

White Rabbit

Ethernet-based solution for sub-ns synchronization and deterministic, reliable data delivery

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on behalf of White Rabbit Team

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Institute of Electronic Systems @ Warsaw University of Technology

15 July 2013
IEEE Plenary Meeting Genève



Outline

- 1 Introduction
- 2 CERN Control & Timing
- 3 WR Network
- 4 Time Distribution
 - Timing demo
- 5 Data Distribution
 - Redundancy demo
- 6 WR @ CERN
- 7 Summary

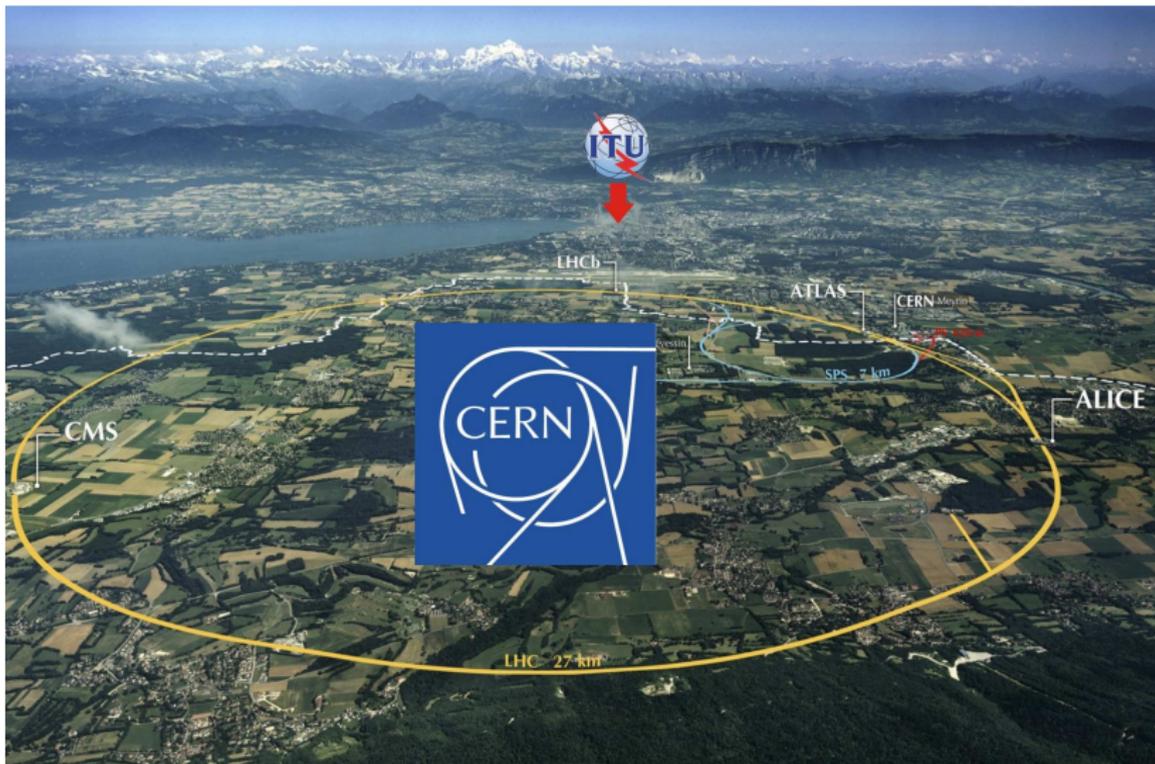


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CERN



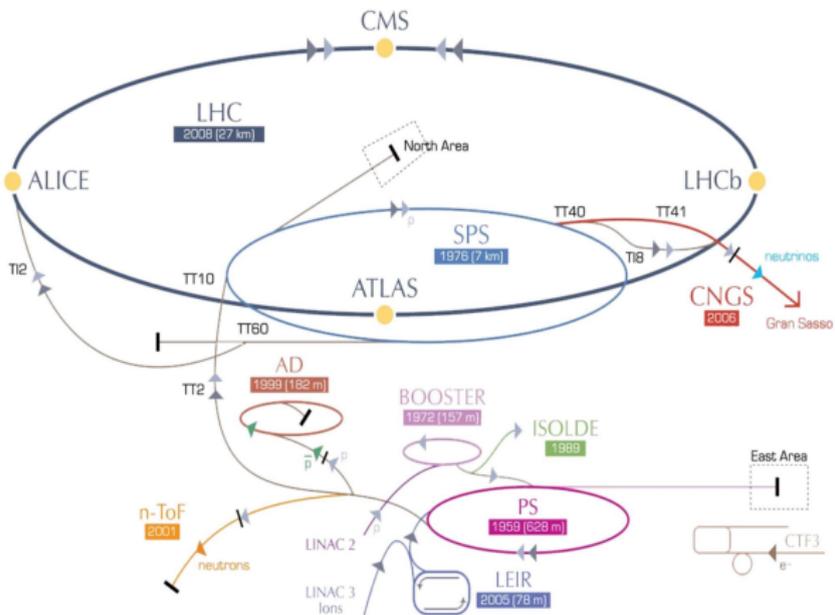
CERN



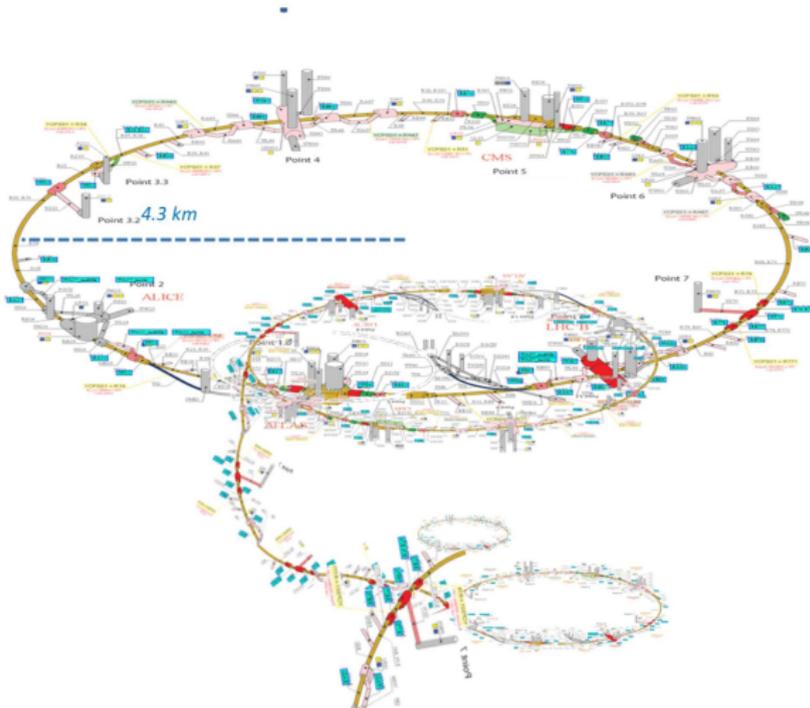
CERN



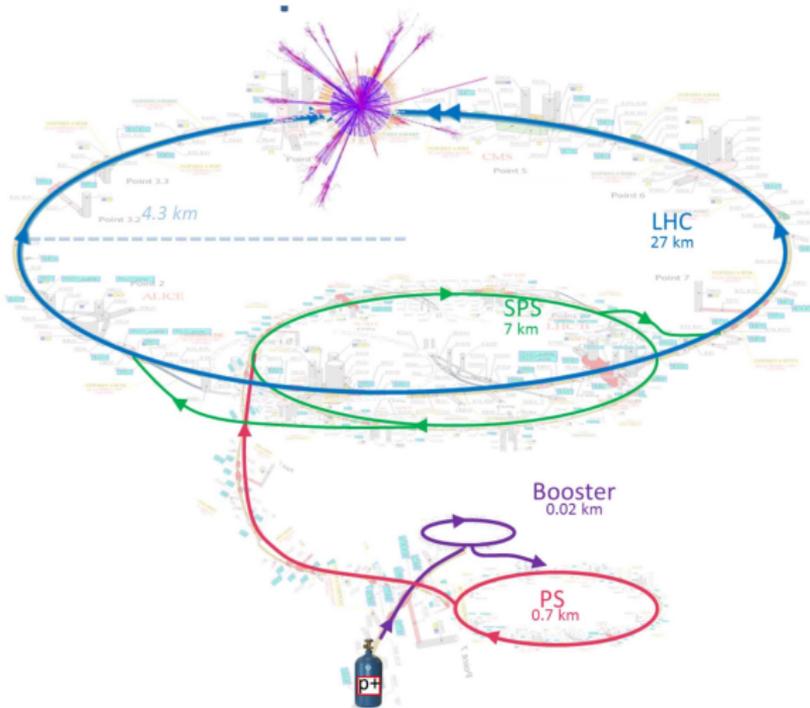
CERN Accelerator Complex



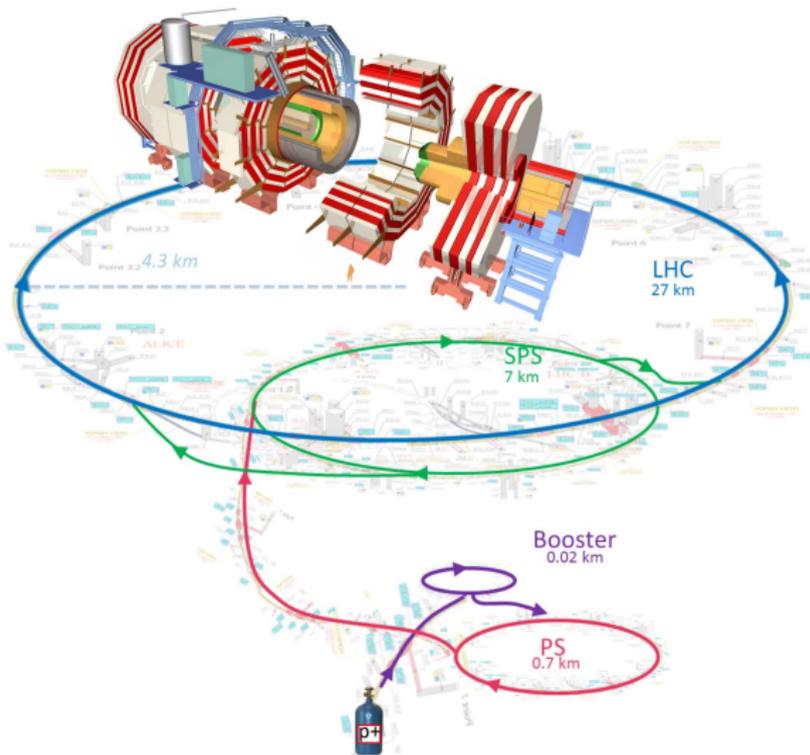
CERN Accelerator Complex



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CERN Accelerator Complex



Beams – Controls – Hardware & Timing



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ADC, DAC, TDC, Fine Delay Generator, ...



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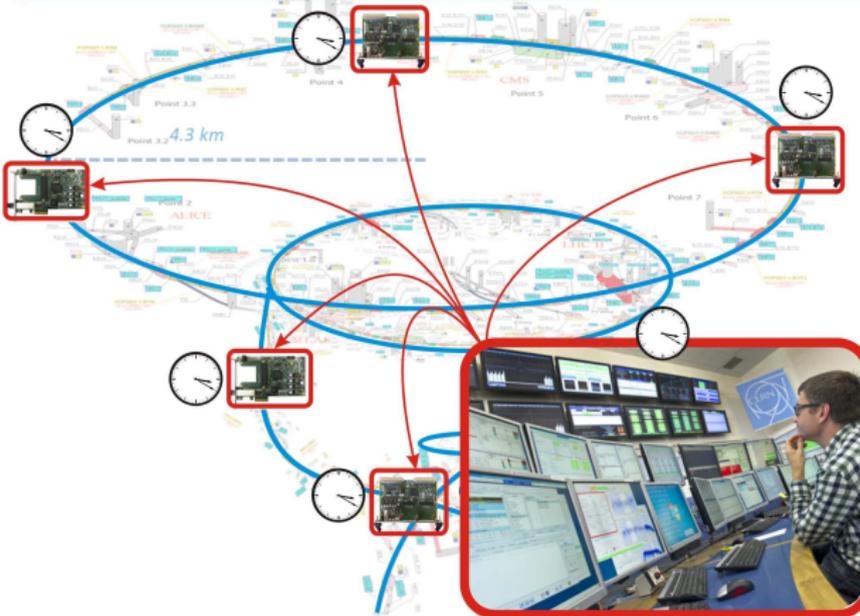
Beams – Controls – Hardware & Timing

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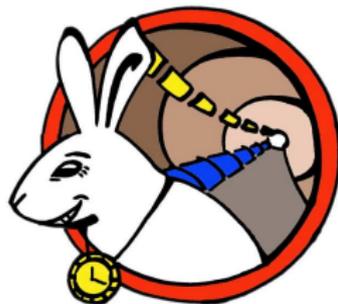
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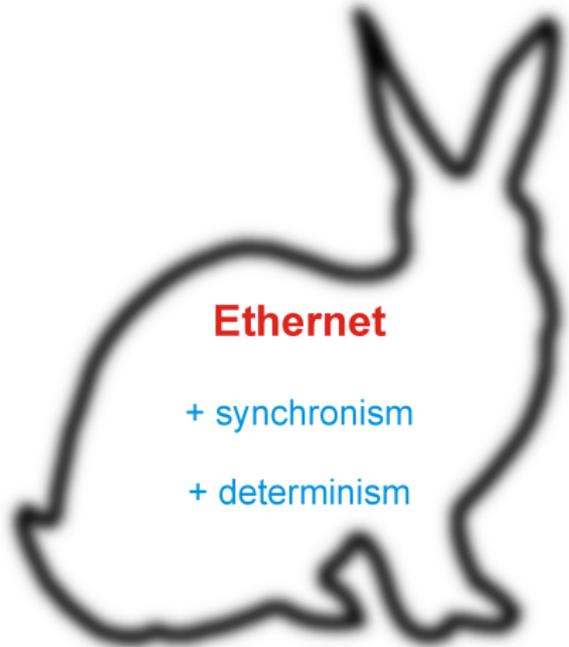
What is White Rabbit?

- Renovation of accelerator's control and timing
- Based on well-known technologies
- Open Hardware and Open Software
- International collaboration



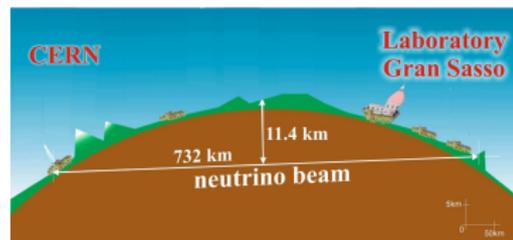
White Rabbit features

- standard-compatible
- sub-ns accuracy
- tens-ps precision
- upper-bound low-latency
- white-box simulation & analysis
- high reliability
- tens-km span
- thousands-nodes systems



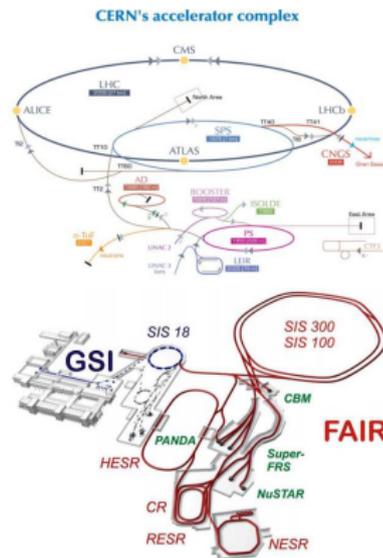
White Rabbit applications

- Deployed for time distribution:
 - CERN Neutrinos to Gran Sasso



White Rabbit applications

- Deployed for time distribution:
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- Future applications:
 - CERN and GSI



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 - HiSCORE: Gamma&Cosmic-Ray experiment (Tunka, Siberia)

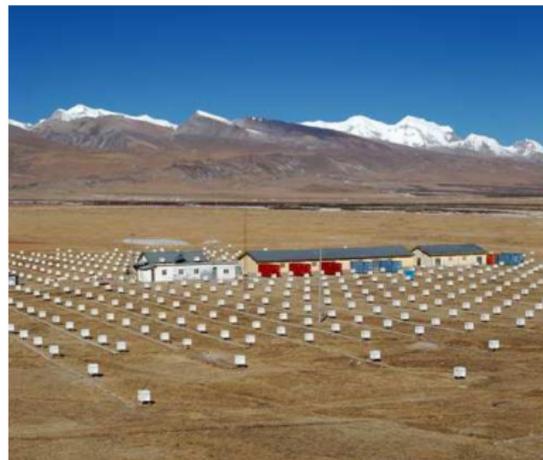


- > Institute for Nuclear Research of the Russian Academy of Sciences
- > Moscow State University
- > Irkutsk State University



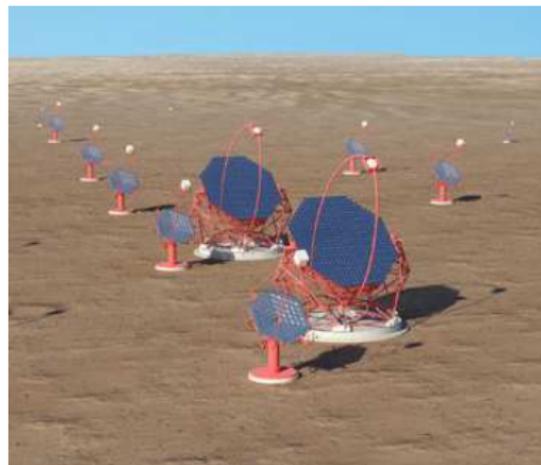
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 - The Large High Altitude Air Shower Observatory (China)



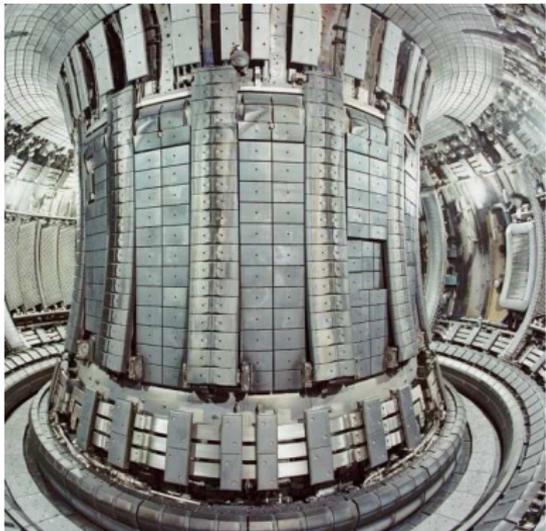
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- Potential applications:
 - Cherenkov Telescope Array



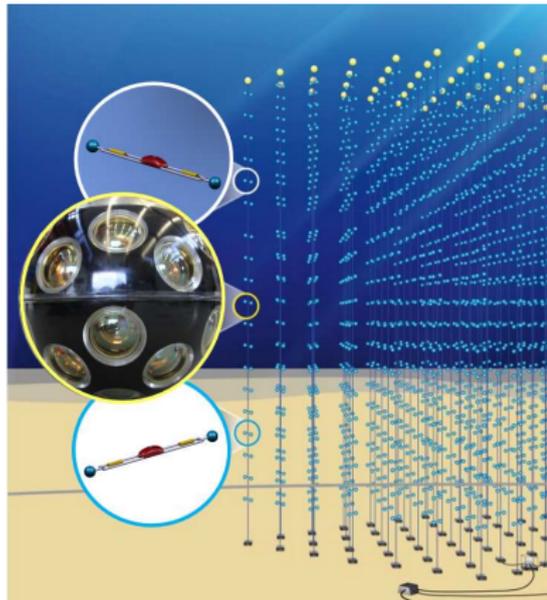
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 - International Thermonuclear Experimental Reactor (ITER)



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- Potential applications:
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 - International Thermonuclear Experimental Reactor (ITER)
 - European deep-sea research infrastructure (KM3NET)



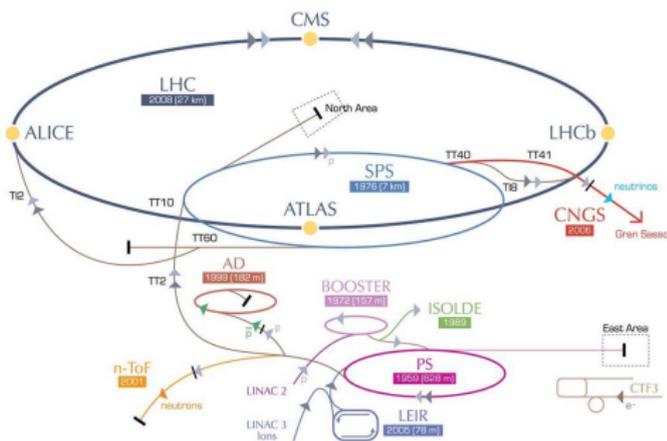
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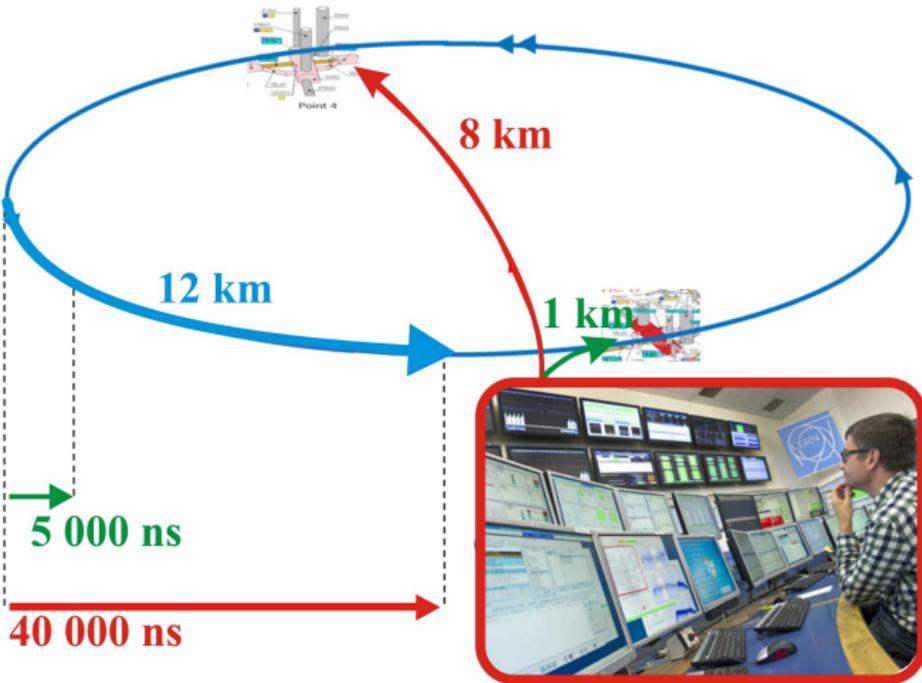


CERN Control and Timing System

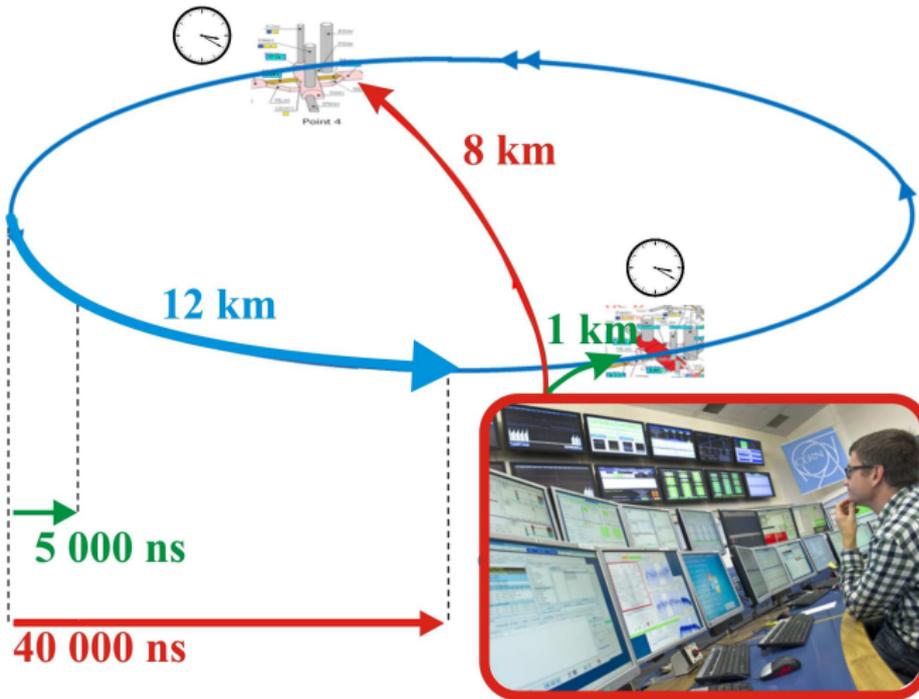
- 6 accelerators including LHC: 27km
- A huge real-time distributed system
- Thousands of devices



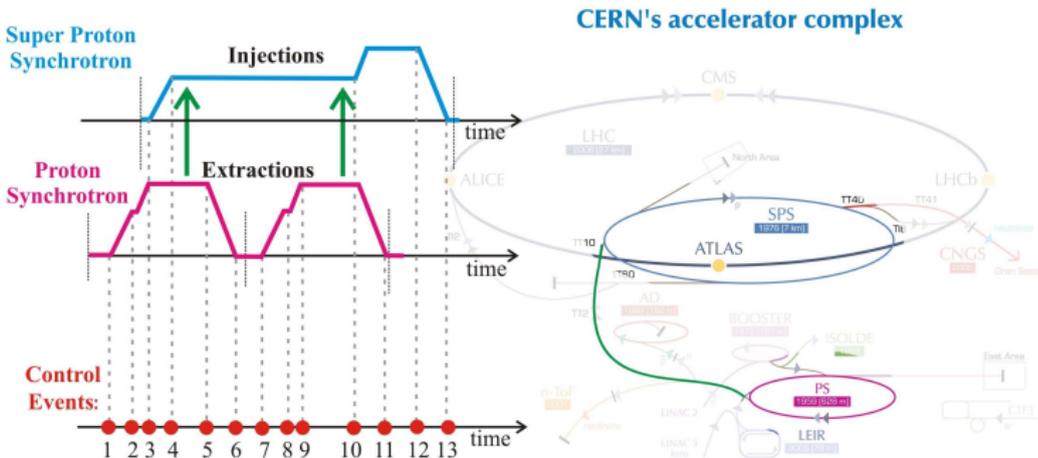
Controlling accelerators



Controlling accelerators



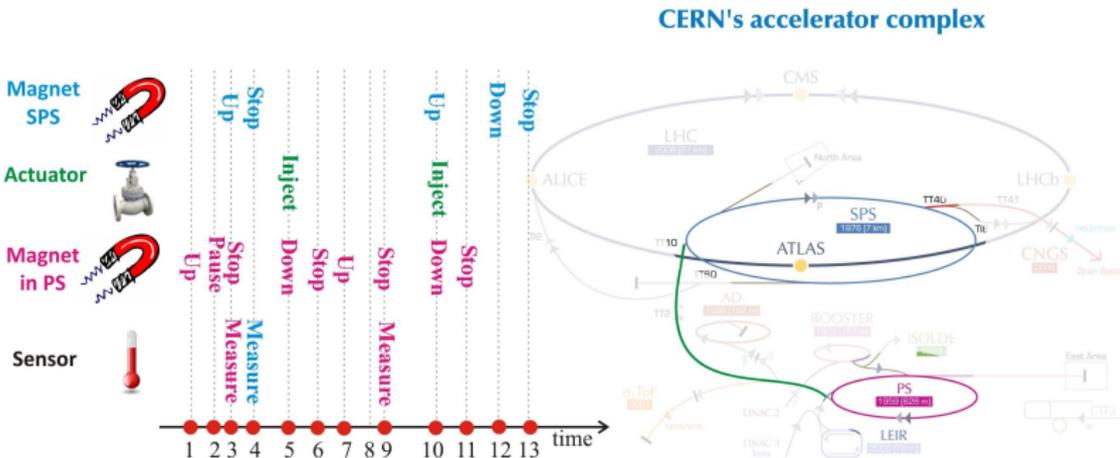
CERN Control System – event distribution (1)



- **Events** – messages which trigger actions
- Each event is identified by an **ID**



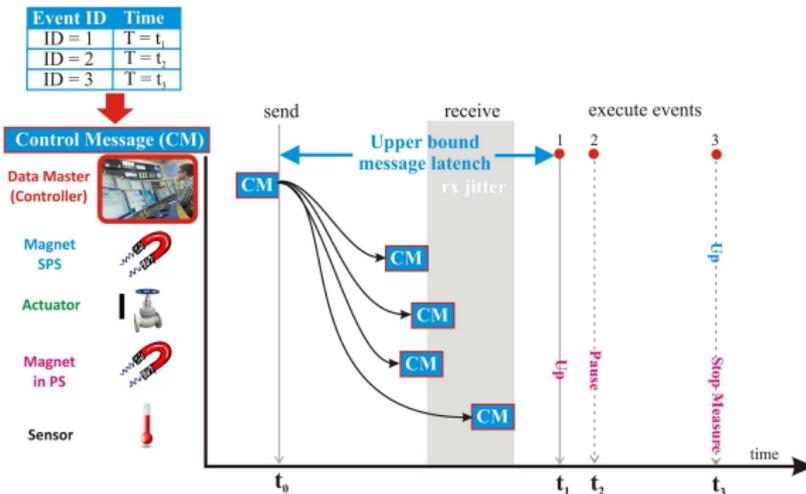
CERN Control System – event distribution (2)



- Devices are subscribed to events
- Each device "knows" what to do on a particular event



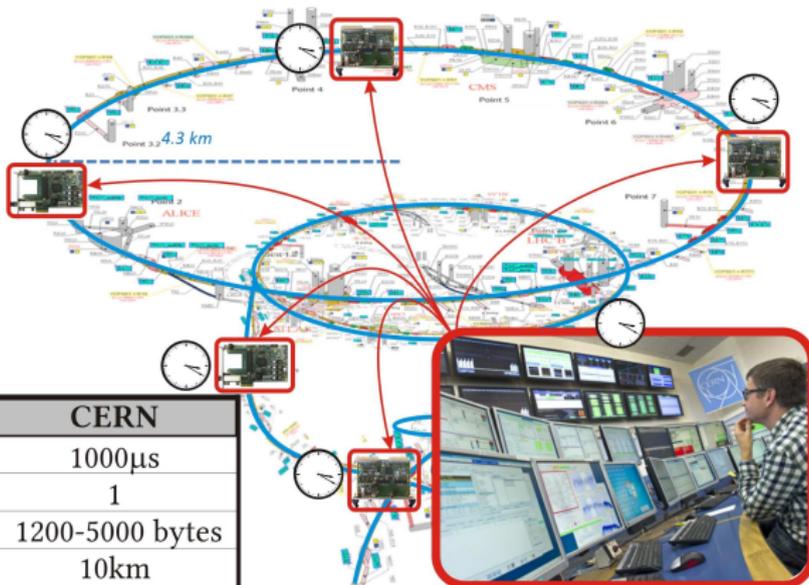
CERN Control System – event distribution (3)



- Each event (ID) has a trigger time associated
- A set of events is sent as a single **Control Message (CM)**
- CM is broadcast to all the end devices (nodes)
- CM is sent in advance (**upper-bound message latency**)



CERN Control & Timing Network – requirements

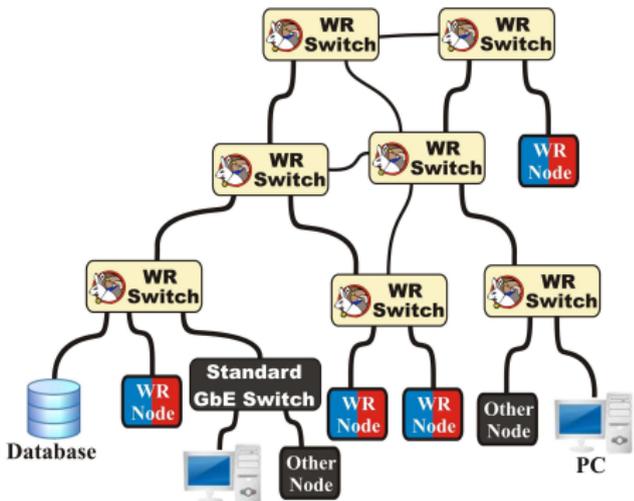


Requirement	CERN
Max latency	1000 μ s
CMs lost per year	1
CM size	1200-5000 bytes
Network span	10km
Accuracy	up to 1ns



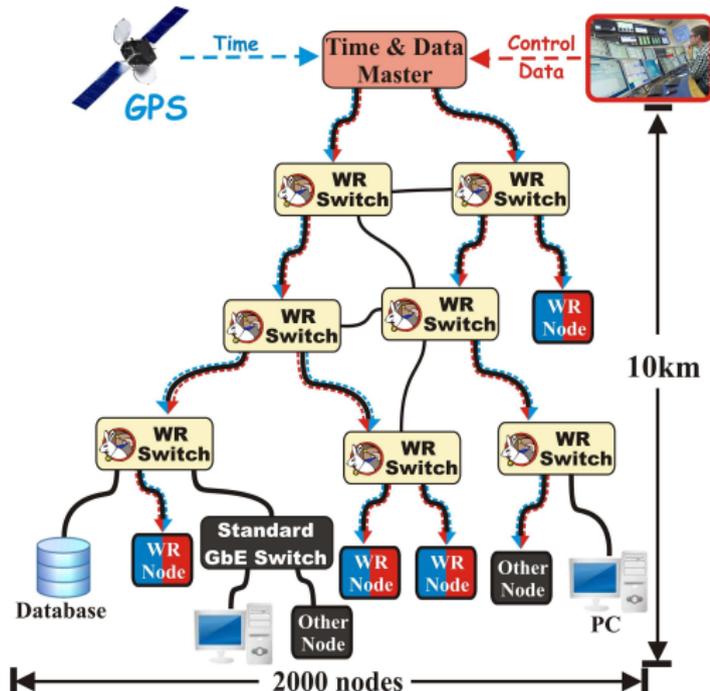
White Rabbit Network – Ethernet-based

- Standard Ethernet network
- Few thousands nodes
- Bandwidth: 1 Gbps
- WR Switch: 18 ports
- Non-WR Devices
- Ethernet features (VLAN) & protocols (SNMP)



White Rabbit Network – Ethernet-based

- High accuracy/precision synchronization
- Deterministic, reliable and low-latency Control Data delivery



White Rabbit Switch

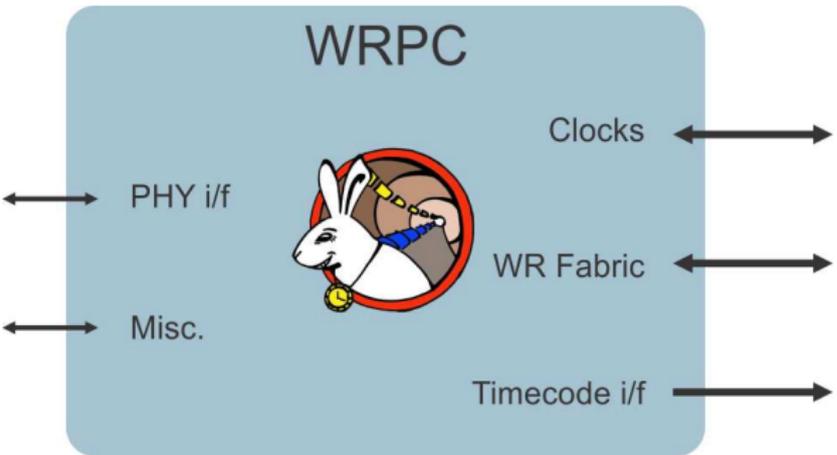


- Central element of WR network
- Original design optimized for timing, designed from scratch
- 18 ports
- 1000BASE-BX10 SFPs: up to 10 km, single-mode fiber
- Open design (H/W and S/W)



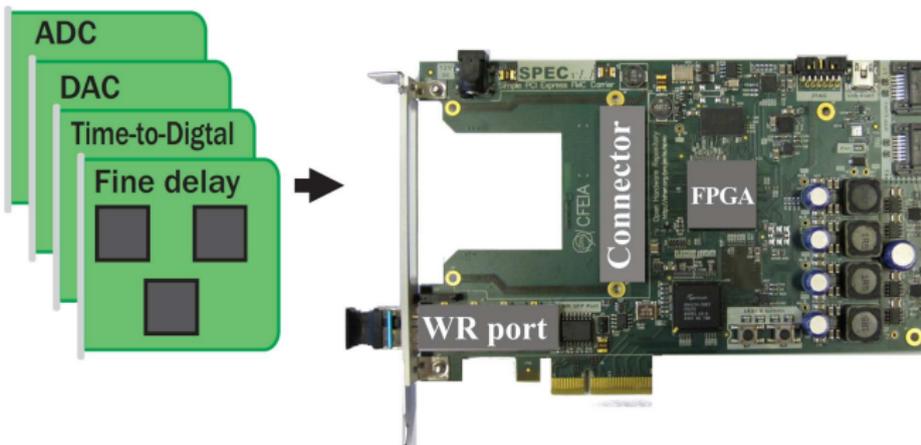
White Rabbit Node

- Ethernet MAC with White Rabbit
 - Open IP Core
 - Easily integrated into custom FPGA-based designs



White Rabbit Node

- Ethernet MAC with White Rabbit
 - Open IP Core
 - Easily integrated into custom FPGA-based designs
- WR Node: universal carrier board



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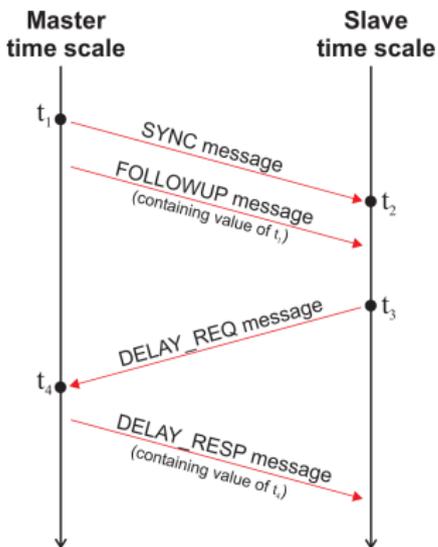


Time Distribution in White Rabbit Network

- Synchronization with **sub-ns** accuracy **tens-ps** precision
- Combination of
 - Precision Time Protocol (**IEEE1588**) synchronization
 - Layer 1 syntonization
 - Digital Dual-Mixer Time Difference (**DDMTD**) phase detection



Precision Time Protocol (IEEE1588)



- Simple calculations:

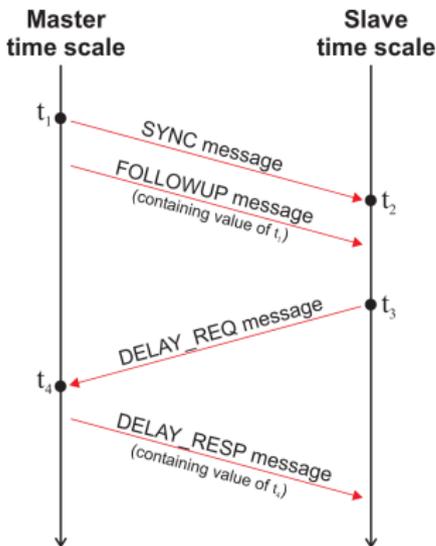
- link *delay*_{ms}: $\delta_{ms} = \frac{(t_4 - t_1) - (t_3 - t_2)}{2}$

- clock *offset*_{ms} = $t_2 - t_1 + \delta_{ms}$

- Assumes medium symmetry



Precision Time Protocol (IEEE1588)



- Simple calculations:

- link $delay_{ms}$: $\delta_{ms} = \frac{(t_4 - t_1) - (t_3 - t_2)}{2}$

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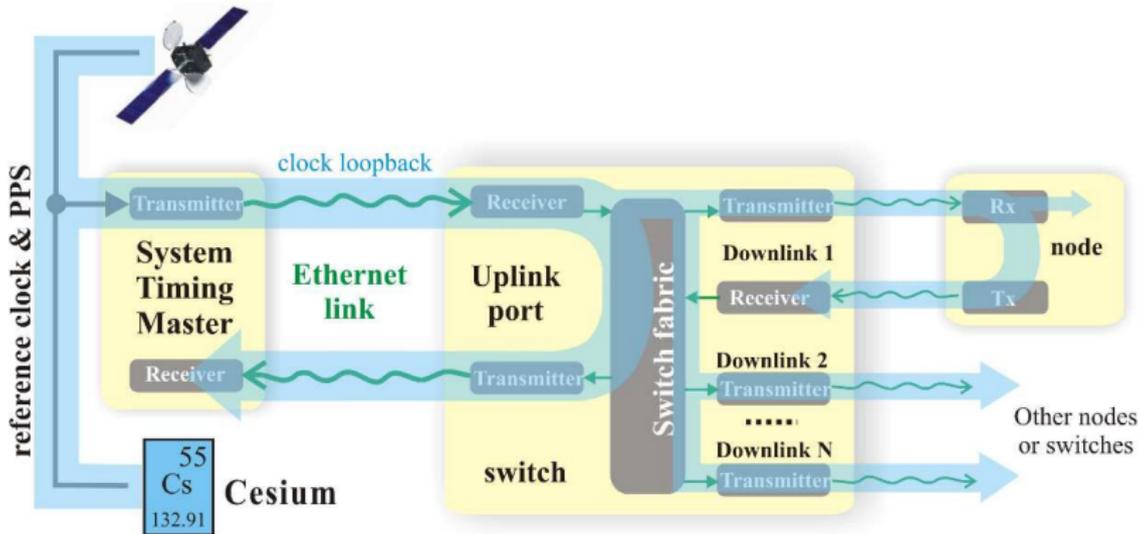
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- Disadvantages

- all nodes have free-running oscillators
- frequency drift compensation vs. message exchange traffic

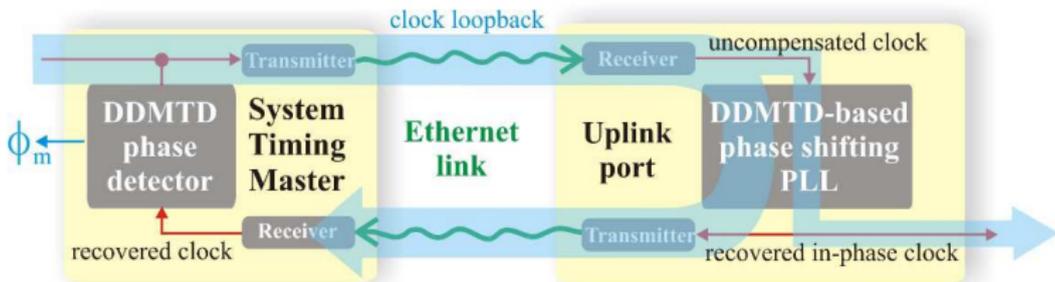


Layer 1 Syntonization

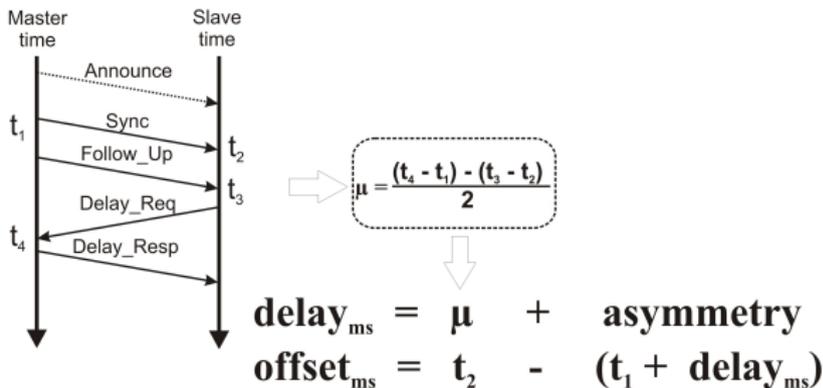


Phase Tracking (DDMTD)

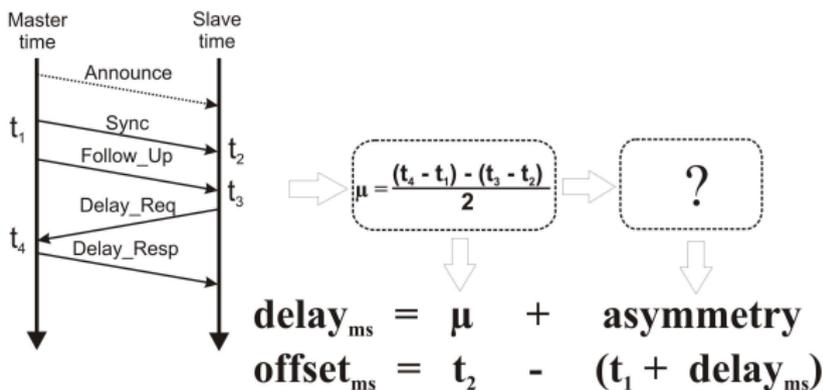
- Monitor phase of bounced-back clock
- Enhance PTP timestamps with phase measurement
- Phase-locked loop in the slave follows the phase changes



Link Delay Model



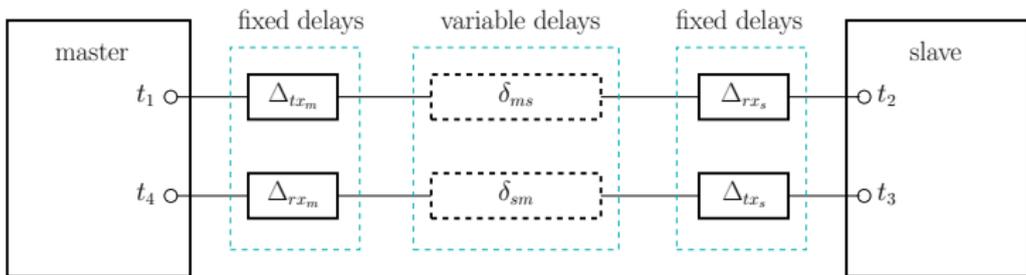
Link Delay Model



Link Delay Model

$$\text{delay}_{ms} = \Delta_{tx_m} + \delta_{ms} + \Delta_{rx_s}$$

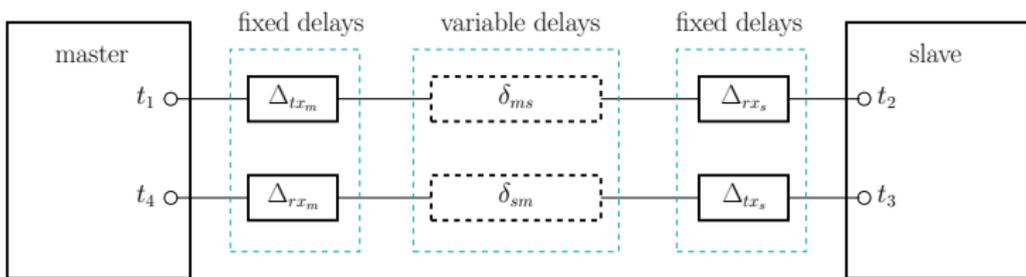
$$\text{delay}_{sm} = \Delta_{tx_s} + \delta_{sm} + \Delta_{rx_m}$$



Link Delay Model

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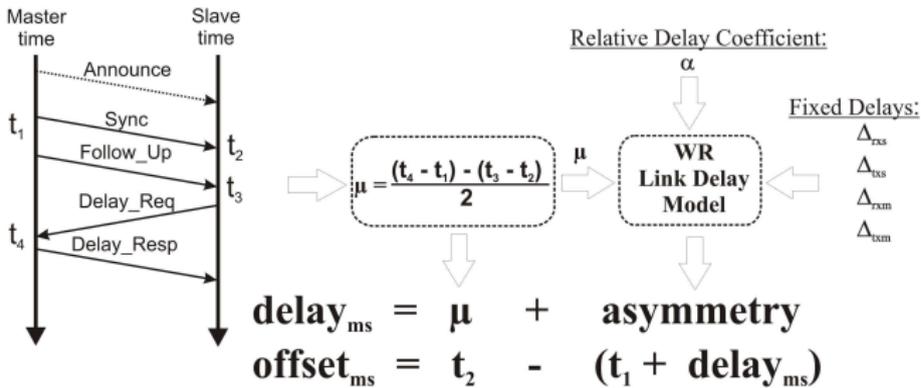


Relative Delay Coefficient (α)
for 1000base-X over a Single-mode
Optical Fibre

$$\delta_{ms} = (1 + \alpha) \delta_{sm}$$



Link Delay Model: fiber optic solution



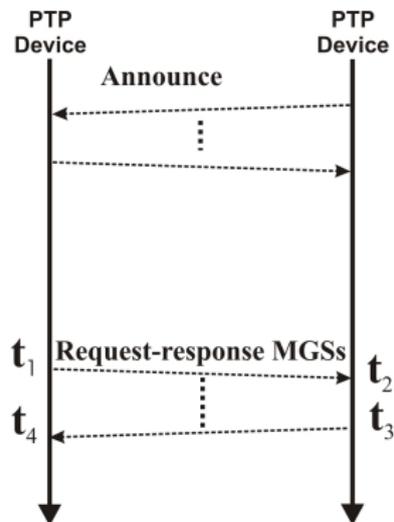
Solution for Ethernet over a Single-mode Optical Fiber

$$\text{asymmetry} = \Delta_{txm} + \Delta_{rxs} - \frac{\Delta - \alpha\mu + \alpha\Delta}{2 + \alpha}$$



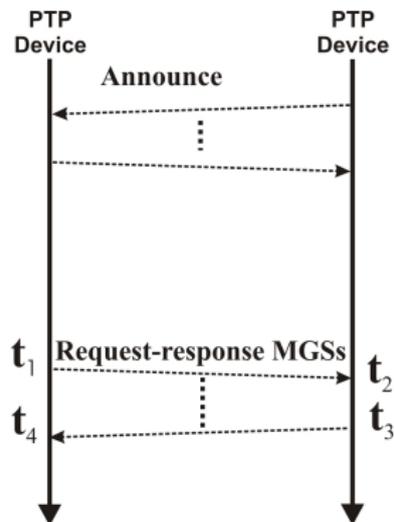
White Rabbit extension to PTP

- White Rabbit requires:
 - WR-specific states
 - Exchange of WR-specific information



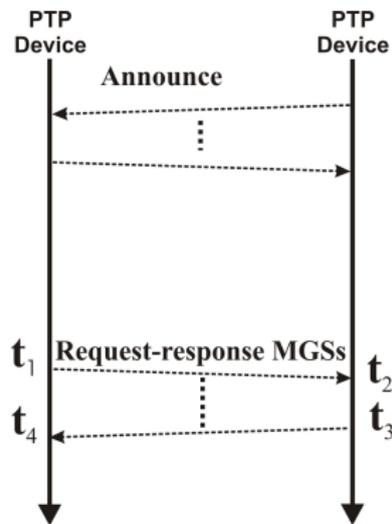
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- White Rabbit estimates link asymmetry



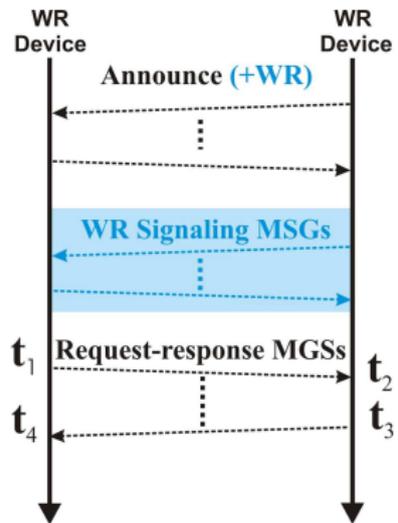
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White Rabbit extension to PTP

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 - WR-specific states
 - Exchange of WR-specific information
- White Rabbit estimates link asymmetry
- WR PTP
 - PTP extensions mechanisms
 - Enhanced precision t_1 , t_2 , t_3 , t_4
 - Correction for asymmetry
 - Interoperability with PTP gear

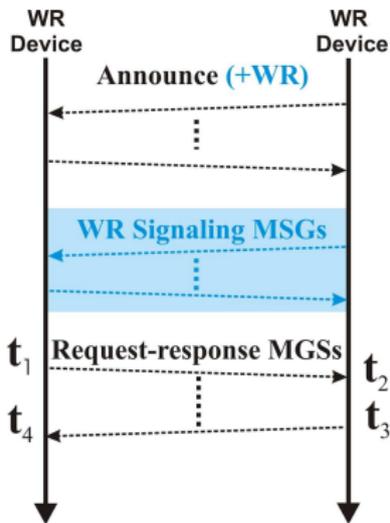


White Rabbit extension to PTP

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 - Correction for asymmetry
 - Interoperability with PTP gear

ISPCS Plug Fest

**WR: most accurate PTP implementation
in the world!**



WR Standardization under IEEE1588

- We want to standardize!



WR Standardization under IEEE 1588

- We want to standardize!
- Intention by p1588 SG expressed in PAR

IEEE Standard for a Precision Clock Synchronization Protocol for Networked Measurement and Control Systems

The protocol enhances support for synchronization to better than 1 nanosecond.

1. Overview

1.1 Scope

This standard defines a protocol enabling precise synchronization of clocks in measurement and control systems implemented with technologies such as network communication, local computing, and distributed objects. The protocol is applicable to systems communicating by local area networks supporting multicast messaging including, but not limited to, Ethernet. The protocol enables heterogeneous systems that include clocks of various inherent precision, resolution, and stability to synchronize to a grandmaster clock. The protocol supports system-wide synchronization accuracy in the sub-nanosecond range with isolated network and local clock computing resources. The default behavior of the protocol allows simple systems to be installed and operated without requiring the administrative attention of users. The standard includes mappings to User Datagram Protocol (UDP), Stream Protocol (SP), Domain, and a layer-2 Ethernet implementation. It includes formal mechanisms for message arbitration, higher sampling rates, correction for asymmetry, a clock type to reduce error accumulation in large topologies, and specifications on how to incorporate the resulting additional data into the synchronization protocol. The standard permits synchronization accuracy better than 1 ns. The protocol has features to address applications where redundancy and security are a requirement. The standard defines conference and management capability. There is provision to support secure as well as insecure messaging. The standard includes an annex on recommended practices. Annexes defining communication-media-specific implementation details for additional network implementations are expected to be provided in future versions of this standard.

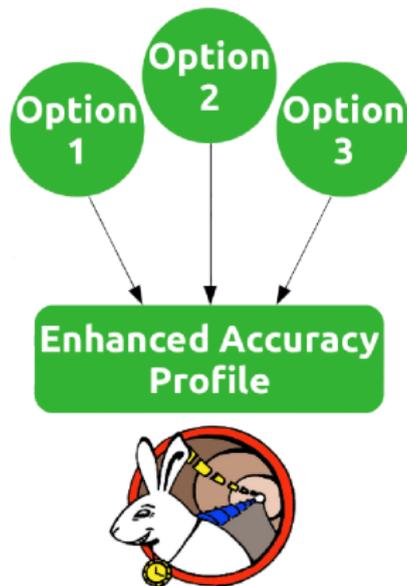
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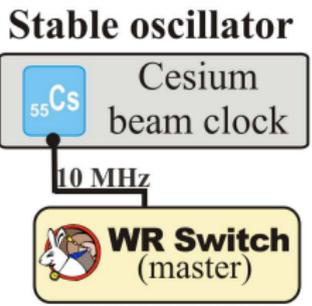


WR Standardization under IEEE1588

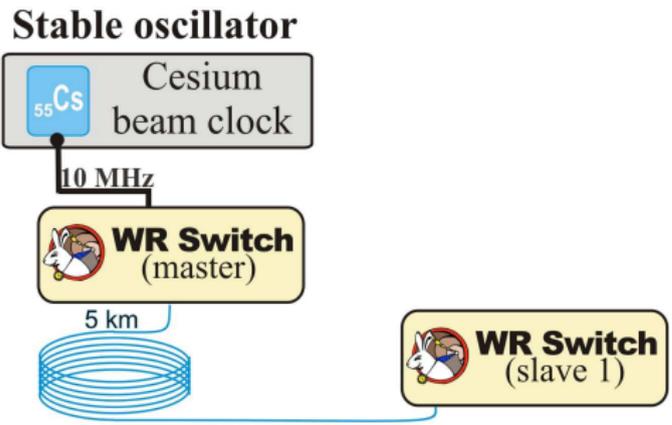
- We want to standardize!
- Intention by p1588 SG expressed in PAR
- Enhanced Accuracy Options / Profile



WR synchronization performance

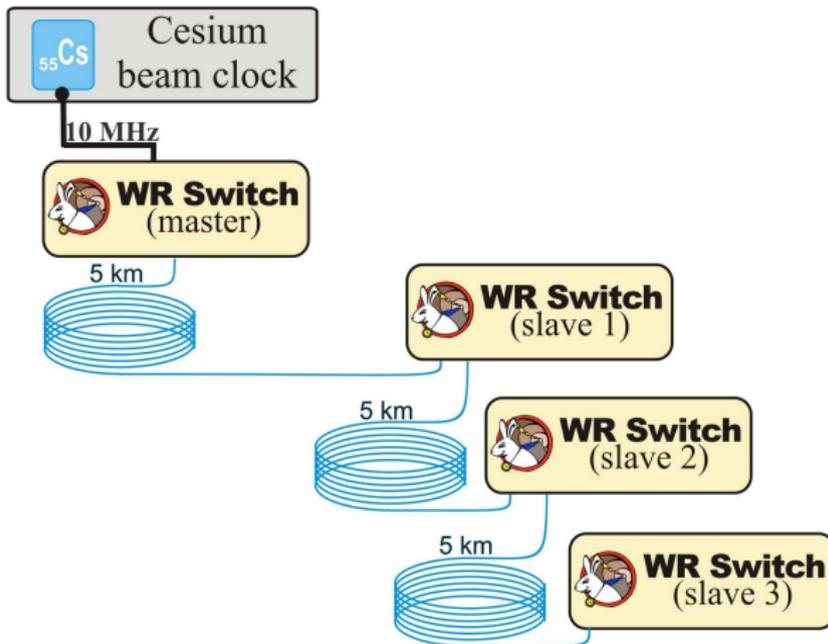


WR synchronization performance

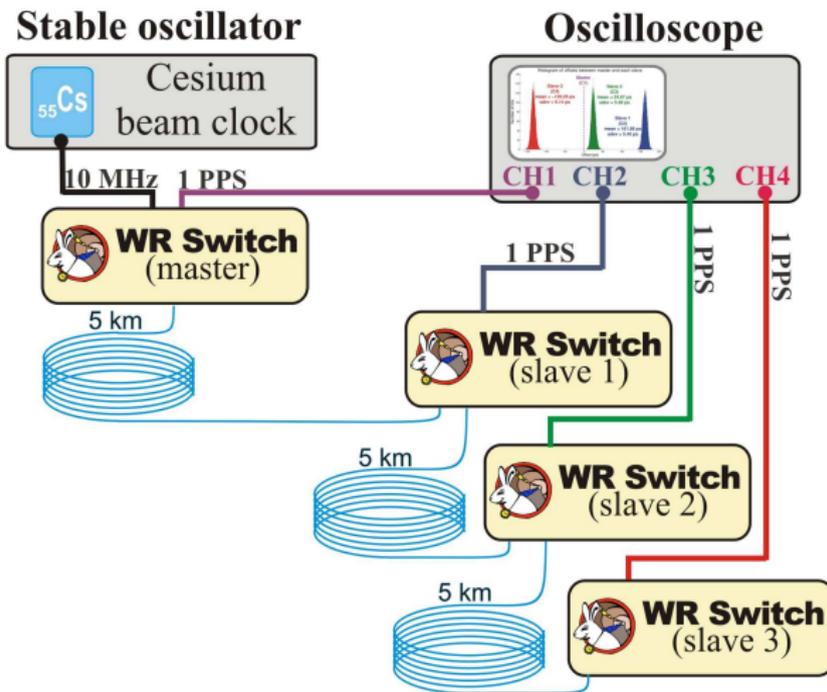


WR synchronization performance

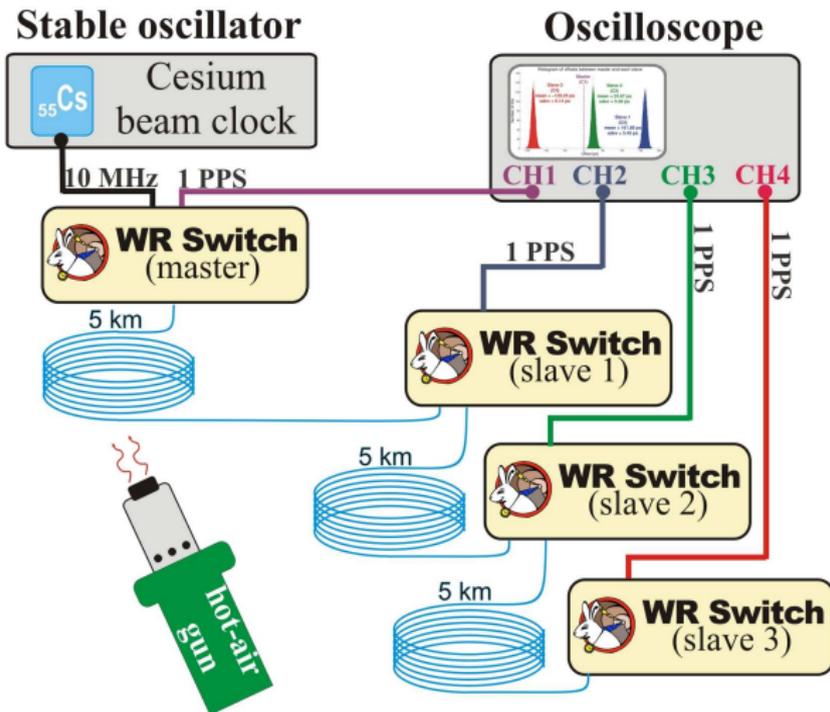
Stable oscillator



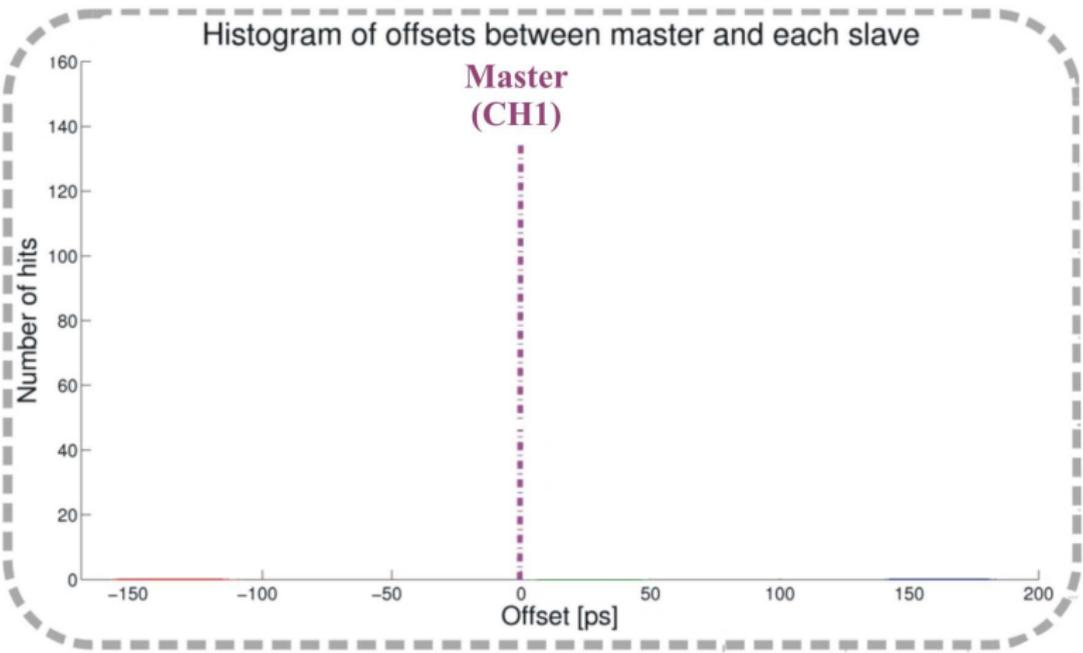
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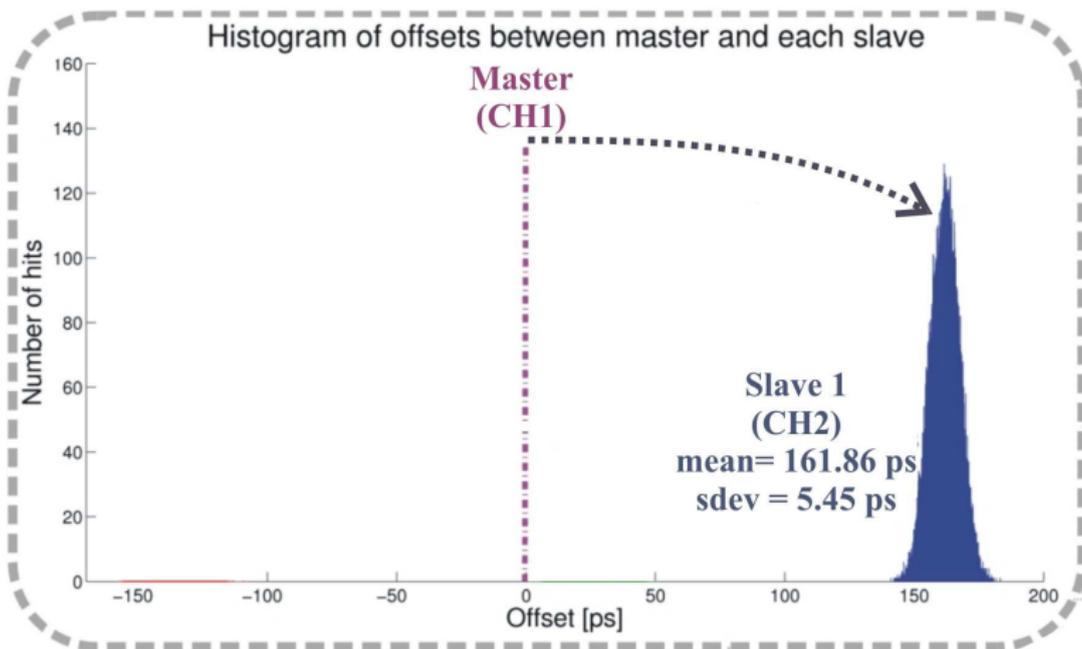
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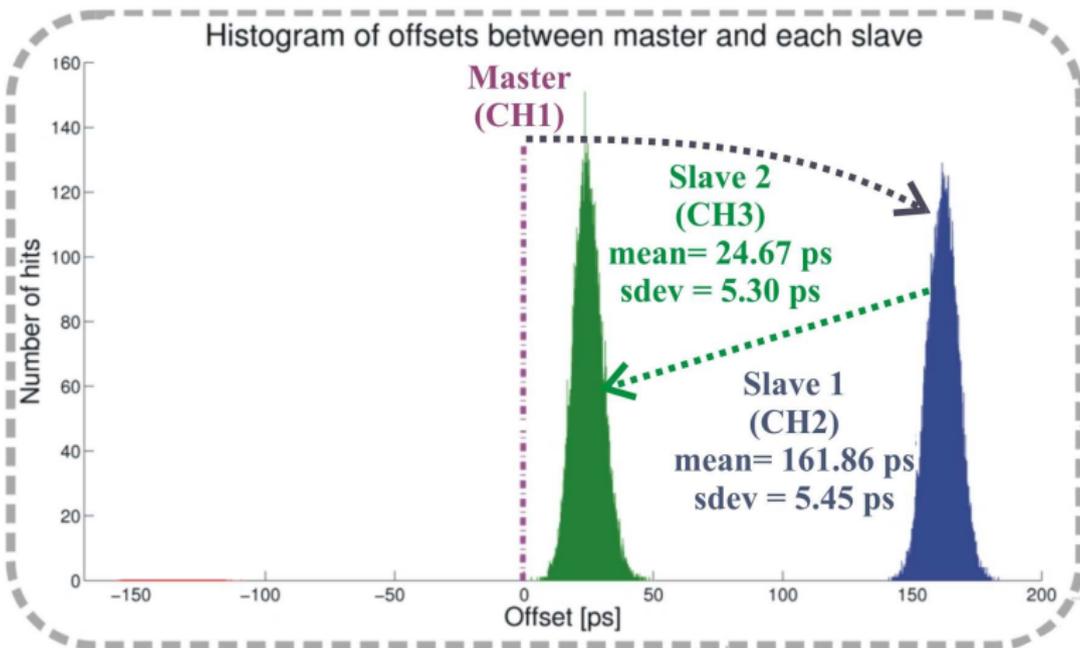
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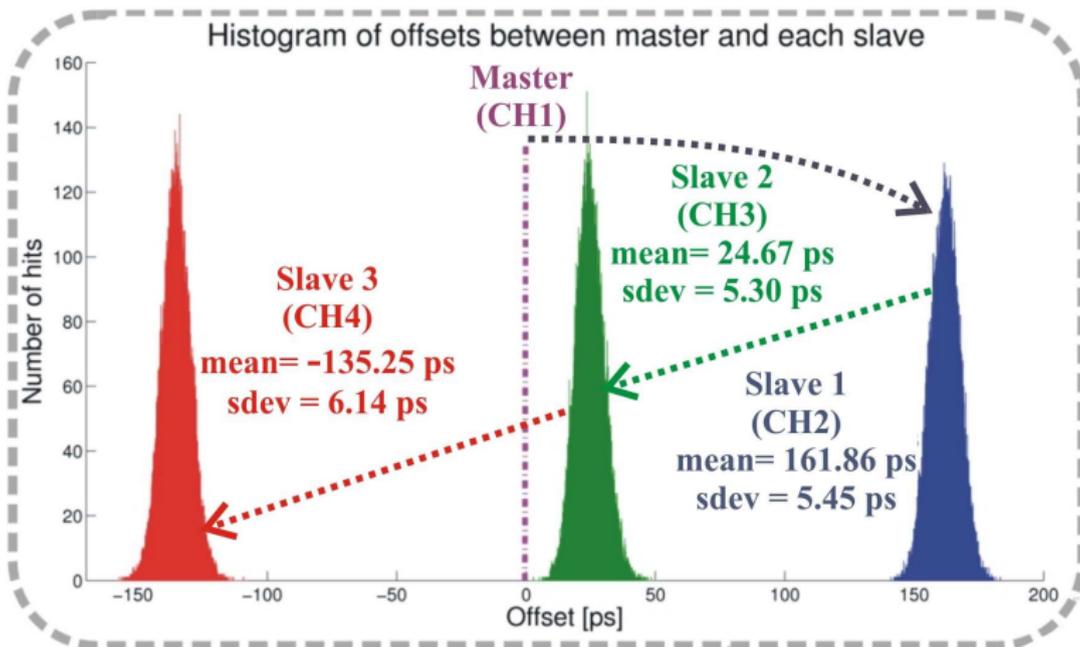
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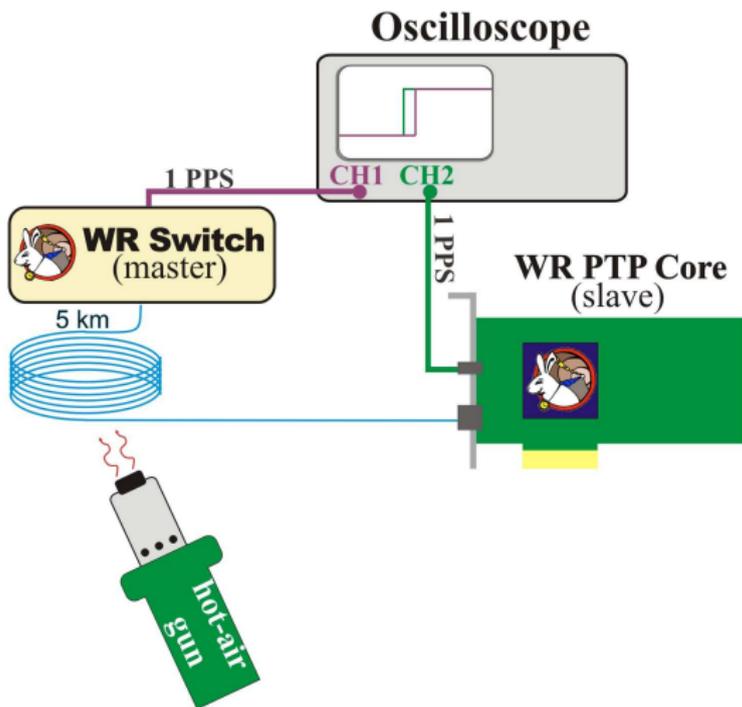
WR synchronization performance



WR synchronization performance



Timing demo

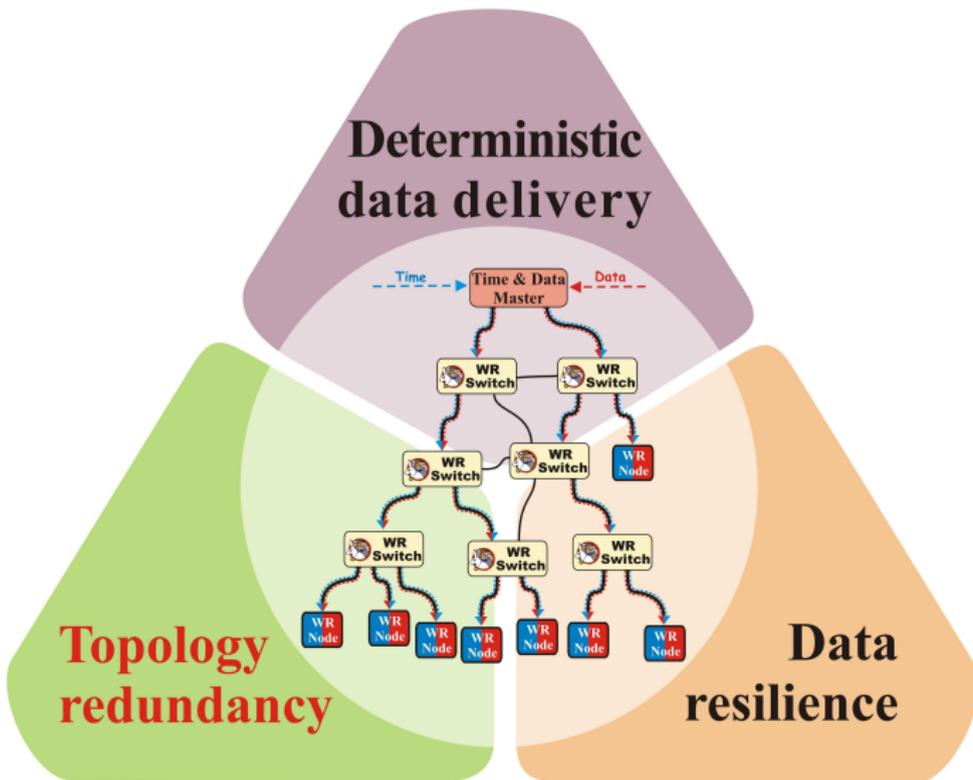


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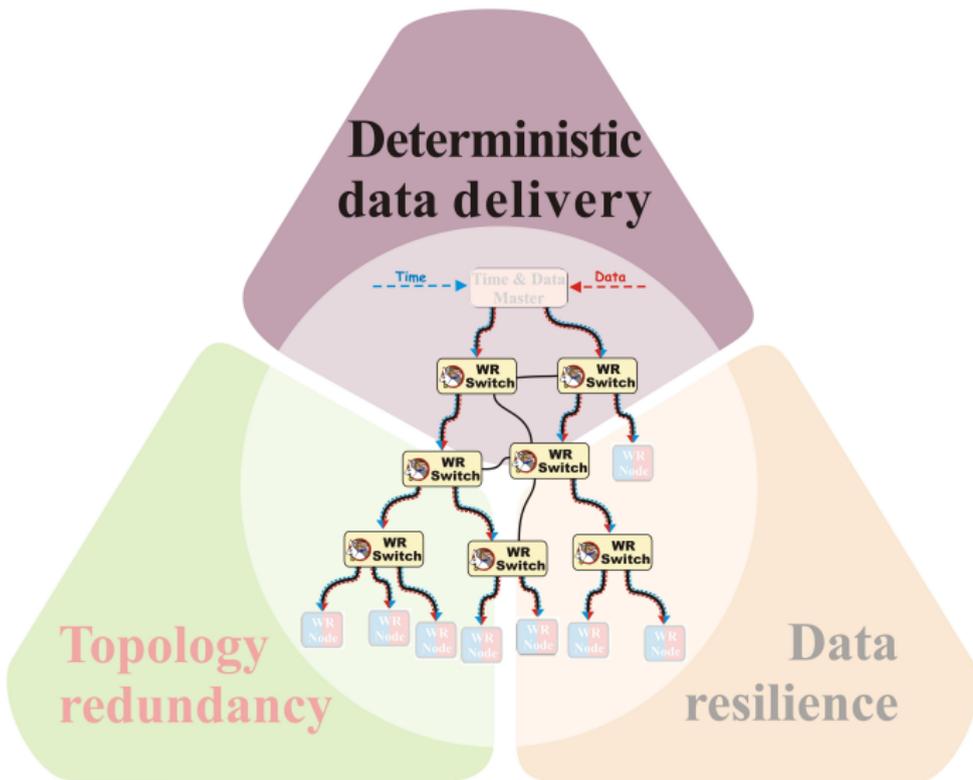
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Data Distribution in a White Rabbit Network

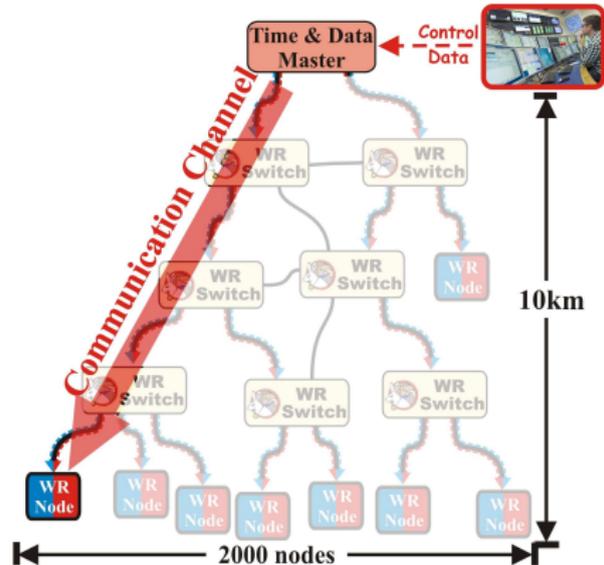


Determinism and Latency (Switch)



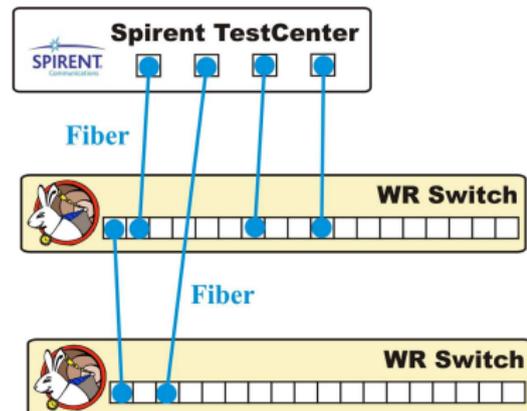
High Priority

- Types of data distinguished by 802.1Q tag:
 - **High Priority** (strict priority)
 - Standard Data (Best Effort)
- **High Priority** characteristics:
 - Broadcast/Multicast
 - Low-latency
 - Deterministic
 - Uni-directional
 - Re-transmission excluded
- Failure of **High Priority**:
 - Medium imperfection
 - Network element failure
 - Exceeded latency

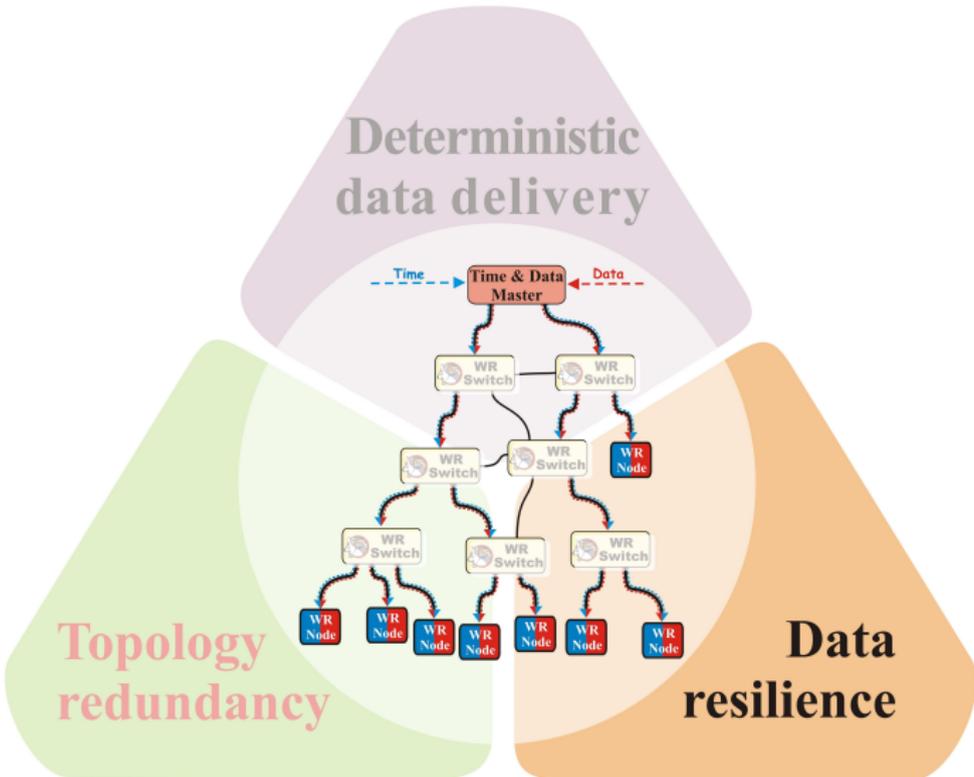


Determinism and Latency

- Deterministic Latency of High Priority
 - **By design: < 10us**
(single source of High Priority)
 - All size of frames
 - All rates
 - Regardless of Best Effort traffic
- Preliminary tests: $\approx 3\mu\text{s}$



Data Resilience (Node)



Topology redundancy

Data resilience



Data Redundancy

- **Forward Error Correction (FEC)** – transparent layer:
 - One message encoded into N Ethernet frames
 - Recovery of message from any M ($M < N$) frames



Data Redundancy

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- FEC can prevent data loss due to:



Data Redundancy

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 - Recovery of message from any M ($M < N$) frames
- FEC can prevent data loss due to:
 - **bit error**

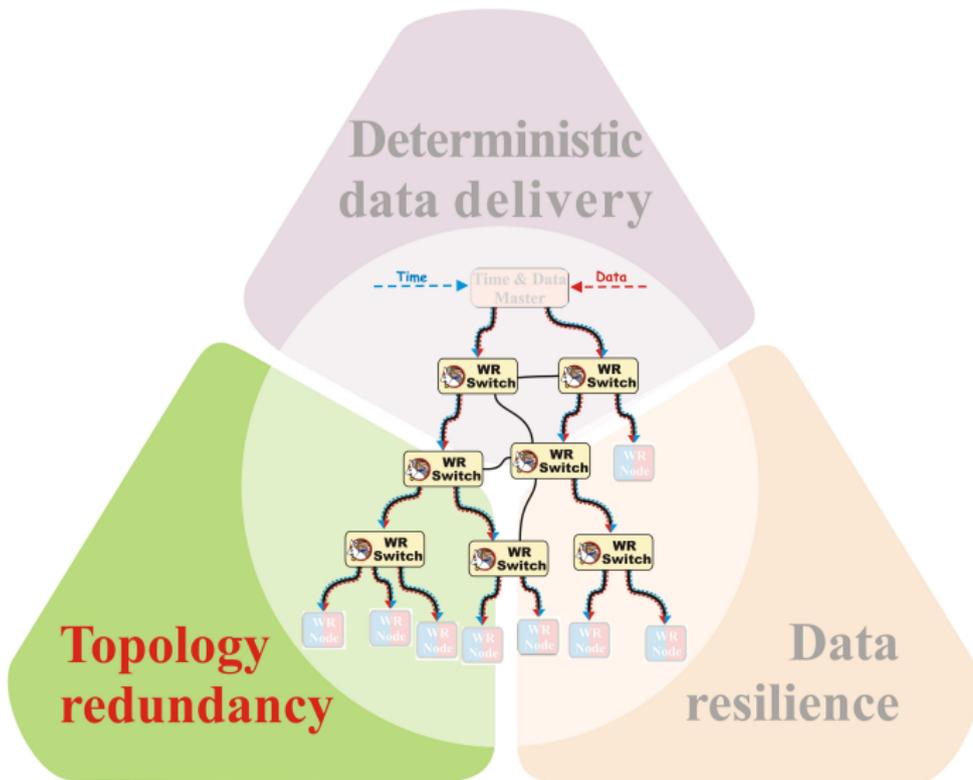


Data Redundancy

- **Forward Error Correction (FEC)** – transparent layer:
 - One message encoded into N Ethernet frames
 - Recovery of message from any M ($M < N$) frames
- FEC can prevent data loss due to:
 - **bit error**
 - **network reconfiguration**



Topology Redundancy (Switch)



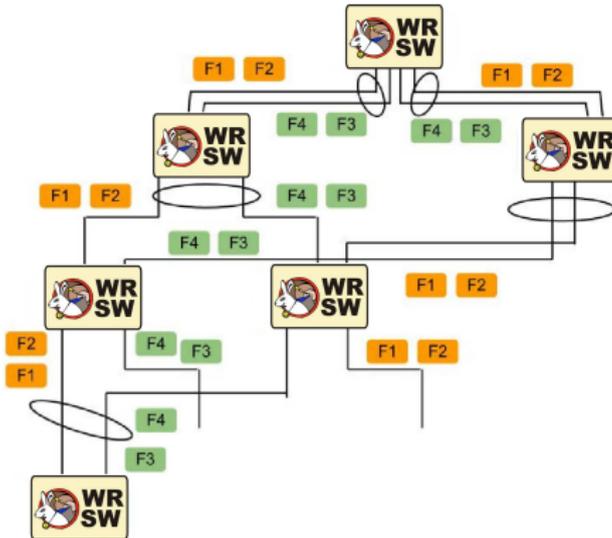
Topology Redundancy (Switch)

- Ideas:
 - Enhanced Link Aggregation Control Protocol (eLACP)
 - WR Rapid Spanning Tree Protocol (WR RSTP)
 - WR Shortest Path Bridging (WR SPB)
- Seamless redundancy = FEC + WR RSTP/SPB/eLACP
- Redundant data received in end stations
- Take advantage of **broadcast/multicast** characteristic of Control Data traffic (within VLAN)



Topology Redundancy: eLACP (short explanation)

Control Message encoded into 4 Ethernet Frames (F1,F2,F3,F4). Reception of any two enables to recover Control Message (*Cesar Prados, GSI*).

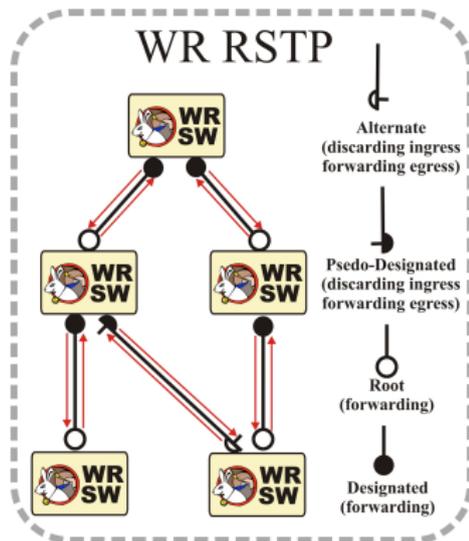


Courtesy of Cesar Prados



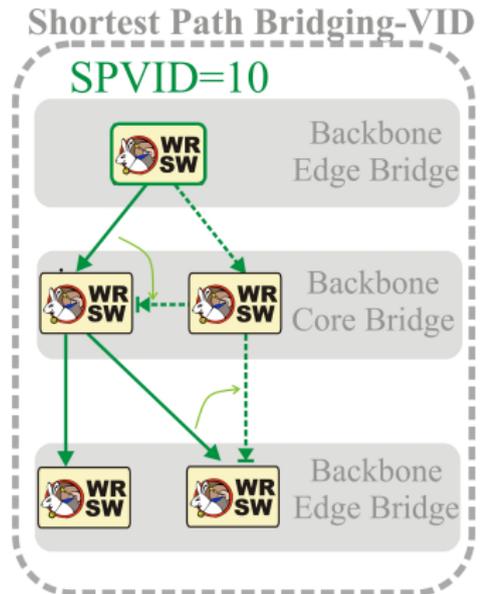
Topology Redundancy: WR RSTP

- Speed up RSTP – max 2 frames lost on re-configuration
- H/W switch-over to the backup link
- RSTP's a priori information (alternate/backup) used
- Limited number of allowed topologies
- Drop only on reception – within VLAN



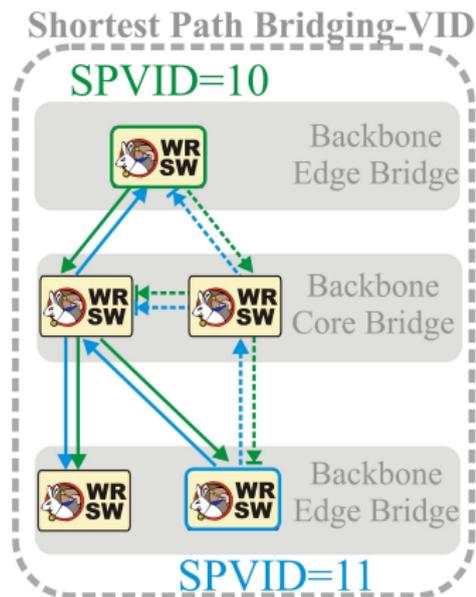
Topology Redundancy: WR SPB

- Shortest Path Bridging – VID (SPBV)
- Backup ports blocking on reception
- Single port forwarding from source
- H/W switch-over to path equally or more distant to the root



Topology Redundancy: WR SPB

- Shortest Path Bridging – VID (SPBV)
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- Single port forwarding from source
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- Not fully congruent

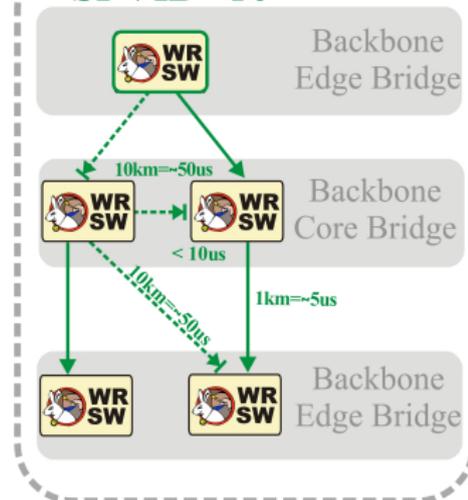


Topology Redundancy: WR SPB

- Shortest Path Bridging – VID (SPBV)
- Backup ports blocking on reception
- Single port forwarding from source
- H/W switch-over to path equally or more distant to the root
- Not fully congruent
- New link metrics: link delay

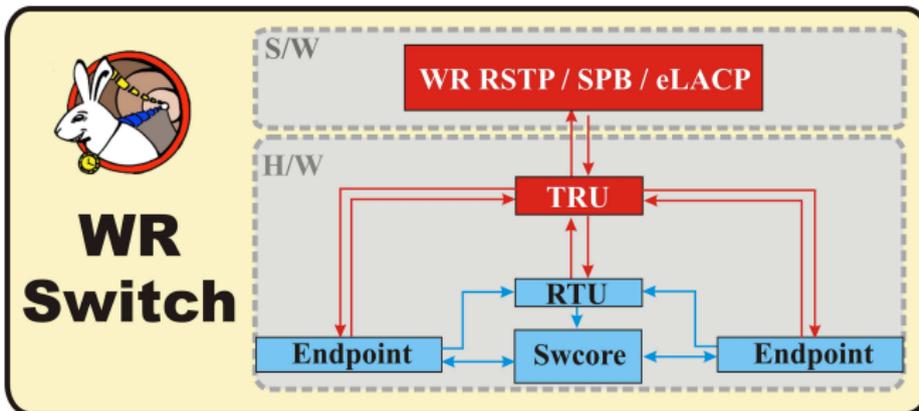
Shortest Path Bridging-VID

SPVID=10

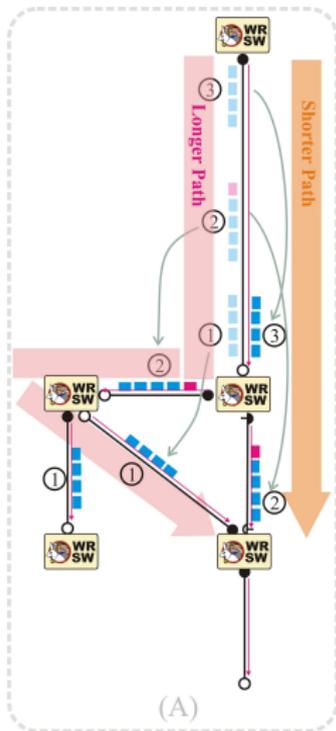


Topology Resolution Unit (TRU)

- Configurable module to support various software protocols
- Accepts active and backup port masks (ingress and egress)
- Monitors and controls ports state
- Takes actions on HW-filtered frames and link-down
- Triggers hardware generation of frames



Topology Resolution Unit (TRU)



- Marker-based hardware-switch-over
- Hardware-generated priority-based PAUSE
- Hardware-generated BPDUs
- Hardware-detection of BPDUs to open blocking (pre-configured) port



Other features/ideas

- Semi-automatic reconfiguration



Other features/ideas

- Semi-automatic reconfiguration
- Time-triggered reconfiguration



Other features/ideas

- Semi-automatic reconfiguration
- Time-triggered reconfiguration
- Time-aware shaper



Other features/ideas

- Semi-automatic reconfiguration
- Time-triggered reconfiguration
- Time-aware shaper
- Drop non-High Priority frames when **High Priority** arrives



White Rabbit and IEEE 802

- We want to be standard-compatible!



White Rabbit and IEEE 802

- We want to be standard-compatible!
- Ideas in line with Time Sensitive Networks



White Rabbit and IEEE 802

- We want to be standard-compatible!
- Ideas in line with Time Sensitive Networks
- Great potential for collaboration between CERN and IEEE

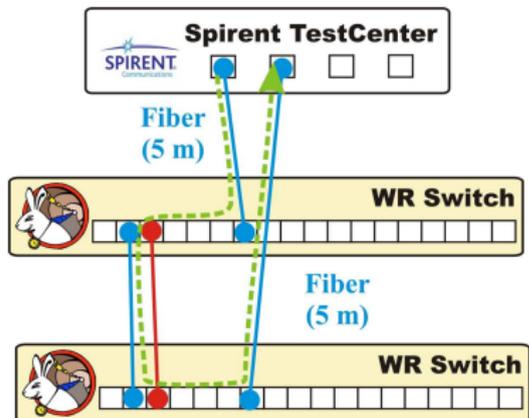


White Rabbit and IEEE 802

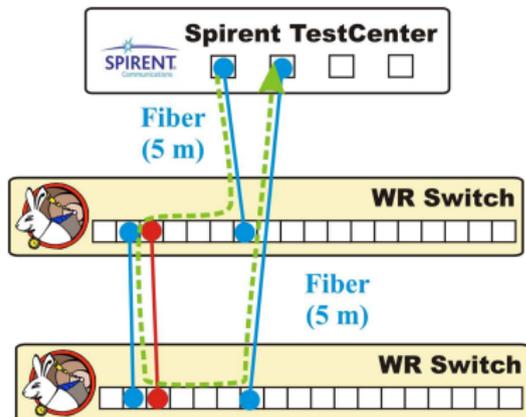
- We want to be standard-compatible!
- Ideas in line with Time Sensitive Networks
- Great potential for collaboration between CERN and IEEE
- Perfect platform for prototyping



Topology reconfiguration performance



Topology reconfiguration performance

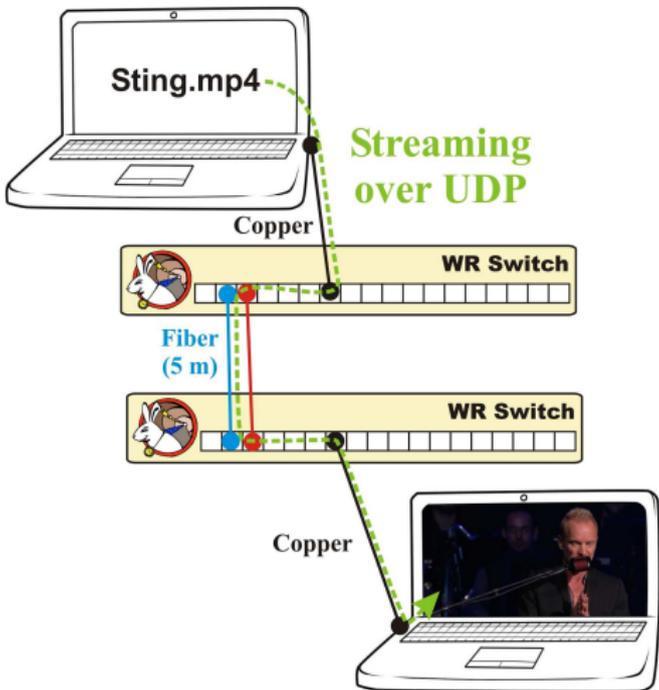


Frame Loss and Latencies

Frame Size (bytes)	Load (%)	Tx Frames	Rx Frames	Frame Loss	Max Latency (uSec)
288	10	1,217,533	1,217,533	0	5.84
288	30	3,652,598	3,652,597	1	5.84
288	50	6,087,663	6,087,663	0	5.84
288	70	8,522,728	8,522,727	1	5.84
288	90	10,957,793	10,957,792	1	6.12



Redundancy demo

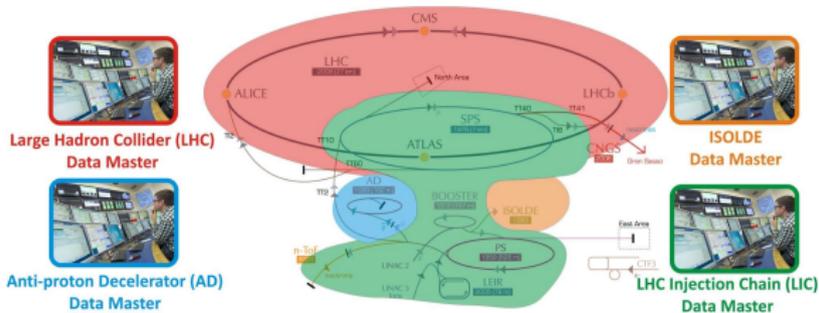


Outline

- 1 Introduction
- 2 CERN Control & Timing
- 3 WR Network
- 4 Time Distribution
 - Timing demo
- 5 Data Distribution
 - Redundancy demo
- 6 WR @ CERN**
- 7 Summary



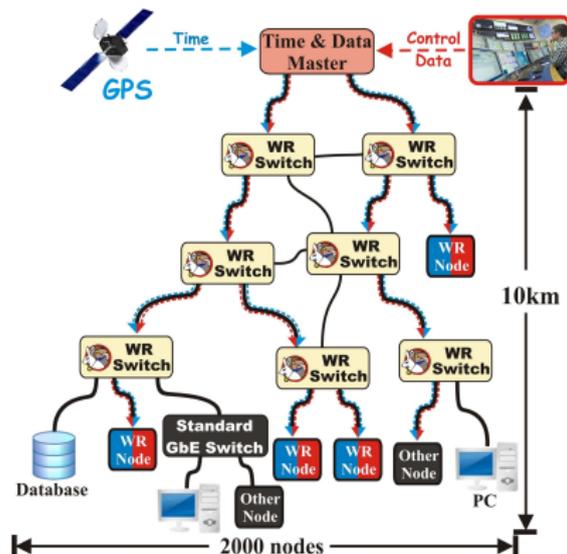
WR-based Control and Timing System (concept)



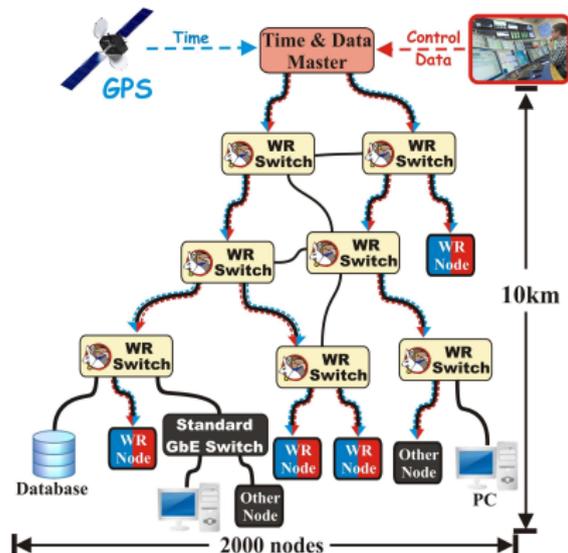
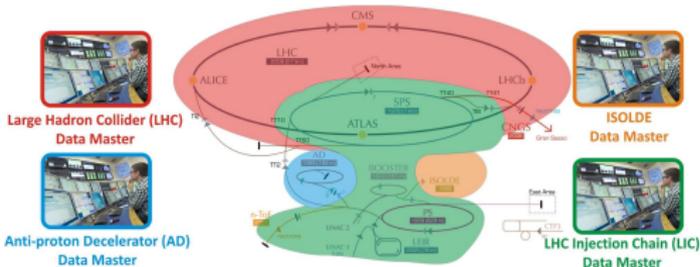
- 4 accelerator networks
- Separate **Data Master (DM)** for each network
- **LIC Data Master** communicates with other DMs and control devices in their networks
- Broadcast/multicast of **Control Messages**



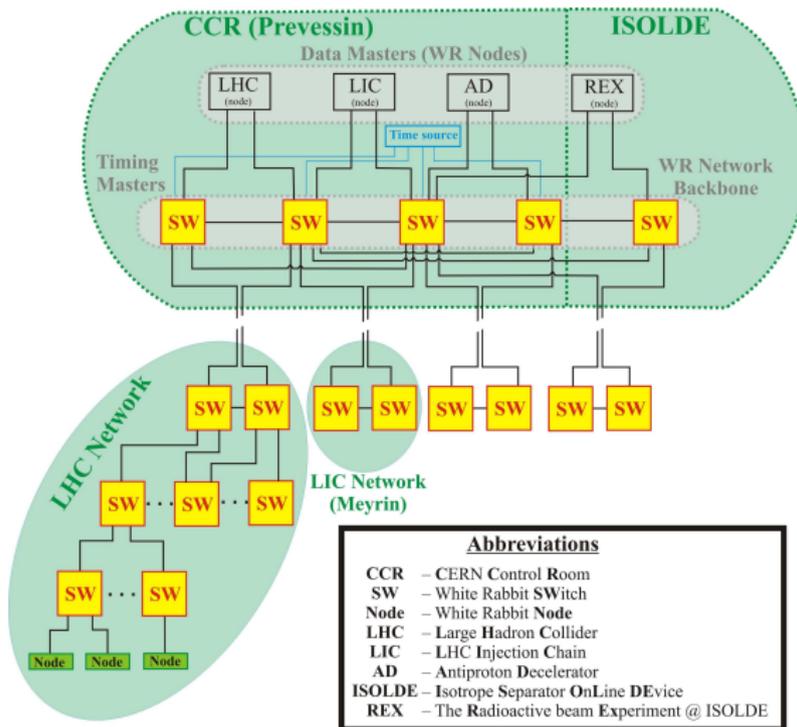
WR-based Control and Timing System (concept)



WR-based Control and Timing System (concept)

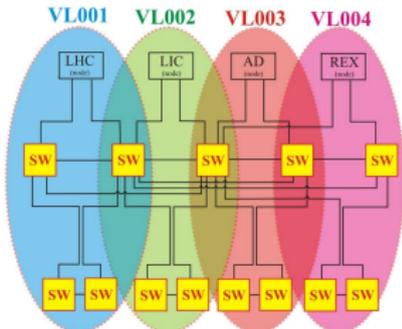


Accelerator Networks

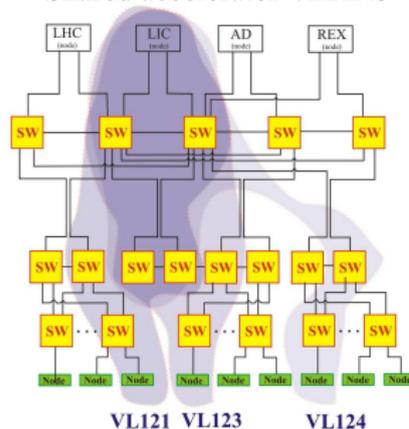


Traffic distribution: VLANs + multicast

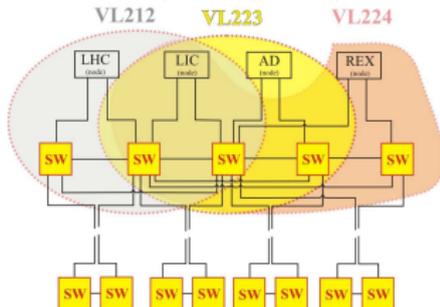
Per-accelerator VLANs



Shared accelerator VLANs



DM-to-DM VLANs



Abbreviations

SW	– White Rabbit SWitch	AD	– Antiproton Decelerator
LHC	– Large Hadron Collider	ISOLDE	– Isotope Separator OnLine Device
LIC	– LHC Injection Chain	REX	– The Radioactive beam Experiment @ ISOLDE
DM	– Data Master		



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White Rabbit Family

Successful international collaboration of institutes, universities and companies



WR Users:

<http://www.ohwr.org/projects/white-rabbit/wiki/WRUsers>



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Pushing frontiers

- Scientific, open (H/W & S/W), with companies



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- Standard-compatible and standard-extending



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- Active participation in IEEE1588 revision process



Pushing frontiers

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- A versatile solution for general control and data acquisition
- Fulfilling all our needs in synchronization and determinism
- Standard-compatible and standard-extending
- Active participation in IEEE1588 revision process
- Eager to collaborate with IEEE802



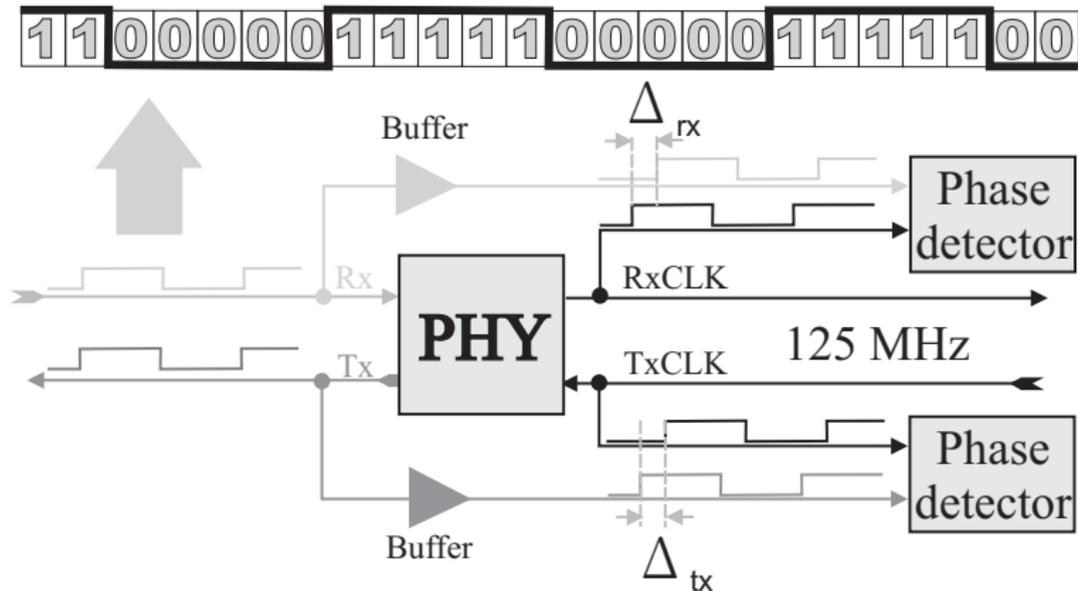
Thank you



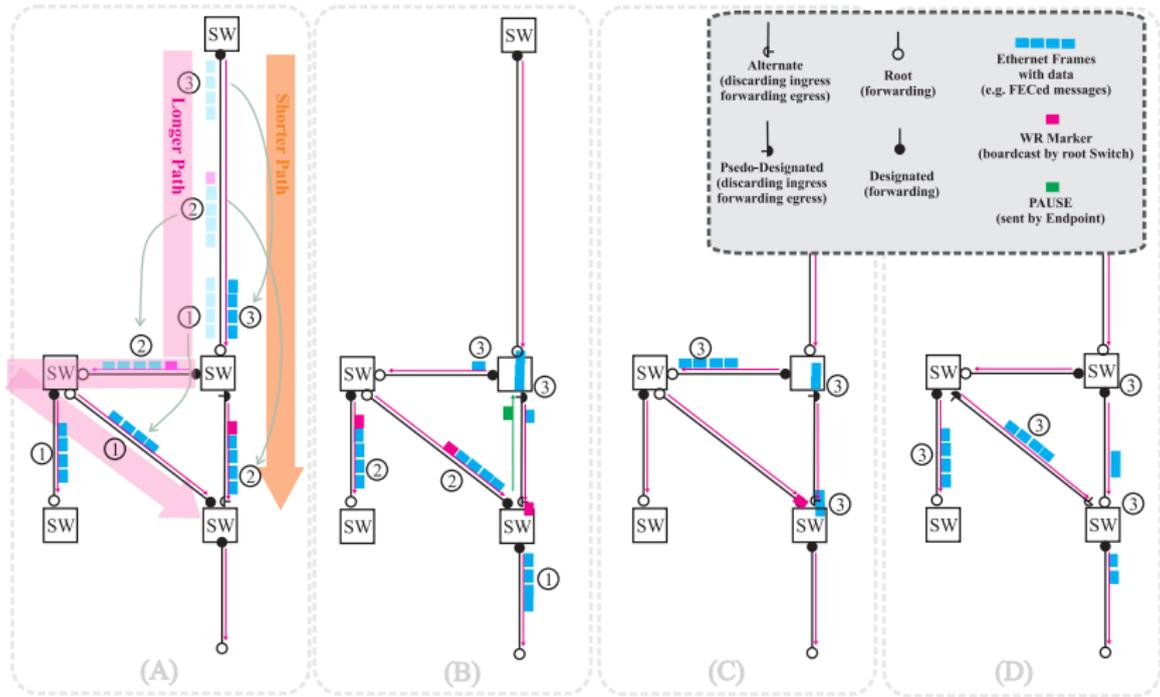
More information:
<http://www.ohwr.org/projects/white-rabbit/wiki>



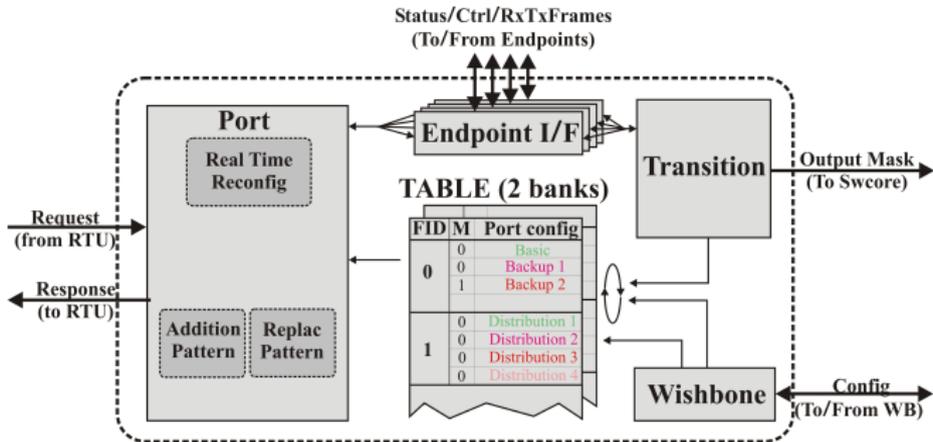
Fixed Delays Measurement



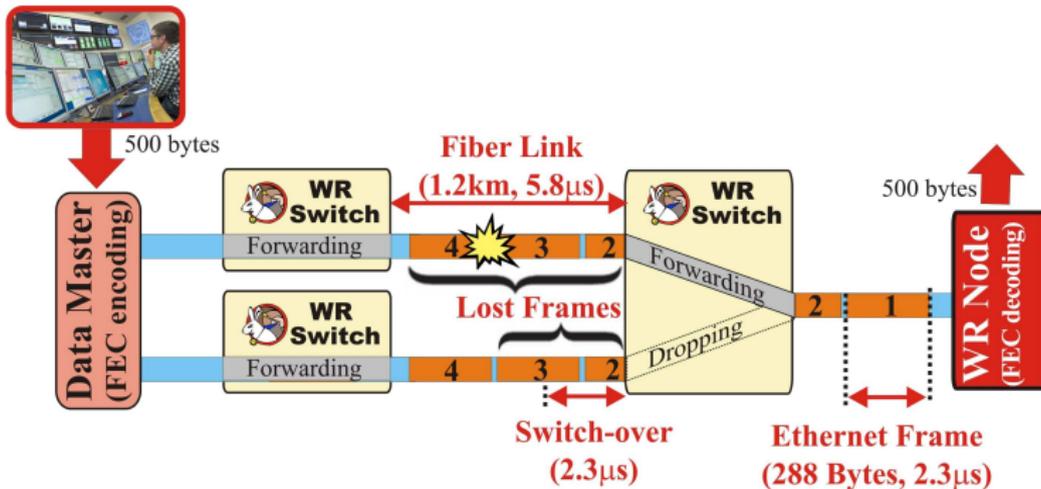
WR RSTP: adding new network element



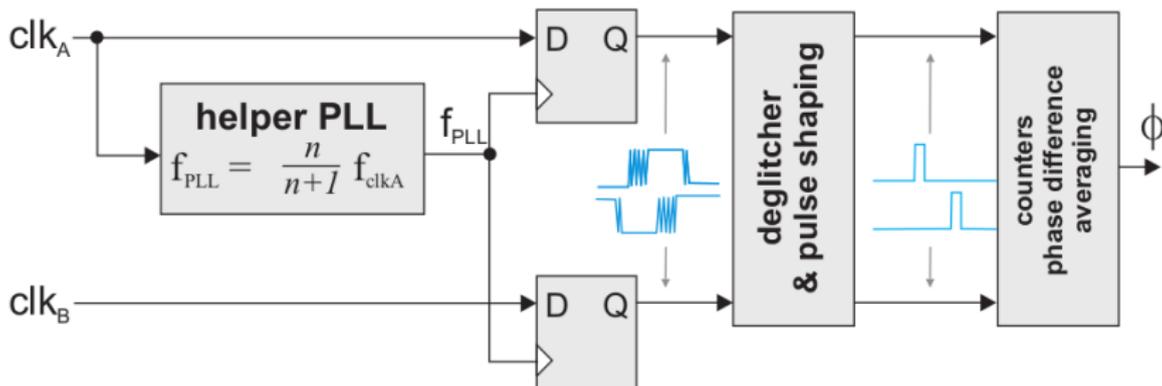
Topology Resolution Unit (TRU)



WR RSTP + FEC



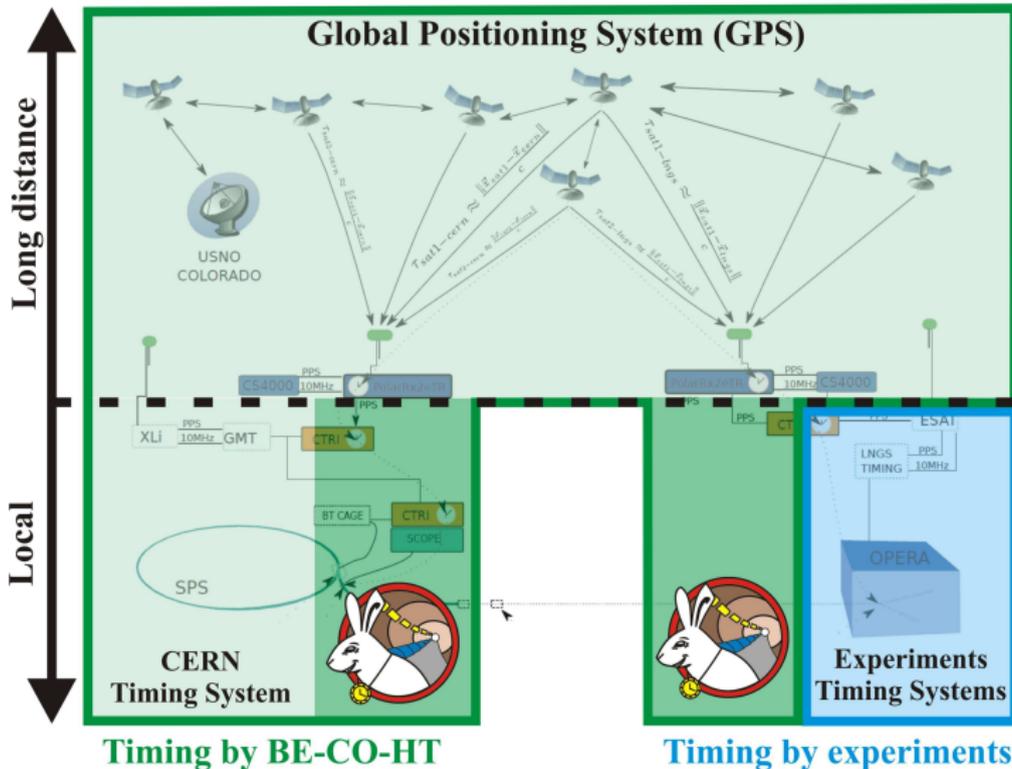
Digital Dual Mixer Time Domain (DMTD) phase detector



- Fully digital, so fully linear
- Can handle multiple channels without need for extra hardware



New time transfer with WR for CNGS



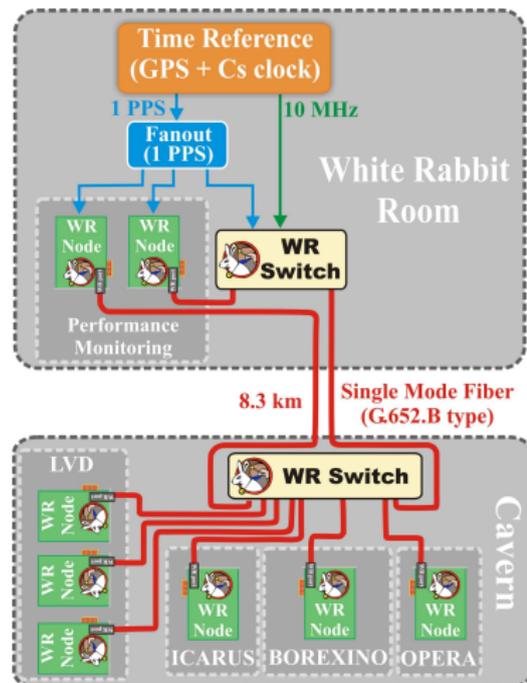
Timing by BE-CO-HT

Timing by experiments

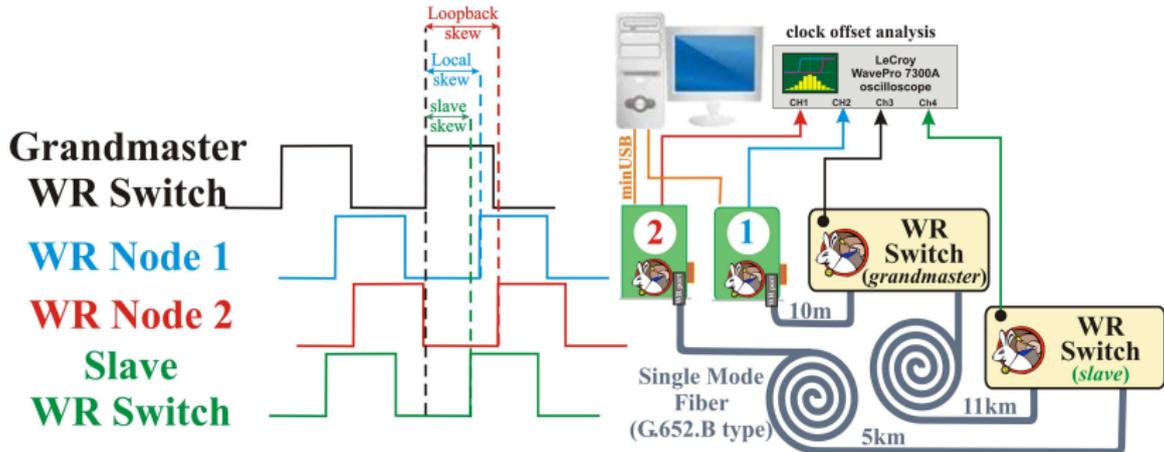


WR installation for CNGS

- Grandmaster WR Switch
- 8 km of fiber between switches
- Boundary Clock WR Switch
- WR Node – includes Time-to-Digital Converter (TDC):
 - 55 ps precision (std. dev)
 - 300 ps accuracy
- Performance monitoring



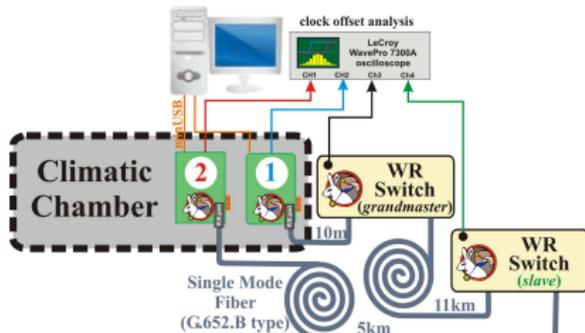
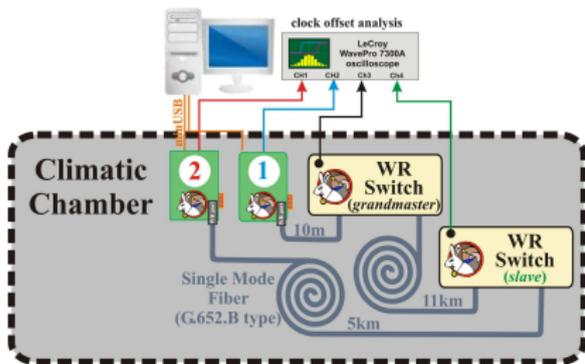
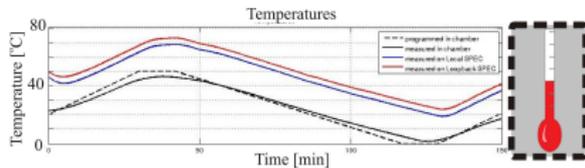
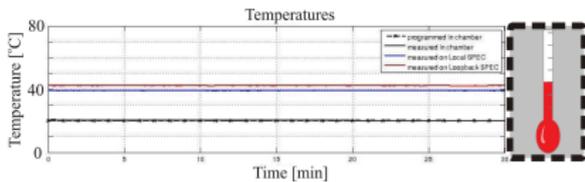
Temperature tests setup (1)



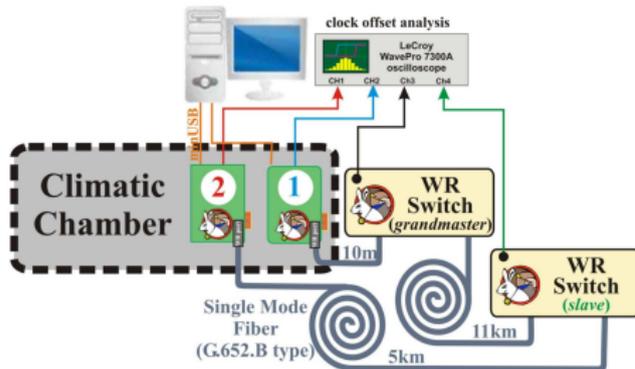
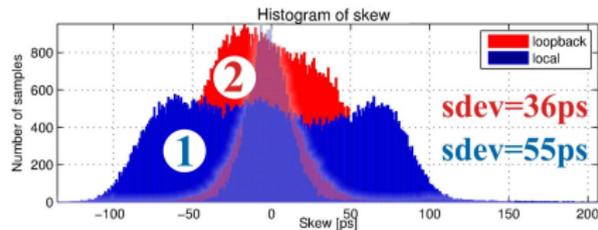
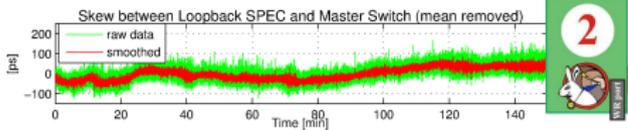
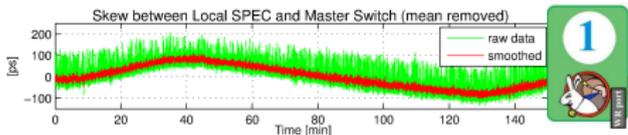
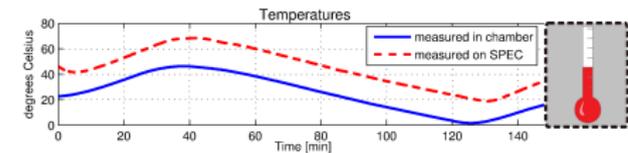
- Measurement of WR Timebase (clock)
- Skew measurement with oscilloscope



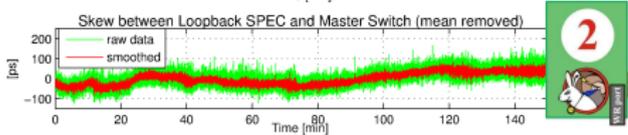
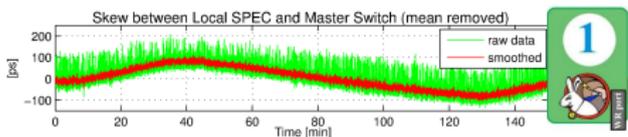
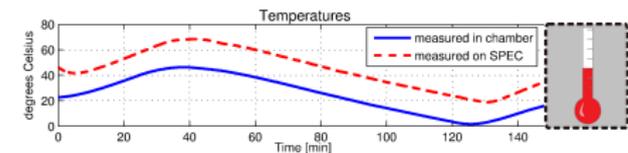
Temperature tests setup (2)



Temperature tests results (1)



Temperature tests results (2)



The change of time offset
due to temperature changes

$$\approx 4 \text{ ps per } 1^\circ\text{C}$$

