

# Silent Start

For 10/25/50G Bidi PHYs

# Silent Start Requirements

- ▶ Not required in OLT PHYs
- ▶ In ONUs
  - ▶ Higher management function
  - ▶ No transmission allowed until a good received signal is seen
  - ▶ Should not “flicker” (ie., transmission should not go in and out due to a marginal received signal)

# Potential control keys from PMA/PCS

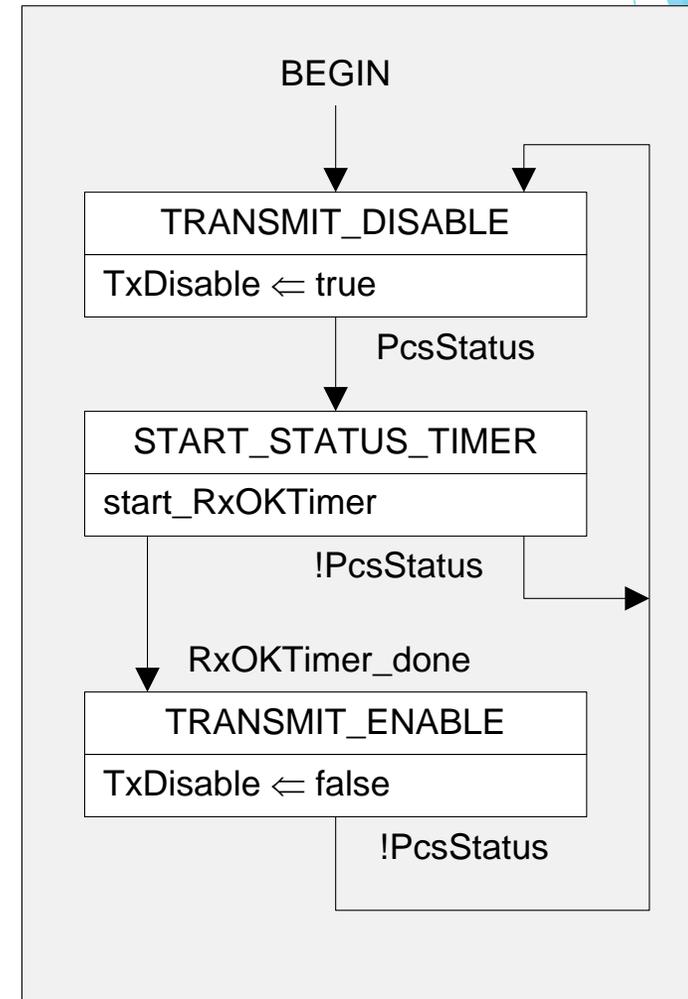
- ▶ BASE-R and MultiGBASE-T receive link status (CI 45.2.3.15.1)
  - ▶ Indicates whether the PCS is in a fully operational state. It is only true if block\_lock is true and hi\_ber is false.
  - ▶ Reflected in MDIO register 3.32.12. A latch low view of this status is reflected in MDIO register 3.1.2 and a latch high of the inverse of this status, Receive fault, is reflected in MDIO register 3.8.10.
- ▶ BASE-R and MultiGBASE-T PCS high BER (CI 45.2.3.15.4).
  - ▶ Indicates the state of the hi\_ber variable ( $> 10 \times 10^{-4}$ )
  - ▶ Reflected in MDIO register 3.32.1.
- ▶ BASE-R and MultiGBASE-T PCS block lock (CI 45.2.3.15.5)
  - ▶ Indicates when receiver acquires block delineation.
  - ▶ Reflected in MDIO register 3.32.0.
- ▶ PMD\_global\_transmit\_disable (CI 45.2.1.8)
  - ▶ Optional in most PMDs
  - ▶ Disables transmission.

# Proposal

- ▶ Describe function in Introduction clause (157)
- ▶ Use PCS\_status as defined in 49.2.14.1 to control Silent Start feature
  - ▶ If PCS-status indicates the PCS receive path is up and running normally for some per-determined time period (1 sec ?) the upstream PMD may transmit.
  - ▶ If PCS\_status indicates there is a PCS receive path fault the PMD transmission shall be disabled.
- ▶ PMD\_global\_transmit\_disable as defined in CI 45.2.1.8 (register 1.9.0, optional in 10/25/50GBASE-R PHYs)
  - ▶ make mandatory in 10/25/50GBASE-BxR-U PHYs

# Variables & State Diagram

- ▶ TxDisable - Boolean variable when set to true PHY transmission is allowed, when set to false PHY transmission is disallowed. Maps to CI 45.2.1.8 (register 1.9.0) PMD\_global\_transmit\_disable
- ▶ PcsStatus - Boolean variable when set to true indicates the PCS is in a fully operational state. When set to false indicates the PCS is in a non-operational state. Maps to CI 45.2.3.15.1 (register 3.32.12) BASE-R and MultiGBASE-T receive link status
- ▶ RxOKTmr - A timer used to ensure the PHY transmission enable includes hysteresis. The RxOKTmr is set to {1 second} on start.



# How to include Silent Start requirement

- ▶ How would the TF prefer like to include the silent start requirement in the draft?
- ▶ Silent Start as described here is really a Management requirement
  - ▶ Read PHY Rx Status
    - ▶ All PCSs have a requirement to include this
  - ▶ Set PHY Tx Control accordingly
    - ▶ Mandating Tx Control point is easy
  - ▶ How to mandate the overall feature may be delicate
- ▶ Option 1 - Duplicate the feature description (~1.5 pg) in each PMD clause including text, variable definitions & SD
- ▶ Option 2
  - ▶ Describe the feature fully in CI 157 (Intro) including variable definitions and State Diagrams (note typically Intros don't include requirements)
  - ▶ Create a requirement statement ("shall") in the PMD clause (158, 159 & 160) to mandate the Silent Start feature for PHYs including PMDs as described in "this clause"
    - ▶ Ex: "Devices including a 10GBASE-BxR-U PMD shall include the Silent Start feature described in 157.x.y." & "10GBASE-RxR-U PMDs shall include the TxDisable variable described in 157.x.y."
  - ▶ Create PICS in PMD clause
- ▶ Other Options?

# Thank You