, in slots. The default value of this attribute shall be 7."</p>	
	9.2.5.1	ch	e		missing “.”, middle of second paragraph	when it detects the free medium for greater than or equal to a DIFS. If, under these conditions,	
	9.2.5.2	BO	E		count and time are used interchangeably when describing backoff.	A STA in backoff must monitor the medium for carrier activity during backoff slots. If no carrier activity is seen for the duration of a particular slot, then the random backoff process shall decrement its <u>backoff time</u> count by aSlot_time.	

Seq. #	Section number	your initials	Comment type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
	9.2.5.2	BO	T	Y	This is patently untrue and must be deleted. Consider the case where two STAs have collided on their initial attempt to transmit. Both will select a random backoff period between 0 and 7. A third station that makes its initial attempt at transmission after this collision event has ended will be able to use the medium after a DIFS with probability 1 when each of the colliding stations will be able to access the medium at that same time only with probability 1/8. This clearly favors newcomers over past colliders.	The advantage of this approach is that stations that lost contention will defer again until after the next medium busy event, and will then likely have a shorter backoff delay than new stations entering the backoff procedure for the first time. This method tends toward fair access on a first come, first served basis.	
	9.2.5.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	A STA in backoff shall must monitor the medium for carrier activity during backoff slots. If no carrier	
	9.2.5.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	the backoff timer shall not be decrement for that slot; The medium shall must be sensed as idle for the duration of a DIFS period before the backoff procedure is allowed to resume. Transmission shall	
	9.2.5.2 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	The effect of this procedure is that when multiple stations are deferring and go into random backoff, then the station selecting the lowest delay through the random function shall will win the contention. The advantage of this approach is that stations that lost contention shall will defer again until after the next medium busy event, and will then likely have a shorter backoff delay than new stations entering the	
	9.2.5.2	jz	T	Y	Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.	<<Adopt changed text for this section from 96/15 and 96/16.>>	

Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
	9.2.5.3	sb	e	n	I assume here (but it does not seem to say explicitly) that the RTS and Data retry counts both increment independently while the sequence is still incomplete, ie the Data retry count does not get reset if an RTS gets retried.	-	
	9.2.5.3 11.4.4.2 .31 11.4.4.2 .32	WD	T	Y	<p>The intent of having two Retry Limits is to cope with two significant different situations. One is that retries are needed to retry a transmission that failed primarily due to residual access collisions in the contention resolution process of CSMA/CA. The other case is primarily geared toward a "Hidden Station" situation, where frames are primarily lost, or CTS is not returned. because the medium is busy in the vicinity of the receive station.</p> <p>In the latter case the defer mechanism does not work for the stations that compete for the medium, and hence a higher value for the Retry Limit is needed to increase the probability that subsequent transmissions are separated in time so that they do not overlap and interfere with each other.</p> <p>So in general the Retry Limit needs to be a higher value in the cases when "Hidden Node" protection is targeted for. This can be detected by looking at the aRTS_Threshold parameter, which is 2305 or higher when the RTS/CTS mechanism is switched off.</p> <p>The current mechanism, together with the values specified in the MIB, causes a reverse behaviour. In addition, when the correct (changed) default values are specified in the MIB, then the effect is that the Short_Retry_Limit (the higher value) is then always used when the RTS/CTS mechanism is effectively turned off.</p> <p>The suggested text corrects this problem, by selecting the Short_Retry_Limit only when the RTS_Threshold parameter is lower then the default 2305.</p> <p>In addition it does reverse and change the defaults values specified in the MIB.</p> <p>It also corrects the problem in the MIB, which</p>	<p>Change text in section 9.2.5.3 Add the following at the end of the last sentence: , unless aRTS_Threshold is higher then 2304, in which case aLong_Retry_Limit should always be used.</p> <p>Change text in section 11.4.4.2.31: Change "aFragmentation_Threshold" into "aRTS_Threshold". Change the default value 5 into 7.</p> <p>Change text in section 11.4.4.2.32: Change "aFragmentation_Threshold" into "aRTS_Threshold". Change the default value 7 into 4.</p>	

Seq. #	Section number	your initials	Comment type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
					inadvertently defines a <u>Fragmentation_Threshold</u> rather than <u>RTS_Threshold</u>.		
	9.2.5.3	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not correctly convey operational requirements.	For instance, CTS may not be returned after the RTS transmission. This mayea happen due to a collision with another RTS or a DATA frame, or due to interference during the RTS or CTS frame. It mayea also be that CTS failed to be returned because the remote station has an active virtual carrier sense condition	
	9.2.5.3 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not correctly convey operational requirements.	required to transmit the ACK frame plus a SIFS . Since this pending transmission is a retransmission attempt the CW shall will be increased (per the backoff rules). This process shall continue until the	
	9.2.5.3	jz	t	Y	CTS_Timeout is not defined. Presumably, it should be SIFS plus however long it takes to detect the start of frame (I have made comments elsewhere that SIFS should really be a window of allowable times to account for implementation jitter). The same goes for ACK_Timeout.		
	9.2.5.3	jz	T	Y	The last two paragraphs are confusing, and don't take into account the complicated possibilities for losing a couple of RTSs/CTSs, then getting a fragment through but losing the ACK, and so forth. That is, we need to clarify whether to add the number of retransmissions of the RTS to any retransmissions of the data before comparing to one of the Retry_Max numbers, and whether to start counting RTS retries over again if we don't get an ACK (i.e. does the sequence RTS...RTS...RTS/CTS/DATA...RTS...RTS leave us with two short retries and one long retry, or four short retries and one long retry, or five retries altogether or what?)	<<I assume we will discuss this at the meeting and I promise to write text at that time, once we agree on how it ought to work.>>	
	9.2.5.3, 11.11.4, 1.2.2,	ch	t	Y	9.2.5.3: CTS_TimeoutTimeout is misspelled, and not defined, and the value sof CW is not doubled	9.2.5.3: If after an RTS is transmitted, the CTS_Timeout Timeout expires without	

Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
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	<p>11.4.2.2 .1, 11.4.3.2 .2, 11.4.4.2 .30</p>				<p>Change the next paragraph to be consistent with the first and refer to the correct MIB variables, and add some punctuation for clarity</p> <p>The conditions for using aShort_Retry_limit and aLong_Retry_limit do not match what is described in the MIB definitions of those variables, so I suggest changing the text here.</p> <p>clause 11: there is no reason for aACK_Timeout to be a MIB variable. It is the sum of two other MIB variables and can be defined as such in the text.</p>	<p><u>reception of a CTS</u>, then a new RTS shall be generated while following the basic access rules for backoff. Since this pending transmission is a retransmission attempt, the CW shall be <u>increased (per the backoff rules)</u>doubled as per the backoff rules. This process shall continue until the number of attempts reaches aShort_Retry_Max. <u>CTS Timeout is equal to aCTS Time plus aSIFS Time.</u></p> <p>The same backoff mechanism shall be used when no ACK frame is received within a predetermined ACK_Timeout, after a directed DATA frame has been transmitted. The ACK_Timeout is equal to aACK Time plus aSIFS Time value is the time required to transmit the ACK frame plus a SIFS. Since this pending transmission is a retransmission attempt the CW shall<u>will</u> be increased (per the backoff rules). This process shall continue until the number of attempts reaches <u>either:</u> aLong_Retry_Max for DATA frames the length of which exceed aFragmentationRTS_Threshold; or, aShort_Retry_Limit for DATA frames the length of which do not exceed aFragmentationRTS_Threshold.</p> <p>11.4.1.2.2: aACK_Time, aACK_Timeout, aShort_Retry_Limit,</p> <p>11.4.2.2.1:</p>	
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Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
						<p>aACK_Time GET, aACK_Timeout GET, aShort_Retry_Limit GET-REPLACE,</p> <p>11.4.3.2.2: aACK_Time, aACK_Timeout, aShort_Retry_Limit,</p> <p>11.4.4.2.30: _____ aACK_Timeout</p> <p>aACK_Timeout ATTRIBUTE WITH APPROPRIATE SYNTAX integer; BEHAVIOUR "This attribute specifies the length of time, in microseconds, in which an ACK frame will be received in response to transmission of a frame which requires acknowledgment, timed from receipt of PHY_DATA.confirm at the MAC. The following equation is used to determine aACK_Timeout: aSIFS_Time + aACK_Time"; REGISTERED AS { iso(1) member-body(2) us(840) ieee802dot11(10036) MAC(1) attribute(7) ack_timeout(29) };</p>	
	9.2.5.4	ch	t		requirement - needs to be 'shall' instead of 'will'	Stations receiving a valid frame shall ould update their NAV with the information received in the Duration field, but only when the new NAV value is greater than the current NAV value and only when the frame is not	

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						addressed to the receiving STA.	
	9.2.5.4	sb	e	n	Need to specify behaviour of NAV for the multirate case. Two possibilities are apparent: (1) set the NAV to cover the max packet length plus ACK; (2) don't worry about it and let CCA play an active role. The later is what will happen for a corrupted frame (FCS error for example). It is also what will happen for a PS-Poll-Data-Ack since the data frame length is unknown. I think the best option here is to rely on CCA. This requires no change to the text because it already has 'valid frame' in the text, but might benefit from a clarifying note.	Clarification note on imperfections in NAV and reliance on CCA under certain conditions.	
	9.2.5.4	WD	T	Y	<p>There is a problem with the current RTS/CTS NAV setting procedure. There are cases where a CTS does not follow an RTS as is expected when the RTS collides in the vicinity of the receiver, or when at the receiver the NAV is set, such that it prevents the transmission of a CTS. The effect of this is that all traffic around the transmitter is prevented, because the NAV is set in all stations, but the medium is not used for the subsequent data, because the CTS is missing. The only traffic that is then possible is the retransmission of the RTS, which may again be failing because no CTS is returned, thereby only extending the NAV setting.</p> <p>In the original proposal there were provisions that would allow stations that do hear an RTS, but no subsequent Data after a RTS Timeout period to undo the previous setting of the NAV.</p> <p>It should be allowed to implement that MAC such that a station can undo such a NAV setting when it was caused by an RTS (or Data frame when fragmentation is used), but not when the update was done by a CTS.</p> <p>All stations that do hear the RTS will also hear the subsequent Data if it is there, so lack of Data traffic after the RTS Timeout (2*SIFS + CTS + Slot) is a valid condition to undo the previous NAV setting.</p>	<p>Add the following text at the end beyond figure 42:</p> <p>Stations that did set the NAV upon reception of an RTS may undo this setting when they do not detect a subsequent Data frame after a RTS Timeout period following the received RTS which has a duration of 2*SIFS+CTS+Slot time.</p>	
	9.2.5.4	db	T	Y	w/o the requested change the Draft is technically	condition of the medium. Error!	

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					incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	Reference source not found. indicates the NAV for stations that <u>mayean</u> hear the RTS frame, while other stations may only receive the CTS frame, resulting in the lower NAV bar as shown (with the	
	9.2.5.5	ch	t		A lot of 'will' to 'shall', following the figure and delete some un-needed text	<p>When tThe source station transmits a fragment, then releases the channel and waits for an acknowledgment. When the source station it shall releases the channel following its fragment, it will then immediately monitor the channel for an acknowledgment frame from the destination station.</p> <p>When the destination station has finished sending the acknowledgment, the SIFS following the acknowledgment shall beis then reserved for the source station to continue (if necessary) with another fragment. The station sending the acknowledgment does not have permission to transmit on the channel immediately following the acknowledgment.</p> <p>The process of sending multiple fragments after contending for the channel is defined as a fragment burst.</p> <p>If the source station receives an acknowledgment but there is not enough time to transmit the next fragment and receive an acknowledgment due to an impending dwell boundary, it shallwill contend for the channel at the beginning of the next</p>	

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						<p>dwel time.</p> <p>If the source station does not receive an acknowledgment frame, it shallwill attempt to retransmit according to the backoff algorithm and . When the time arrives to retransmit the fragment, the source station will contend for access in the contention processwindow.</p> <p>After a station contends for the channel to retransmit a fragment of a MSDU, it shallwill start with the last fragment that was not acknowledged. The destination station will receive the fragments in order (since the source sends them one at a time, in order). It is possible however, that the destination station may receive duplicate fragments. It shall be the responsibility of the receiving station to discard duplicate fragments. This will occur if the destination station sends an acknowledgment and the source does not receive it. The source will retransmit the same fragment after executing the backoff algorithm and contending for the channel.</p> <p>A station shallwill transmit after the SIFS only under the following conditions during a fragment burst:</p> <p style="padding-left: 40px;">The station has just received a fragment that requires acknowledging.</p> <p style="padding-left: 40px;">The source station has</p>	

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						<p>received an acknowledgment to a previous fragment, has more fragment(s) for the same MSDU to transmit, and there is enough time left in the dwell time to send the next fragment & receive an acknowledgment.</p> <p>The following rules also apply.</p> <p>When a station has transmitted a frame other than a fragment, it shall not transmit on the channel following the acknowledgment for that frame, without going through a backoff.</p> <p>When an MSDU has been successfully delivered, and the station has a subsequent MSDU to transmit, then it shall go through a backoff.</p> <p>Only unacknowledged fragments are retransmitted.</p> <p>If a multiple fragment MSDU does not require an acknowledgment (for example, a broadcast/multicast packet transmitted by the Access Point), the source station shallwill transmit all fragments of the MSDU without releasing the channel, as long as there is enough time left in the dwell time. If there is not, the station shallwill transmit as many fragments as possible and recontend for the channel during</p>	

Seq. #	Section number	your initials	Comment type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
						the next dwell time. The spacing between fragments of a broadcast/multicast frame shall be equal to the SIFS period.	
	9.2.5.5	jz	t		I don't see that fragmenting broadcasts/multicasts serves any purpose. Since we can't retry them, their reliability is in fact reduced by adding all the extra header/CRC bits to their transmission. (Or is there some weird radio-physics thing that makes later bits in a frame more likely to get corrupted than early ones?)		
	9.2.5.5	AS	t	y	If a fragment burst is interrupted the AP may not be able to resume sending the fragments if it has to transmit a beacon and possibly a CFP or broadcast frames.	<p>Original Text: Should the sending of the fragments be interrupted due to one of these reasons, when the next opportunity for transmission occurs the station shall resume sending the fragments .</p> <p>Replacement Text: Should the sending of the fragments be interrupted due to one of these reasons, the station shall resume sending the fragments at its earliest opportunity.</p>	
	9.2.5.5	AS	t	y	The destination station will receive fragments for the same frame in order, but there may be an indeterminate number of fragmented frames received from the same station between two fragments of the same frame.	<p>Original Text: The destination station will receive the fragments in order (since the source sends them one at a time, in order).</p> <p>Replacement Text: The destination station will receive fragments of the same MSDU in order (since the source sends them one at a time, in order).</p>	
	9.2.5.5	BO	T	Y	The rule is incomplete	When an MSDU has been successfully delivered <u>or all retransmission attempts have been used</u> , and the station has a subsequent MSDU to transmit, then it shall go through a backoff.	

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	9.2.5.5	TT	T	Y	See Rationale in comment of Section 9.1.4 on not fragmenting broadcast frames.	Delete last paragraph of Section 9.2.5.5. If a multiple fragment MSDU does not require.....	
	9.2.5.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	MSDU have been sent, an acknowledgment is not received, or the station <u>is restricted from</u> can not sending any additional fragments due to a dwell time boundary. Should the sending of the fragments be	
	9.2.5.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	When the source station releases the channel following its fragment, it <u>shall</u> will immediately monitor the	
	9.2.5.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	fragment and receive an acknowledgment due to an impending dwell boundary, it <u>shall</u> will contend for	
	9.2.5.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	If the source station does not receive an acknowledgment frame, it <u>shall</u> will attempt to retransmit according to the backoff algorithm. When the time arrives to retransmit the fragment, the source station <u>shall</u> will contend for access in the contention window.	
	9.2.5.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	After a station contends for the channel to retransmit a fragment of a MSDU, it <u>shall</u> will start with the last fragment that was not acknowledged. The destination station <u>will</u> receives the fragments in order (since the source sends them one at a time, in order). It is possible however, that the destination station may receive duplicate fragments. It	

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						<p>shall be the responsibility of the receiving station to discard duplicate fragments. This may<u>will</u> occur if the destination station sends an acknowledgment and the source does not receive it. The source shall<u>will</u> retransmit the same fragment after executing the backoff algorithm and contending for the channel.</p> <p>A station shall<u>will</u> transmit after the SIFS only under the following conditions during a fragment burst:</p>	
	9.2.5.5 A.4.4	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>If a multiple fragment MSDU does not require an acknowledgment (for example, a broadcast/multicast packet transmitted by the Access Point), the source station shall<u>will</u> transmit all fragments of the MSDU without releasing the channel, as long as there is enough time left in the dwell time. If there is not, the station shall<u>will</u> transmit as many fragments as possible and recontend for the channel during the next dwell time. The spacing between fragments of a broadcast/multicast frame shall be equal to the SIFS</p>	
	9.2.5.5	jz	T	Y	<p>Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.</p>	<p><<Adopt changed text for this section from 96/15 and 96/16.>></p>	
	9.2.5.5	TT	T	Y	<p>See Rationale in comment of Section 9.1.4 on not fragmenting broadcast frames.</p>	<p>Delete last paragraph of Section 9.2.5.5.</p>	

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						If a multiple fragment MSDU does not require.....	
	9.2.5.6	jz	E		The diagram is yucky. The NAVs are all one big black blob. It should be redrawn to clarify (in black/white) which parts of the NAV came from which frames' Duration field. Also, need to substitute "0" for "1" throughout the second paragraph.		
	9.2.5.6	WD	E	n	Change the fill pattern in figure 44 to show the actual NAV durations, and the RTS frame.		
	9.2.5.6 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	The following is a description of using RTS/CTS for the first fragment of a fragmented MSDU. RTS/CTS <u>maywill</u> also be used for retransmitted fragments if their size warrants it. The RTS/CTS frames define the	
	9.2.5.6 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	Each frame contains information that defines the duration of the next transmission. The RTS <u>shallwill</u> update the NAV to indicate busy until the end of ACK 1. The CTS <u>shallwill</u> also update the NAV to indicate busy until the end of ACK 1. Both Fragment 1 and ACK 1 <u>shallwill</u> update the NAV to indicate busy until the end of ACK 2. This is done by using the duration field in the DATA and ACK frames. This <u>shallwill</u> continue until the last Fragment which has a duration of one ACK time plus one SIFS time and its ACK which <u>shallwill</u> have the duration set to zero. Each Fragment and ACK acts as a virtual RTS and CTS, therefore no RTS/CTS frame needs to be generated even though subsequent fragments are larger the aRTS_Threshold.	

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 						<p>In the case where an acknowledgment is not received by the source station, the NAV shall will be marked busy for next frame exchange. This is the worst case situation. This is shown in Error! Reference source not found. If the acknowledgment is not sent by the destination station, stations that may can only hear the destination station shall will not update their NAV and be free to access the channel. All stations that hear the source shall will be free to access the channel after the NAV from Frame 1 has expired.</p>	
	9.2.6	WD	T	Y	<p>There is currently no CTS procedure described. This is of particular interest, because the CTS may only be returned by a addressed station, when the NAV indicates a free medium, while there is no time to react on the physical CCA signal, because the CTS is to be returned after a SIFS.</p>	<p>Add the following text, preferably in section that is inserted in between 9.2.6.1 and 9.2.6.2. - CTS Procedure: A station that is addressed by the RTS frame, will transmit a CTS frame after SIFS, but only when the NAV does indicate that the medium is free. The CTS shall be addressed to the TA address present in the RTS frame. The duration field in the CTS frame shall be the duration field from the received RTS frame, adjusted by subtraction of SIFS and CTS time duration.</p>	
4	9.2.6.1	jjk	e		<p>Incorrect parameter in range specifier in second paragraph</p>	<p>The aRTS_Threshold attribute shall be a managed object within the MAC MIB, and its value can be set and retrieved by the MAC LME. The aRTS_Threshold attribute shall be constrained to range (0 ... aMax Frame Length+1Maximum)</p>	

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						MPDU Length). The value 0 shall be used to indicate that all MPDU shall be delivered with the use of RTS/CTS. Values of aRTS_Threshold \geq aMax_Frame_Length shall indicate that all MPDUs shall be delivered without RTS/CTS.	
	9.2.6.1	ch	t		<p>These two subclauses are cumbersome. It would be clearer with just one subclause describing Directed MPDU Transfer followed by the one describing Broadcast And Multicast MPDU Transfer.</p> <p>Also, Figure 46 and the paragraph immediately preceding it, describe the ACK procedure, and should be moved to clause 9.2.8. Also a few words added to that moved paragraph would help its clarity.</p>	<p>9.2.6 Directed MPDU Transfer Procedure</p> <p>9.2.6.1 Directed MPDU Transfer Procedure Using RTS/CTS</p> <p>STA shall use an RTS/CTS exchange for directed frames only when the length of the MPDU is greater than the length threshold indicated by the aRTS_Threshold attribute.</p> <p>The aRTS_Threshold attribute shall be a managed object within the MAC MIB, and its value can be set and retrieved by the MAC LME. The aRTS_Threshold attribute shall be constrained to range (0 ... Maximum MPDU Length). The value 0 shall be used to indicate that all MPDU shall be delivered with the use of RTS/CTS. Values of aRTS_Threshold \geq aMPDU_Max_Length shall indicate that all MPDUs shall be delivered without RTS/CTS.</p> <p><u>When RTS/CTS are used</u> The asynchronous payload frame (e.g.</p>	

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						<p>DATA) shall be transmitted after the end of the CTS frame and an SIFS period. No regard shall be given to the busy or free status of the medium.</p> <p>9.2.6.2 Directed MPDU Transfer Procedure without RTS/CTS</p> <p><u>When RTS/CTS are not used, following the basic access mechanism, the source STA shall transmit the asynchronous payload frame (e.g. DATA) shall be transmitted following the basic access mechanism.</u></p> <p><u>-With or without use of the RTS/CTS mechanism, the destination STA which is the destination of a directed asynchronous payload frame shall follow the ACK Procedure.</u></p> <p><u>The source STA shall start its backoff time a DIFS after the end of the ACK or a DIFS after aACK Timeout.</u></p> <p>Figure 46</p> <p>Add to the end of subclause 9.2.8 Ack Procedure:</p> <p><u>The source STA shall start its backoff time a DIFS after the end of the ACK or a DIFS after aACK Timeout prior to accessing the medium again.</u></p> <p>Figure 46</p>	
	9.2.6.1	db	T	Y	w/o the requested change the Draft is technically	The aRTS_Threshold attribute shall be	

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					incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	a managed object within the MAC MIB, and its value mayea be set and retrieved by the MAC LME. The aRTS_Threshold attribute shall be constrained to range (0 ...	
	9.2.7 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	the MPDU is directed to the AP. The Broadcast/Multicast message shall will be distributed into the BSS. The station originating the message shall will receive the message as a Broadcast/Multicast message. Therefore all stations shall must filter out Broadcast/Multicast messages which contain their address as the source address.	
	9.2.7	jz	T	Y	Multicast/Broadcast reliability is compromised by the power save mechanism. We should adopt the mechanism is 96/15 and 96/16 to fix this. My "No" vote will only change to a "Yes" vote if we adopt these changes or else mandate the use of a stripped-down PCF to enhance multideestination reliability.	<<Adopt changed text for this section from 96/15 and 96/16.>>	
	9.2.8	BO	T	Y	Text is intended to be explanatory but winds up being confusing. Delete it.	This policy induces some probability that another frame could be corrupted by the generated ACK. However if no ACK is returned because a busy medium is detected, then it is guaranteed that a retransmission results.	
	9.2.9	BO	E		Edit for clarity.	<u>A destination STA shall reject a frame as a duplicate frame, any frame that has the RETRY bit set in the Frame Control field and matches a <source-address, sequence-number and fragment-number> tuple of an entry in the cache .</u>	

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	9.2.9	ch	e		duplicate word, second paragraph	Duplicate frame filtering is facilitated through the inclusion of a Sequence Control Field (consisting of a sequence number and fragment number) field within Data and Management frames.	
	9.2.9 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	sequence number and fragment number) field within Data and Management frames. MPDUs which are part of the same MSDU shall have the same sequence number, and different MSDUs shall will (with a high probability) have a different sequence number.	
	9.2.9 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	There is the small possibility that a frame may will be improperly rejected due to such a match; however, this occurrence would be rare and will simply results in a lost frame (similar to an FCS error in Ethernet).	
	9.3	AS	t	y	The PC does not gain priority access due to the use of PIFS but due to the fact that everybody else has their NAV set during the CFP.	<p>Original Text: All STA inherently obey the medium access rules of the PCF, because these rules are based on the DCF, with the Point Coordinator gaining priority access to the medium using a PCF IFS (PIFS) which is smaller than the DCF IFS (DIFS) used by the DCF to access the medium.</p> <p>Replacement Text: All STA inherently obey the medium access rules of the PCF, because these rules are based on the DCF, and they</p>	

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						set their NAV at the beginning of each CFP.	
	9.3	ch	T	Y	<p>According to subclause 5.5, Class 3 frames, whcih include the CFP control frames, can only be sent when associated. According to subclause 5.4.2.2, association is a service between a statino and an AP.</p> <p>I think this means that only an AP can be a Point Coordinator (in fact, it says that a few paragraphs later, but I had fun figuring it out the hard way!).</p>	It is an option for an <u>AP</u> -STA to be able to become the Point Coordinator(PC).	
	9.3	TT	t	Y	<p>Section 9.3.2 indicates that the PC is in the AP. Therefore non-AP STAs cannot be the PC.</p> <p>Stronger wording to ensure only one frame is transmitted on a CF-Poll. Also how a CF-Aware station handles the need to retransmit is not explitctly described.</p>	<p>Rewrite second sentence 'It is an option for....' as follows:</p> <p>The Point Coordinator(PC) must reside in the AP. It is an option for an AP to become the PC.</p> <p>Change text in first paragraph:</p> <p>.....in the contention free period. When polled by the Point Coordinator, a CF-Aware station may transmit only one frame to any destination (not just to the Point Coordinator), and may "piggyback" the acknowledgment of a frame received from the Point Coordinator using particular data frame subtypes for this transmission. If the data frame is not in turn, acknowledged theCF-Aware station shall not re-transmit the frame until it is polled again by the Point Coordinator. The CF-Aware station shall maintain the same sequence number in subsequent transmissions of the same frame even though it may have transmitted them in other CFPs or even the Contention Period. If the</p>	

Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
					<p>How retries are handled during the CFP is not mentioned in this standard. I believe the assumption was that the PC can move on with its polling list rather than retrying an unacknowledged frame. Since this is somewhat different to the DCF rules it should be stated explicitly.</p>	<p>addressed recipient of a CF</p> <p>Add new paragraphs after 1st paragraph:</p> <p>A PCF that is maintaining a polling list shall not perform a DCF retry on an unacknowledged frame transmission during the CFP. The frame can be transmitted again the next time the particular SID is at the top of polling list. The AP shall maintain the same sequence number in subsequent transmissions of the same frame even though it may have transmitted other new frames.</p> <p>A PCF may re-transmit an unacknowledged frame during the CFP after a PIFS time.</p>	
	9.3	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>The rules under which multiple, overlapping point-coordinated BSSs <u>may</u> coexist are presented in</p>	
	9.3	TT	t	Y	<p>Section 9.3.2 indicates that the PC is in the AP. Therefore non-AP STAs cannot be the PC.</p> <p>Stronger wording to ensure only one frame is transmitted on a CF-Poll. Also how a CF-Aware station handles the need to retransmit is not explictly described.</p>	<p>Rewrite second sentence 'It is an option for....' as follows:</p> <p>The Point Coordinator(PC) must reside in the AP. It is an option for an AP to become the PC.</p> <p>Change text in first paragraph:</p> <p>.....in the contention free period. When polled by the Point Coordinator, a CF-Aware station may transmit only one frame to any destination (not just to the Point Coordinator), and may</p>	

Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
					<p>How retries are handled during the CFP is not mentioned in this standard. I believe the assumption was that the PC can move on with its polling list rather than retrying an unacknowledged frame. Since this is somewhat different to the DCF rules it should be stated explicitly.</p>	<p>“piggyback” the acknowledgment of a frame received from the Point Coordinator using particular data frame subtypes for this transmission. If the data frame is not in turn, acknowledged the CF-Aware station shall not re-transmit the frame until it is polled again by the Point Coordinator. The CF-Aware station shall maintain the same sequence number in subsequent transmissions of the same frame even though it may have transmitted them in other CFPs or even the Contention Period. If the addressed recipient of a CF</p> <p>Add new paragraphs after 1st paragraph:</p> <p>A PCF that is maintaining a polling list shall not perform a DCF retry on an unacknowledged frame transmission during the CFP. The frame can be transmitted again the next time the particular SID is at the top of polling list. The AP shall maintain the same sequence number in subsequent transmissions of the same frame even though it may have transmitted other new frames.</p> <p>A PCF may re-transmit an unacknowledged frame during the CFP after a PIFS time.</p>	
	9.3.1 9.3.3.4	WD	E	n	This section uses the CFP_Rate field name, whereas this is specified as the CFP Period field in section 7.3.2.5	Change all occurrences of CFP_Rate into CFP_Period.	
	9.3.1	ch	t	Y	Subclause 7.3.2.5 says that the field in the DTIM	This value, in units of DTIMbeacon	

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					<p>beacon is CFP_Period (not rate) and is defined in units of DTIM Intervals (not beacon intervals).</p> <p>Corresponding comment has been made in 11.4.4.1.24 to change the MIB definition of CFP_Rate</p>	<p>intervals, is communicated to other stations in the BSS in the CFP_PeriodRate field of the CF Parameter Set Element of Beacon frames.</p>	
	9.3.1	ch	t	Y	Says rate, really means duration	If the CFP DurationRate is greater than the beacon interval, the PC shall transmit beacons at the appropriate times during the CFP	
	9.3.1 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not correctly convey operational requirements.	<p>delay. In the case of a busy medium due to DCF traffic, the beacon shall will be delayed for the time required to complete the current DCF frame exchange. The longest delay will occurs when if the current frame exchange is an MSDU which is larger than both aRTS_Threshold and aFragment_Threshold. In</p>	
	9.3.2	AS	t	y	Contention in the CF period is prevented because everybody set their NAV	<p>Original Text:</p> <p>This prevents most contention by preventing non-pollled transmissions by stations which received the beacon, whether or not they are CF-Aware.</p> <p>Replacement Text:</p> <p>This prevents most contention by preventing non-pollled transmissions by stations whether or not they are CF-Aware.</p>	
	9.3.2.2	mif	e	N	fix dangling reference	reference should be to clause 11.1.2.1	
	9.3.2.2	ch	t	Y	<p>There is no CFP_Rate in the CF parameter set, the re is Period and Count.</p> <p>The STA needs to be prepared to set its NAV at TBTT, based upon when the Beacon Interval times</p>	<p>at which a Contention Free Period is scheduled to start (based on the CFP_CountRate in the CF Parameter Set Element of the beacons from this</p>	

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					CFP_Count. This needs to be recalculated with every Beacon received, just in case something changed.	PC)	
	9.3.2.2	ch	T	Y	<p>This subclause says that STA must update their NAV according to the CF_Dur_Remaining in any Beacon, even one from another BSS.</p> <p>This subcaluse does not say whether a STA should preset its NAV at TBTT when it is known from information in Beacons for another BSS that that BSS is going to start a CFP.</p> <p>If this is the case, some limit needs to be set here, because it is going to require one timer for each of these potential TBTTs at which the STA may have to preset its NAV due to a CFP start.</p> <p>I think this is all asking too much, and a STA should only have to pay attention to the Beacon information from its own BSS. Supposedly the fact that the PCF is built on the DCF is going to stop STA from interfering with any CFP that it can hear. If a STA can hear the Beacon, then it can hear half of most of the traffic going on during the CFP, and using the frame duration properly will take care of this.</p>	<p>Each non-PC station shall update its NAV using the CF_Dur_Remaining value in any error-free CF Parameter Set Element of the beacon frame containing such an element that the station receives. This includes CF_Dur_Remaining values in CF Parameter Set Elements from beacons received from other (overlapping) BSSs. This prevents stations from taking control of the medium during the CFP, which is especially important in cases where the CFP spans multiple medium occupancy intervals, such as dwell periods of an FH-PHY. This setting of the NAV also reduces the risk of hidden stations sensing a DIFS during the CFP and possibly corrupting a transmission in progress.</p>	
	9.3.2.2	TT	t	Y	<p>If the assumption is that hearing a foreign BSS's beacon with a valid CF_Dur_Remaining value should set the NAV to prevent interference with the foreign BSS's CFP, then it is best to play it safe and not reset the NAV until it expires. (I think it's too much to ask an STA to also be able to clear a NAV set by a foreign BSS when it hears a CF_End from that foreign BSS.)</p>	<p>Add to end of last paragraph:</p> <p>Receipt of either of these frame shall reset the NAV of all stations in the BSS, unless the NAV was set by a Beacon from an overlapping BSS in which case the NAV shall be allowed to expire normally.</p>	
	9.3.2.2	TT	t	Y	<p>If the assumption is that hearing a foreign BSS's beacon with a valid CF_Dur_Remaining value should set the NAV to prevent interference with the foreign BSS's CFP, then it is best to play it safe and not reset the NAV until it expires. (I think it's too much to ask an STA to also be</p>	<p>Add to end of last paragraph:</p> <p>Receipt of either of these frame shall reset the NAV of all stations in the BSS, unless the NAV was set by a</p>	

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					able to clear a NAV set by a foreign BSS when it hears a CF_End from that foreign BSS.)	Beacon from an overlapping BSS in which case the NAV shall be allowed to expire normally.	
	9.3.2.2, 9.3.3.1	ch	t	Y	Receipt of a CF-End should only reset the NAV if the NAV is set because of the CFP. If your NAV was set by the CFP, then set to longer due to something else you can hear, clearing it will cause you to destroy that other thing.	The PC shall transmit a CF-End or CF-END+ACK frame at the end of each CF-Period. Receipt of either of these frames shall reset the NAV of all stations in the BSS, <u>for STA at which the CFP is the only reason the STA has the NAV set at the time the CF-End or CF-End+ACK frame is received.</u> Also the last sentence of 9.3.3.1: All stations of the BSS receiving a CF-End or CF-END+ACK, <u>at which the CFP is the only reason the STA has the NAV set at the time the CF-End or CF-End+ACK frame is received,</u> reset their NAVs so they may attempt to transmit during the contention period.	
	9.3.3.1	ch	t	Y	CF_Max_Duration may span more than one beacon interval, so this text must be wrong.	The CFP ends when the CFP_Max_Dur_Remaining time time has elapsed since the last Beacon or when the PC has no further frames to transmit nor stations to poll.	
	9.3.3.1 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	A CF-Poll bit in the Subtype field of these frames shall will allow the stations to send their data frames if any. Stations shall respond to the CF-Poll immediately when a frame is queued, by sending this frame	
	9.3.3.1 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	addressed to a different station than the one being acknowledged. This shall occur only if the acknowledged	

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						frame/fragment was marked as last fragment in the frame control. CF-Aware stations that	
	9.3.3.1 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	A CF-Aware station shall must respond to a CF-Poll. If the station has no frame to send when polled, the response shall be a Null frame. If the station has no frame to send when polled, but an acknowledgment is	
	9.3.3.2	ch	t	Y	This subclause implies that if a STA to STA transfer is fragmented and sent during the CFP, each fragment (i.e. Data/Ack pair) can only be sent after a CF-Poll from the PC - i.e. the two STAs cannot do repeated Data/Ack transactions following a CF-Poll. Is this true?		
	9.3.3.3	ch	T	Y	Normally the PC does not check the status of the medium before transmitting during the CFP. The desire here is not just for the PC to leave a gap of some length every aMedium_Occupancy_Time, but for it to then sense the medium before re-taking it after that gap. This is not specified here.	To further reduce the susceptibility to inter-PCF collisions, the PC shall require the medium be free for a DIFS plus random (over range of 1 to aCW_min) number of slot times once every aMedium_Occupancy_Limit Kmicroseconds during the CFP. <u>After the medium as been unused by the PC for this amount of time. the PC must sense the medium to be free for a PIFS prior to seizing control again.</u> This can only result in loss of control of the medium to overlapping BSS or hidden station traffic,	
	9.3.3.3	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	aMedium_Occupancy_Limit Kmicroseconds during the CFP. This can only results in loss of control of	
	9.3.3.4 &	WD	T	Y	The current definition of the CFP_Max_Duration limit is not sufficient to allow non-CF_aware stations to succesfully transfer data, with such transfer delays	Add to the end of section 9.3.3.4: The CFP_period shall be no larger then 200 msec to allow sufficient	

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	11.4.4.1.26				<p>that are acceptable to higher protocol layers. Known values of such timeout mechanisms are in the 400-600 msec range, after which a protocol layer message is expected to be received. This means that a station should at maximum have an opportunity to send every 200 msec or so, otherwise the higher layer times out, and retransmits the same message with a limited maximum retry limit.</p> <p>Currently the CFP_Period can be specified as multiple integers of the DTIM interval, where the MIB default is set to 5.</p> <p>We need to specify that the CFP_Period should be limited to 200 msec maximum.</p> <p>Change the MIB defaults such that this setting would not violate the 200 msec maximum</p>	<p>response time for a non-CF-Aware station to access the medium.</p> <p>Modify section 11.4.4.1.24: Change the default value to 1</p> <p>Modify section 11.4.4.1.26: Change the default to 2.</p>	
	9.3.3.5	ch	e		punctuation and grammer	Such a frame directed to a non-PCF stations shall be acknowledged using an ACK Control frame sent after an SIFS (This is the same as these stations already do-).	
	9.3.3.5	ch	t	Y	<p>The first and second paragraphs contradicts the 2nd last paragraph of 9.3.3.1, which says that a CF-Poll can be answered with a Null Frame or a regular Ack.</p> <p>Which is correct?</p>		
	9.3.3.5	ch	t	Y	clarity and consiseness	The PC shall not issue frames with a sub-type which includes CF-Polls if insufficient time remains in the current CFP to permit the polled station to transmit a Data frame containing a maximum length MPDU.	
	9.3.4.1	BO	T	Y	Remove vestiges of time bounded services.	The PC shall issue polls to stations whose entries on the polling list are for reasons other than time bounded service connections in order by	

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						ascending SID value.	
	9.3.4.1	BO	T	Y	Restrict and clarify usage of CFP	While time remains in the CFP, <u>the delivery of all CF frames has been completed and all stations on the polling list have been polled</u> , the PC may generate one or more CF-Polls to <i>any</i> stations on the polling list. While time remains in the CFP, <u>the delivery of all CF frames has been completed and all stations on the polling list have been polled</u> , the PC <i>may</i> send Data or Management frames to <i>any</i> stations.	
	9.4	amb	e		“Error! Reference...” should be corrected		
	9.4	ch	e		grammer	The fragmentation and reassembly mechanisms allows for fragment retransmission.	
	9.4	db	E	n	2ND paragraph auto ref bad.	fix reference	
	9.4	sb	e	n	Minor editorials in the second paragraph of this section. Three periods and an erroneous reference.	Correct.	
	9.4	TT	t	Y	The text in this section was confusing as it refered to payload which was not defined. Since fragments are MPDUs and its the MPDU length that is set to aFragmentation_Threshold the text needs rewording.	Change text of second paragraph: The payload size of a fragment MPDU shall be an equal number of octets for all fragments except for the last, which may be smaller. The payload size of a fragment MPDU shall never be larger than aFragmentation_Threshold unless WEP is invoked..... Change text of third paragraph: When data is to be transmitted, the number of octets in the payload fragment (pre WEP processing) of the	

Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
					Since only FH radios have dwell time boundaries the text should explicitly say its talking about an FH radio.	<p>fragment shall be determined by</p> <p>Change text of fourth paragraph:</p> <p>The number of data octets in the payload of a fragment MPDU shall depend on aFragmentation_Threshold and the number of octets in the MPDU that have not yet been assigned to a fragment the values of the following variables at the instant the fragment is constructed for the first time.:</p> <ul style="list-style-type: none"> a) aFragmentation_Threshold b) The number of octets in the MSDU that have not yet <p>Change text of second last paragraph:</p> <p>Since the In an FH PHY station, control of the channel will be lost</p>	
	9.4 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	is invoked for the MPDU... If WEP is active for the MPDU, then the MPDU shall <u>will</u> be expanded by IV and ICV (see clause Error! Reference source not found.), this mayean result in a fragment larger than aFragmentation_Threshold.	
	9.4 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	Since the control of the channel is <u>will</u> be lost at a dwell time boundary and the station shall <u>will</u> have to contend for the channel after the dwell boundary, it is required that the acknowledgment of a fragment be	

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	9.4	mif	T	Y	<p>The provision that the frame body of all fragments, except the final fragment of an odd-length MSDU, shall be an even number of octets is no longer present in this sub-clause. This provision was a fundamental aspect of my votes in favor of the fragmentation proposal at the July, 1994 Plenary meeting, and in the successful resolution of some of my letter ballot comments relating to fragmentation in earlier letter ballots. Its omission in D3.0 renders the entire fragmentation mechanism unacceptable. If fragmentation is to be retained, all fragments, other than the final fragment, should be required to be both equal in length and an even number of octets in length. The added overhead in many implementations of reassembling fragments of odd length is unnecessary and unjustifiable, especially considering that only 1 of the 3 PHYs has a major need for fragmentation, and 1 of the other PHYs has no need for fragmentation, so the facility is present in the MAC for (at most) 1.5 out of 3 PHYs.</p> <p>(This text change also corrects an editorial problem with a dangling reference.)</p>	<p>The payload of a fragment shall be an equal number of octets for all fragments except the last, which may be smaller. The payload of a fragment shall <u>always contain an even number of octets, except for the last fragment of an odd-length MSDU, which shall contain an odd number of octets.</u> The payload of a <u>fragment shall</u> never be larger than aFragmentation_Threshold unless WEP is invoked for the MPDU.. . If WEP is active for the MPDU, then the MPDU will be expanded by IV and ICV (see clause 8.), this can result in a fragment larger than aFragmentation_Threshold.</p>	
	9.4	TT	t	Y	<p>The text in this section was confusing as it referred to payload which was not defined. Since fragments are MPDUs and its the MPDU length that is set to aFragmentation_Threshold the text needs rewording.</p>	<p>Change text of second paragraph:</p> <p>The payload size of a fragment MPDU shall be an equal number of octets for all fragments except for the last, which may be smaller. The payload size of a fragment MPDU shall never be larger than aFragmentation_Threshold unless WEP is invoked.....</p> <p>Change text of third paragraph:</p> <p>When data is to be transmitted, the number of octets in the payload fragment (pre WEP processing) of the fragment shall be determined by</p>	

Seq. #	Section number	your initials	Cmnt type E, e, T, t	Part of NO vote	Comment/Rationale	Corrected Text	Disposition/Rebuttal
					<p>Since only FH radios have dwell time boundaries the text should explicitly say its talking about an FH radio.</p>	<p>Change text of fourth paragraph:</p> <p>The number of data octets in the payload of a fragment MPDU shall depend on aFragmentation_Threshold and the number of octets in the MPDU that have not yet been assigned to a fragment the values of the following variables at the instant the fragment is constructed for the first time.:</p> <p>a) aFragmentation_Threshold b) The number of octets in the MSDU that have not yet</p> <p>Change text of second last paragraph:</p> <p>Since the In an FH PHY station, control of the channel will be lost</p>	
	9.5	TT	t	Y	Incorrect text.	<p>Change More Fragments Indicator description as follows:</p> <p>More Fragments Indicator: Indicates to the destination station that this is not the last fragment.....</p>	
	9.5 A.4.4	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>MSDU. Only the last or sole fragment of the MSDU shall<u>will</u> have this bit set to zero. All other fragments of the MSDU shall<u>will</u> have this bit set to one.</p>	
	9.5 A.4.4	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was</p>	<p>The destination station shall<u>can</u> reconstruct the MSDU by combining</p>	

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					not used the draft does not corectly convey operational requirements.	the fragments in order of Fragment Number portion of the Sequence Control Field. If WEP has been applied to the fragment it shall be	
	9.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	not yet complete. As soon as the station receives the fragment with the More Fragments bit set to zero, the station knows that no more fragments <u>may</u> will be received for the MSDU.	
	9.5 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	To properly reassemble MPDUs into an MSDU, a destination station shall <u>must</u> discard any duplicated fragments received. If a station receives a fragment with the same Source, Destination, and Sequence Control Field as a previous fragment, then the station shall <u>must</u> discard the duplicate fragment. However an acknowledge shall <u>must</u> be sent in response to a duplicate fragment of a directed MSDU.	
	9.5	TT	t	Y	Incorrect text.	Change More Fragments Indicator description as follows: More Fragments Indicator: Indicates to the destination station that this is not the last fragment.....	
	9.6	BO	T	Y	Remove all reference to multirate support. The draft provides no mechanism, other than this meager attempt at window dressing, to ensure interoperability and to ensure that attempts to use multiple rates do not consume more bandwidth than they save.	_____ Multirate Support The following set of rules must be followed by all the stations to ensure coexistence and interoperability on	

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					<p>The only mechanisms for choosing a particular transmission rate that have been discussed thus far have all been heuristic, depending on learning that a station is no longer capable of communicating at other than the basic rate(s) by failing to receive acknowledgments when communicating at higher rates. The only mechanism to learn that communication at a higher rate is possible, is to attempt to communicate at that higher rate.</p> <p>Both of these methods lead to contradictory requirements to increase throughput (which is the real aim of using multiple rates). First, assuming that communication at a higher rate has been previously established, when that high rate communication fails, several retransmissions will take place, consuming a great deal of the available bandwidth of the BSS. Only after a number of retransmissions, will an attempt be made at a basic rate. Assuming that the basic rate transmission is successful, the bandwidth gain for this frame is negative. Assuming max length frames (the most efficient usage of multiple rates), the time to transmit this frame after N transmissions at the higher rate will be approximately $(0.6*N + 1)$ times the time to transmit at the basic rate.</p> <p>Similarly, trying to establish communication at the higher rate (and failing) will consume the same amount of time $(0.6*N + 1)$ times the time to transmit at the basic rate).</p> <p>As can easily be seen, with $N > 1$ the time consumed to learn that a frame can not be transmitted at the higher rate more than doubles the time required to transmit the frame at the basic rate.</p> <p>The egregious offender here is not the station that has been in previous communication at the higher rate (although its waste of bandwidth is indeed offensive), but the many stations that have only been communicating at</p>	<p>Multirate Capable PHYs:</p> <p>All Control Frames are transmitted at the aBSS_Basic_Rate_Set (which as specified before belongs to the ESS_BASIC_RATE) so they will be understood by all the stations in the ESS.</p> <p>All Multicast and Broadcast Frames are transmitted at the aBSS_Basic_Rate_Set, regardless of their type.</p> <p>Unicast Data and/or Management Frames are sent on any available transmit rate. The algorithm for selecting this rate is implementation dependent and is beyond the scope of this standard.</p>	
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					the basic rate and desire to communicate at the higher rate. Unless an unambiguous mechanism is described that will prevent the described behavior, the throughput of a multirate BSS will be significantly less than that of a basic rate only BSS.		
	9.6 A.4.4	db	T	Y	w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.	The following set of rules shall must be followed by all the stations to ensure coexistence and interoperability on Multirate Capable PHYs. All Control Frames are transmitted at the aBSS_Basic_Rate_Set (which as specified before belongs to the ESS_BASIC_RATE) so they shall will be understood by all the stations in the ESS.	
	9.6	jz	T	Y	Multirate is broken. We should adopt the text suggested in document 96/8 to fix it. Each PHY should define a Basic_Rate_Set at which all implementations must be able to send/receive. Individual APs can be configured for a primary rate that is different (higher or lower).	<<adopt changed text for this section from 96/8, and change the term "aBSS_Basic_Rate_Set" (which is not defined anywhere) to "either one of the rates defined in the PHY MIB's BSS_Basic_Rate set or the STA's Primary Rate".>>	
	9.7	ge	t		last three table items should not have a frames in sequence value	should be a note in the table entries that refers to text defining <CF-Sequence> just above table 20	
	9.7	WD	T	Y	It is currently ambiguous what happens when the PS-Poll is followed by an erroneous Data frame. Because the Data frame is not successfully received, in response to the PS-Poll, then the PS-Poll will be retransmitted according to the normal retransmission rules. However if the AP did send Data directly after the SIFS in response to the PS-Poll, but did not receive the Ack, then this might mean that the Data frame is to be retransmitted after a backoff. It should be noted that this is a special case for the	Modify entry 6 in table 19 into: PS-Poll - Data(dir)	

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					<p>AP, since it does not go through an access procedure to send the data, but instead generates it in direct response to the PS-Poll from the station, who did go through the access procedure. In general the retransmission responsibility is usually assigned to the station that did do the initial access procedure, and not by the responding station. this for instance also applies to the PCF.</p> <p>It is therefore suggested to prevent the ambiguity by deleting the Ack from the PS-Poll - Data-Ack sequence, so that only there will be a PS-Poll - Ack, or PS-Poll - Data sequence. this will clearly give the station the responsibility to regenerate the PS-Poll when the data transfer was not successfull.</p>		
	9.7	AS	T	y	<p>Delete the sequence: PS-Poll - [Data(dir) - ACK -] Data(dir) - ACK</p> <p>This sequence has a number of problems. The basis of which is that PS-Poll frames do not have sequence numbers. This means that the AP has no way of determining if a PS-Poll is a retransmission or a request for the next frame.</p>		
	9.7	TT	T	Y	<p>Under the current DCF rules it is not possible to correctly perform the PS-Poll - Data - ACK sequence.</p> <p>Since the PS-Poll is a directed frame that must have a response, there must be a timeout that the source STA must use before doing a DIFS and random backoff. Since the response is a data frame of unkown length, this timeout value is unknown.</p> <p>Currently the only other two timeouts are ACK timeout and CTS timeout, which end at the precise moment where the ACK and CTS frames were supposed to end.</p> <p>I believe it is preferable to eleminate this particular frame sequence rather than change the response timeout rules to wait until a response frame is fully received before you</p>	<p>Remove entry: PS-Poll-[Data(dir)-ACK]Data(dir)-ACK from Table 19 Frame Sequences.</p>	

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					<p>can tell if it is a true response to the frame you sent.</p> <p>It is also not mentioned in the standard, what happens when the DATA is not ACKed. Does the AP retry the data frame, or does it wait for another PS-Poll? If the ACK was transmitted but not received by the AP, then this PS-Poll would not happen until after the next Beacon frame was seen with the appropriate TIM set.</p> <p>I believe that a much cleaner solution is to have only the PS-Poll - ACK sequence and use the proposed solution described in my comments on clause 11.2.1.4 and 11.2.1.6.</p>		
	9.7	db	T	Y	<p>w/o the requested change the Draft is technically incorrect - since approved "standard" language was not used the draft does not corectly convey operational requirements.</p>	<p>Where "DATA*" mayean be any of the DATA sub-types, "DATA/END*" mayean be any of the DATA or CF-END sub-types, and "*CF-ACK" mayean be DATA+CF-ACK or CF-ACK(no data).</p>	
	9.7	jz	t	Y	<p>We should add a clarification that only fragments of the <i>same MSDU</i> may be transmitted with a SIFS between them. The current text implies that, under some circumstances, <i>Data/Managent</i> may be sent back-to-back.</p>		
	9.7	TT	T	Y	<p>Under the current DCF rules it is not possible to correctly perform the PS-Poll - Data - ACK sequence.</p> <p>Since the PS-Poll is a directed frame that must have a response, there must be a timeout that the source STA must use before doing a DIFS and random backoff. Since the response is a data frame of unkown length, this timeout value is unknown.</p> <p>Currently the only other two timeouts are ACK timeout and CTS timeout, which end at the precise moment where the ACK and CTS frames were supposed to end.</p>	<p>Remove entry: PS-Poll-[Data(dir)-ACK]Data(dir)-ACK from Table 19 Frame Sequences.</p>	

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					<p>I believe it is preferable to eliminate this particular frame sequence rather than change the response timeout rules to wait until a response frame is fully received before you can tell if it is a true response to the frame you sent.</p> <p>It is also not mentioned in the standard, what happens when the DATA is not ACKed. Does the AP retry the data frame, or does it wait for another PS-Poll? If the ACK was transmitted but not received by the AP, then this PS-Poll would not happen until after the next Beacon frame was seen with the appropriate TIM set.</p> <p>I believe that a much cleaner solution is to have only the PS-Poll - ACK sequence and use the proposed solution described in my comments on clause 11.2.1.4 and 11.2.1.6.</p>		
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